

T.C.
ISTANBUL KÜLTÜR UNIVERSITY
INSTITUTE OF GRADUATE STUDIES

**A PROPOSED MODEL FOR ESTIMATING THE CURVATURE
DUCTILITY OF REINFORCED CONCRETE SECTIONS**

Master of Science Thesis

Mohamad MARI

1800000784

Department: Civil Engineering

Program: Structural Engineering

Supervisor: Prof. Dr. HÜSEYİN FARUK KARADOĞAN

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Thesis Jury Members:

Prof. Dr. AHMET MURAT TÜRK

Dr. Öğr. ÜYESİ ERDAL COŞKUN

May 2021

Preamble:

I would like to acknowledge and thank the following important people who have supported me, not only during the course of this project, but throughout my master's degree.

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ABSTRACT

Reinforced concrete is a widely used system for constructing structures all over the world. Currently, the main requirement for designing reinforced concrete structures is achieving a ductile behavior by deforming before the section fracture under the ultimate limit state. In general, to ensure a ductile behavior, an adequate moment-curvature is important. Nowadays, one of the most used methods for quantifying the ductility of the section is through curvature ductility. Previously, several analytical models were proposed to determine this parameter and its effect. However, some problems are encountered due to the major assumptions in developing these models which reduce their reliability for general applications. In this study, computer software was developed to calculate the curvature ductility of reinforced concrete columns and walls. In addition to that, an enhanced mathematical model for estimating the curvature ductility is proposed. Finally, a parametric study was conducted to evaluate the influencing parameters on the curvature ductility of different sections. The results of this study have shown a significant improvement in the proposed against the currently available one. Furthermore, the developed program was capable of defining the moment-curvature with good accuracy in comparison to both ETABS and Xtract. Moreover, the results of the parametric study have presented a considerable independency of the sectional ductility on the level of the confinement and the tensile strength of the concrete used. This study is expected to help practicing engineers in their daily works by reliably estimating the behavior of reinforced concrete sections.

ÖZET

Betonarme, tüm dünyada yapıların inşasında yaygın olarak kullanılan bir sistemdir. Günümüzde, betonarme yapıların tasarımı için temel gereksinim, nihai sınır durumu altında kesit kırılmasından önce şekil değiştirerek sünek bir davranış elde etmektir. Genel olarak, sünek bir davranış sağlamak için yeterli bir moment eğriliği önemlidir. Günümüzde, kesitin sünekliğini ölçmek için en çok kullanılan yöntemlerden biri eğrilik sünekliğidir. Daha önce, bu parametreyi ve etkisini belirlemek için birkaç analitik model önerildi. Ancak, genel uygulamalar için güvenilirliğini azaltan bu modellerin geliştirilmesinde büyük varsayımlar nedeniyle bazı sorunlarla karşılaşılmaktadır. Bu çalışmada, betonarme kolon ve duvarların eğrilik sünekliğini hesaplamak için bilgisayar yazılımı geliştirilmiştir. Buna ek olarak, eğrilik sünekliğini tahmin etmek için geliştirilmiş bir matematiksel model önerilmiştir. Son olarak, farklı kesitlerin eğrilik sünekliğine etki eden parametreleri değerlendirmek için parametrik bir çalışma yapılmıştır. Bu çalışmanın sonuçları, şu anda mevcut olana karşı önerilende önemli bir gelişme göstermiştir. Ayrıca, geliştirilen program hem ETABS hem de Xtract ile karşılaştırıldığında moment eğriliğini iyi bir doğrulukla tanımlayabiliyordu. Ayrıca, parametrik çalışmanın sonuçları, kullanılan betonun sarılma seviyesi ve çekme mukavemeti üzerinde kesit sünekliğinin önemli bir bağımsızlığını ortaya koymuştur. Bu çalışmanın, betonarme bölümlerin davranışını güvenilir bir şekilde tahmin ederek mühendislere günlük işlerinde yardımcı olması beklenmektedir.

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CHAPTER 1

INTRODUCTION

1.1 GENERAL INTRODUCTION

Over the last decades, the philosophy behind designing of reinforced concrete (RC) structures has developed significantly. Nowadays, the main requirement for accepting the design of a given RC section is the fact that it follows a ductile behavior in order to avoid a brittle failure of the structure. This is generally done through ensuring an adequate curvature in the ultimate limit state. The definition of ductility is the ability of members to undergo deformations without a significant decrease in its flexural capacity (Park & Ruitong, 1988) [1]. Currently, one of the most common methods to quantify the ductility of RC members is through curvature ductility. Several approaches were previously introduced to the literature for calculating this parameter taking several factors into account such as the reinforcement ratio, strength of both steel reinforcement and the concrete one, and the size of the RC section. Furthermore, some parametric studies were conducted upon these computational approaches. However, there are some problems in these methods such as their capability to be applied in all reinforcement ratios including the amount of tensile reinforcement as well as compressive reinforcement. Thus, a detailed study is important to improve these models by proposing an alternative analytical model that can overcome the current lacks in these models.

1.2 AIM OF THE STUDY

This study is intended to firstly develop a software that can define the moment curvature of RC columns and walls, secondly, propose an improved analytical approach for estimating the

curvature ductility of these sections, and finally, conduct a parametric study that can highlights the influence of several factors including the strength of steel and concrete used, the rate of axial load applied, and dimensions of the RC section on the ductility. This information is of importance for both practicing structural engineers as well as scientists in the working in the field.

1.3 OUTLINE OF THE THESIS

The thesis herein consists of five main chapters of which the main scientific content is delivered. The first chapter introduce the topic by providing a general introduction and defines the aim of the study. The second chapter gives a detailed literature review of the current approaches used and highlights the findings of previous studies. Thereafter, the third chapter includes the research methodology that was followed while conducting the investigations and the main assumptions. Then the results and discussions are given in the fourth chapter of which the findings of this study will be illustrated and compared to previous ones available in the current state of the art. Finally, the major conclusions of this study are drawn in the fifth chapter and the thesis is ended with a brief information on the possible future works.

CHAPTER 2

LITERATURE REVIEW

2.1 INTRODUCTION

In this chapter, a detailed review of the current state of the art on the analytical modeling of behavior of RC sections will be presented. Furthermore, previous approaches computing the curvature ductility will be summarized.

2.2 CURVATURE DUCTILITY

The ductility of reinforced concrete sections is very important, since it is essential to avoid a brittle failure of the structure by ensuring adequate curvature at the ultimate limit state. According to Olivia & Mandal (2015) [2], ductile behavior in a structure can be achieved using plastic hinges positioned at appropriate locations throughout the structural frame. The ductility of plastic hinges can be obtained from the Moment – Curvature relationship of a reinforced concrete section by dividing the curvature at ultimate point on the curvature at yielding point. Where, yielding curvature is the point when tensile reinforcement yields, and ultimate curvature is the curvature value when the furthest compressed concrete fiber is crushed. Olivia & Mandal (2015) [2] suggested a formula for yielding curvature for a reinforced concrete section:

$$\phi_y = \frac{f_y}{E_s(1-k)d}$$
$$k = \sqrt{(\rho + \rho')^2 n^2 + 2 \left(\rho + \frac{\rho' d'}{d} \right) n} - (\rho + \rho')n$$

$$\rho = \frac{A_s}{b d}, \rho' = \frac{A'_s}{b d}, n = \frac{E_s}{E_c}$$

where ϕ_y is yielding curvature, d is effective depth of tensile reinforcement, and n is modular ratio.

And they suggested another formula for ultimate curvature:

$$\phi_u = \frac{\varepsilon_{cu} \beta_1}{a}$$

$$a = \frac{A_s f_y - A'_s f_y}{0.85 f'_c b}$$

where ϕ_u is ultimate curvature, a is the depth of equivalent rectangular stress block, b is the cross-section width, and β_1 is the ratio of the height of equivalent rectangular concrete compressive stress block to neutral axis. And according to ACI 318M-08 the value of β_1 can be calculated as follows:

$$\beta_1 = 0.85 ; f'_c \leq 28 \text{ MPa}$$

$$\beta_1 = 0.85 - 0.007(f'_c - 28) \geq 0.65 ; f'_c > 28 \text{ MPa}$$

The previous ultimate curvature formula assumes the compression reinforcement reaches yielding point before failure, this cannot occur except in case of a very small compression reinforcement ratio to a relatively high tensile reinforcement ratio, otherwise the formula gives greater values than actual and in the case of symmetric reinforced section without axial force and middle reinforcement, formula gives infinite ductility which does not coincide with reality. And this point will be discussed furthermore later in this research.

CHAPTER 3

RESEARCH METHODOLOGY

3.1 INTRODUCTION

In this section detailed discussions on the material properties used in the case studies and program development stages will be provided. Furthermore, the research strategy followed in the study will be highlighted.

3.2 STRESS-STRAIN BEHAVIOR OF CONCRETE

3.2.1 *Unconfined Concrete*

In previous studies several empirical equations were proposed to represent the stress-strain behavior of plain concrete with various compressive strengths after series of experimental tests. The proposed empirical stress-strain equations were compared with experimental results under axial compression and showed good agreements. Although, the stress-strain relationship of these equations showed a bit difference when compared with each other, and that is because of the parameters defining the relationship depend on the testing conditions. A simple formula proposed by Carreira et al. (1985) [3] for low strength and normal strength concrete:

$$\frac{f}{f_o} = \frac{R \left(\frac{\varepsilon}{\varepsilon_o} \right)}{1 + (R - 1) \left(\frac{\varepsilon}{\varepsilon_o} \right)^\beta}$$
$$\beta = \frac{R}{R - 1} , \quad R = \frac{E_c}{E_o} , \quad E_o = \frac{f_o}{\varepsilon_o}$$

Where R is material parameter depending on the shape of the stress-strain curve, a value of $R=1.90$ was proposed later as a constant value, upon this, the last equation was modified to be as follow:

$$\frac{f}{f_o} = \frac{1.9 \left(\frac{\varepsilon}{\varepsilon_o} \right)}{1 + 0.9 \left(\frac{\varepsilon}{\varepsilon_o} \right)^{2.1}}$$

3.2.2 *Confined Concrete*

The main objectives of transverse reinforcement are (preventing buckling of longitudinal bars, resisting shear forces, and providing sufficient ductility for concrete section). In addition, confinement plays an important role in increasing the concrete compressive strength by resisting the lateral strain of the cross section. The lateral confinement of concrete resists the lateral strain by applying lateral pressure force, where the largest stress at ties location and the smallest stress at the middle distance between ties. Since lateral deformation is related to axial deformation according to Poisson's ratio, it leads to a reduction in the axial strain, which is observed as an increment in concrete compressive strength. The increment in compressive strength of concrete is determined as a proportion of the lateral confinement pressure. A model was proposed by Saatcioglu and Razvi (1992) [4] based on experimental tests then modified later by Suzuki et al. (2004) [5]. The Suzuki's study has discussed the effect of the most important two parameters, volumetric ratio of transverse reinforcement and yield strength of transverse reinforcement as shown in Figure 1, Figure 2, and Figure 3.

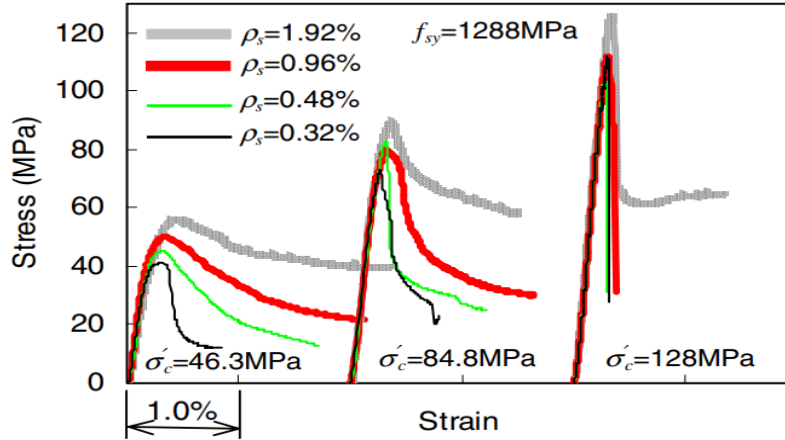


Figure 1: Effect of tie volumetric ratio

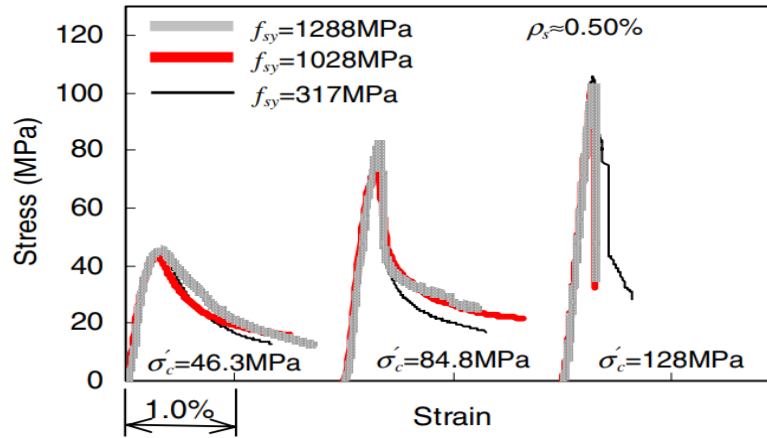


Figure 2: Effect of tie yield strength

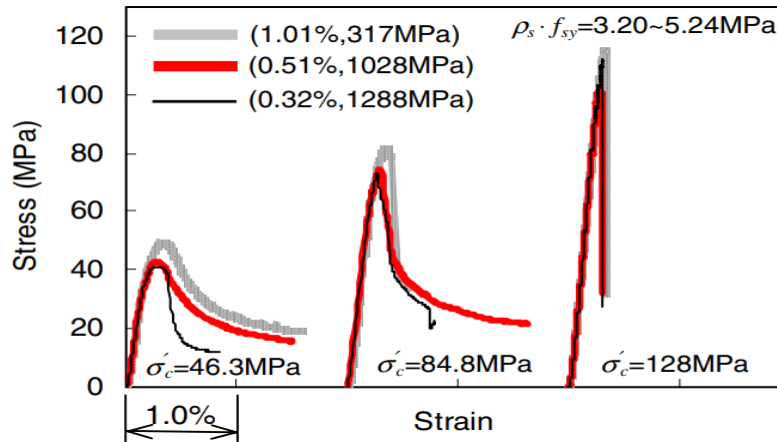


Figure 3: Effect of $\rho_s \cdot f_{sy}$

Since the lateral pressure is distributed uniformly, the effective confinement index was defined as the uniform effective lateral pressure as in the following equation:

$$p_e = k_e \rho_w f_{s,c}$$

where ρ_w is the area ratio of transverse reinforcement; $f_{s,c}$ is the stress in transverse reinforcement at the peak strength and k_e is the effective confinement coefficient given by:

$$k_e = \frac{\left(1 - \sum \frac{(\omega_i)^2}{6 b_c d_c}\right) \left(1 - \frac{s'}{2 b_c}\right) \left(1 - \frac{s'}{2 d_c}\right)}{1 - \rho_{cc}}$$

where ω_i is the clear spacing between adjacent longitudinal steel bars in a rectangular section; s' is the clear spacing of ties; b_c and d_c are the widths of concrete core; and ρ_{cc} is the longitudinal reinforcement ratio in core section. The model was based on the equivalent uniform confinement pressure concept for square cross section having the same confinement pressure in two orthogonal directions. Therefore, in the case of rectangular section with different confinement pressure in both directions, the average effective pressure can be obtained after calculating the effective lateral pressure in each direction as follow:

$$p_e = \frac{p_{ex} b_c + p_{ey} d_c}{b_c + d_c}$$

A regression analysis was performed on all test results to formulate the peak strength (σ_{cc}), the strain at peak strength (ε_{cc}), and the slope of the descending branch (E_{des}) in terms of p_e . The results of regression analyses are presented as follows:

$$\frac{\sigma_{cc}}{\sigma_{co}} = 1.0 + 4.1 \left(\frac{p_e}{\sigma_{co}}\right)^{0.7}$$

$$\varepsilon_{cc} = \varepsilon_{co} + 0.015 \left(\frac{p_e}{\sigma_{co}}\right)^{0.56}$$

$$E_{des} = 0.026 \frac{\sigma_{co}^3}{p_e^{0.4}}$$

$$\sigma_{co} = 0.85 \sigma'_c$$

$$\varepsilon_{co} = 0.0028 - 0.0008 k_3$$

$$k_3 = \frac{40}{\sigma_{co}} \leq 1.0$$

Where σ_{co} and ε_{co} are the peak stress and corresponding strain of unconfined concrete. The study proposed a trial-and-error method for calculating the stress in confinement ties. And for simplicity, the study proposed a direct equation:

$$f_{s,c} = E_s \left(0.45 \varepsilon_{co} + 0.73 \left(\frac{k_e \rho_w}{\sigma_{co}} \right)^{0.7} \right) \leq f_{sy}$$

The strain-strain relationship of confined concrete was plotted according to a model proposed by Shah et al. (1985) [6], where the ascending part is represented by:

$$\sigma_c = \sigma_{cc} \left(1 - \left(1 - \frac{\varepsilon_c}{\varepsilon_{cc}} \right)^\alpha \right) ; (0 \leq \varepsilon_c \leq \varepsilon_{cc})$$

$$\alpha = E_c \frac{\varepsilon_{cc}}{\sigma_{cc}}$$

$$E_c = 3320 \sqrt{\sigma_{co}} + 6900$$

And the descending part was defined as a straight line connecting the point of peak strength and the point at which the stress drops to 85% of peak strength:

$$\sigma_c = \sigma_{cc} - E_{des} (\varepsilon_c - \varepsilon_{cc}) ; (\varepsilon_{cc} \leq \varepsilon_c < \varepsilon_{ccu})$$

The study compares numerical results with experimental results for different compressive strengths of concrete, and they were in a good agreement as shown in Figure 4, Figure 5, and Figure 6.

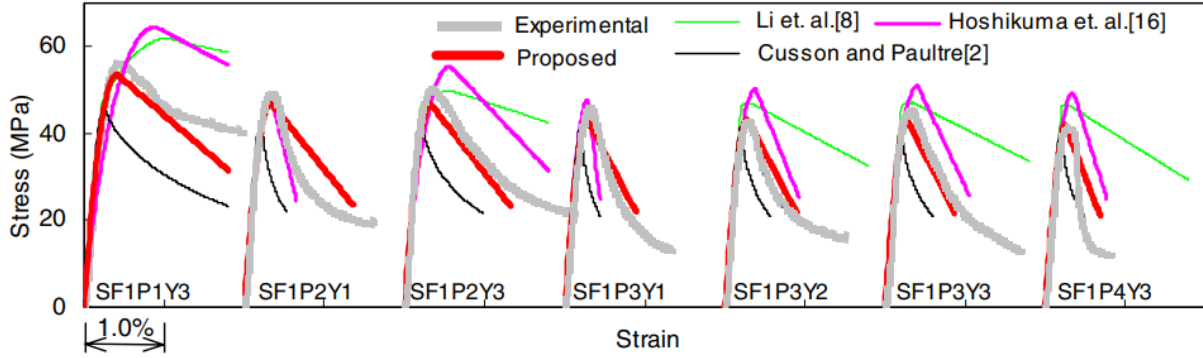


Figure 4: Comparison of stress-strain models ($\sigma'_c = 46.3 \text{ MPa}$)

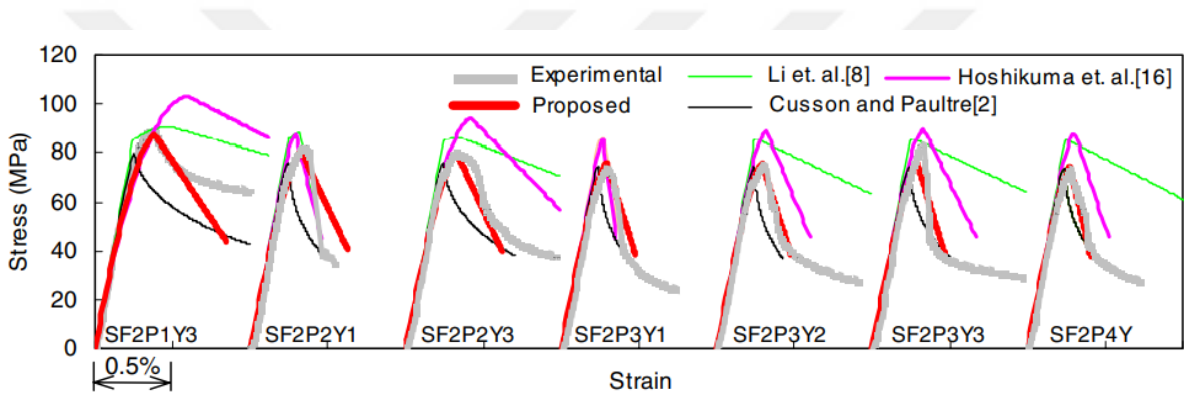


Figure 5: Comparison of stress-strain models ($\sigma'_c = 84.8 \text{ MPa}$)

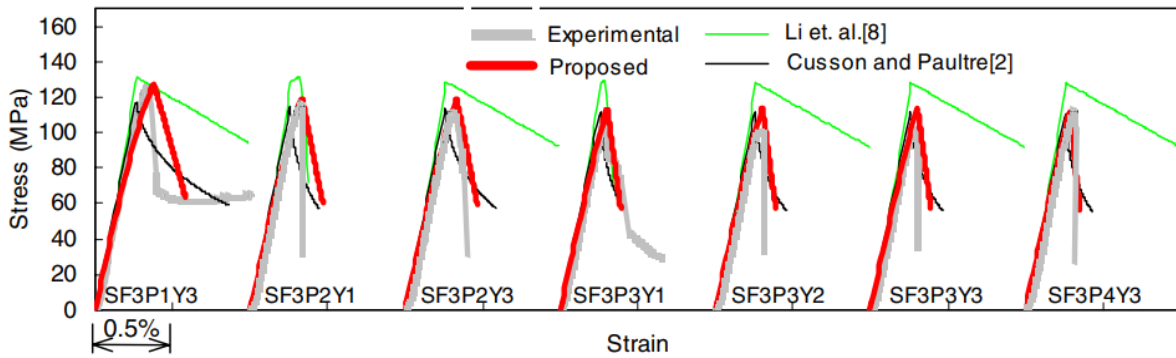


Figure 6: Comparison of stress-strain models ($\sigma'_c = 128 \text{ MPa}$)

Another recent model was proposed by Legeron and Paultre (2003) [7] to describe the behavior of confined concrete based on Mander et al. (1988) [8] model. The analytical model was compared with a wide range of concrete columns with concrete strength ranging from 30 to 120 MPa confined with steel of yield strength ranging from 250 to 1,400 MPa.

$$f'_{le} = \frac{K_e (A_{shy} f'_h)}{c_y s}$$

$$K_e = \frac{\left(1 - \frac{\sum w_i^2}{6 c_x c_y}\right) \left(1 - \frac{s'}{2c_x}\right) \left(1 - \frac{s'}{2c_y}\right)}{1 - \rho_{cc}} \geq 0$$

$$f'_h = \begin{cases} f_{hy} & \text{for } \kappa \leq 10 \\ \frac{0.25 f'_c}{\rho_{sey} (\kappa - 10)} \geq 0.43 \varepsilon'_c E_s \neq f_{hy} & \text{for } \kappa > 10 \end{cases}$$

$$\kappa = \frac{f'_c}{\rho_{sey} E_s \varepsilon'_c}$$

$$\rho_{sey} = K_e \rho_{sy}$$

$$f_{cc} = f_{co} \left(-1.254 + 2.254 \sqrt{1 + \frac{7.94 f'_l}{f_{co}} - \frac{2 f'_l}{f_{co}}} \right)$$

Where K_e is the geometric confinement effectiveness coefficient, which measures the effectiveness of the confinement reinforcement of confined concrete and varies from 1 for a continuous tube to 0 when ties are spaced more than half the core cross section minimum dimension; A_{shy} is the total section of confinement reinforcement for the set of ties in direction y ; c_y is the cross section dimension in direction y , measured center-to-center of peripheral ties; s center-to-center spacing between ties; and f'_h is the stress in the confinement reinforcement at peak stress. According to the author, the stress strain curve can be predicted by three coordinates. The ascending part between zero and the first coordinate can be derived by an equation based on Sargin et al. equation (1968) [9]:

$$\sigma_{cc} = f_{cc} \times \frac{k_c \times \bar{\varepsilon}_c + (k'_c - 1) \times \bar{\varepsilon}_c^2}{1 + (k_c - 2) \times \bar{\varepsilon}_c + k'_c \times \bar{\varepsilon}_c^2} ; 0 \leq \varepsilon_c \leq \varepsilon_{cco}$$

$$\bar{\varepsilon}_c = \frac{\varepsilon_c}{\varepsilon_{cco}} , \text{ and } \varepsilon_{cco} = \varepsilon_{co} \times \left[1 + 5 \left(\frac{f_{cc}}{f_{co}} - 1 \right) \right]$$

$$k_c = \frac{E_{bco} \times \varepsilon_{cco}}{f_{cc}} , \quad E_{bco} = 11000 \sqrt[3]{f_{cc}} , \quad \text{and } k'_c = k_c - 1$$

The descending part between the first and the second coordinates can be determined by:

$$\sigma_{cc} = f_{cc} - E_{sc}(\varepsilon_c - \varepsilon_{cco}) ; \quad \varepsilon_{cco} < \varepsilon_c \leq \varepsilon_{65}$$

$$E_{sc} = \frac{6 \times f_{co}^2}{k_e \times \rho_s \times f_{yh}}$$

$$\varepsilon_{65} = \frac{0.35 \times f_{cc}}{E_{sc}} + \varepsilon_{cco}$$

where E_{sc} is the slope of the descending part and ε_{65} is the strain at 65% of confined peak stress.

After reaching the strain ε_{65} , the stress of confined concrete has a constant value of $0.65f_{cc}$ until the ultimate strain (ε_{ccu}).

$$\varepsilon_{ccu} = 0.4 \frac{f_l}{f_{co}} + \varepsilon_{cu}$$

3.2.3 Tensile Strength of Concrete

Concrete is a brittle material and weak under tension, therefore it is used to resist compression mainly and the tensile strength of concrete is usually neglected due to its small value compared to compressive strength. However, in this research the effect of tensile strength of concrete on bending capacity and curvature ductility of structural elements subjected to bending moment and axial force will be discussed. According to Jaber et al. (2018) [10], some laboratory split experiments were conducted, and it was noticed that split tensile strength was linearly related to compressive strength of concrete as follow:

$$f_{spt} = k f_c'^n$$

where k and n are constants and various values have been proposed by several researchers and codes based on experimental results. The following table shows some of these values:

Table 1: Values of k and n

Source	k	n
ACI 318	0.56	0.50
ACI 363R	0.59	0.50
Gardner	0.47	0.59
Nihal	0.387	0.63
JCI	0.13	0.85
JSCE	0.23	0.67
CEB-FIB	0.30	0.67
Raphael	0.313	0.667
Ahmad and Shah	0.462	0.55
Oloukun et al.	0.294	0.69

The tensile concrete strength is highly affected by the shape of the applied force and the used experiment. There are three forms of tensile strength, and they are splitting tension, direct tension, and tension under bending. Karadogan et al. (2015) [11] proposed two formulae for converting direct tensile strength to splitting tensile strength and tensile strength under bending as follows:

$$f_{ctk} = \frac{f_{ctk}^y}{1.5}$$

$$f_{ctk} = \frac{f_{ctk}^e}{2}$$

where f_{ctk}^y is the splitting tensile strength, f_{ctk}^e is the tensile strength under bending, and f_{ctk} is the direct tensile strength. After substituting one equation with the other, we get the following formula:

$$f_{ctk}^e = \frac{4 f_{ctk}^y}{3}$$

To take the effect of tensile concrete strength on bending capacity of reinforced concrete section, the value of maximum tensile strength is insufficient, thus, tensile stress-strain relationship of concrete is needed. According to Kaklauskas (1999) [12], concrete tensile stress-strain relationship

consists of two parts, a linear part with a slope of concrete modulus of elasticity E_c , and it is defined by the following formula:

$$\sigma_t = E_c \varepsilon_t$$

The first part is limited by the strain at first crack in concrete under tension ε_{cr} . The second part is nonlinear and extended to the strain value of $\beta \varepsilon_{cr}$. The second part is defined by the following formula:

$$\sigma_t = 0.625 \sigma_{cr} \left(1 - \frac{\bar{\varepsilon}_t}{\beta} + \frac{1 + 0.6 \beta}{\beta \bar{\varepsilon}_t} \right)$$

$$\bar{\varepsilon}_t = \frac{\varepsilon_t}{\varepsilon_{cr}}$$

The value of β depends on the reinforcement ratio ρ and it is defined by:

$$\beta = 32.8 - 27.6 \rho + 7.12 \rho^2$$

3.3 STEEL REINFORCEMENT

Stress-strain relationship of steel consists of two main phases, first phase is linear elastic phase with a slope of modulus of elasticity E_s and limited by yielding point. After yielding point steel enters plastic phase. According to Khatulistiwa et al. (2020) [13], plastic phase starts with constant stress, then a hardening stage which is extended to ultimate stress, finally steel begins losing its resistance until failure, the following figure shows the stress strain curve of steel:

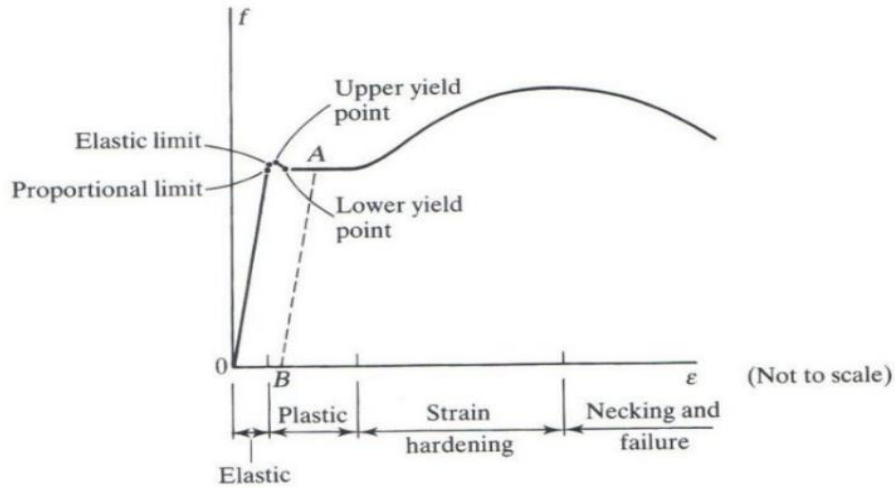


Figure 7: Idealized stress strain behavior of steel rebar

The previous curve was simplified into a bi-linear relationship consists of two phases, elastic phase and plastic phase as shown in Figure 8 below:

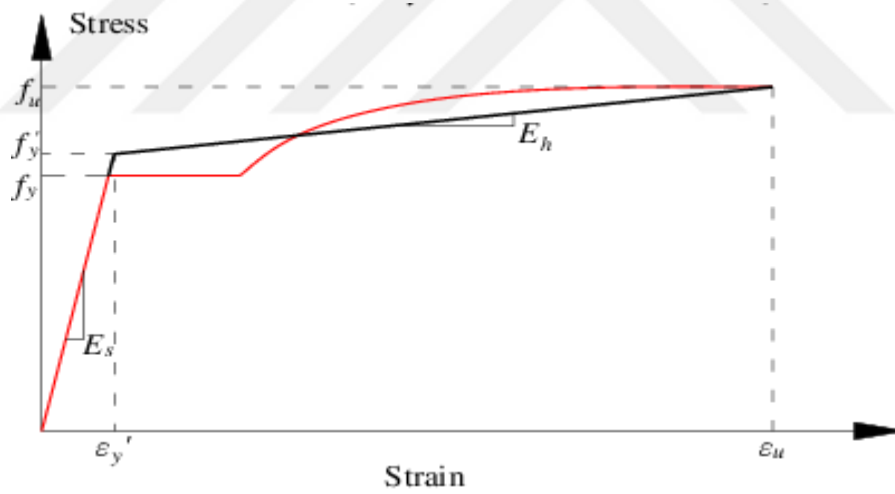


Figure 8: Stress strain behavior of steel rebar

Steel strength is affected by chemical composition. Various grades of steel will be used in this study, taken from the ASTM Standard. The following table shows the important characteristics of each steel grade, which are yield strength f_y , tensile strength f_u , and elongation ϵ_u . Where steel modulus of elasticity E_s has a constant value of 200 GPa.

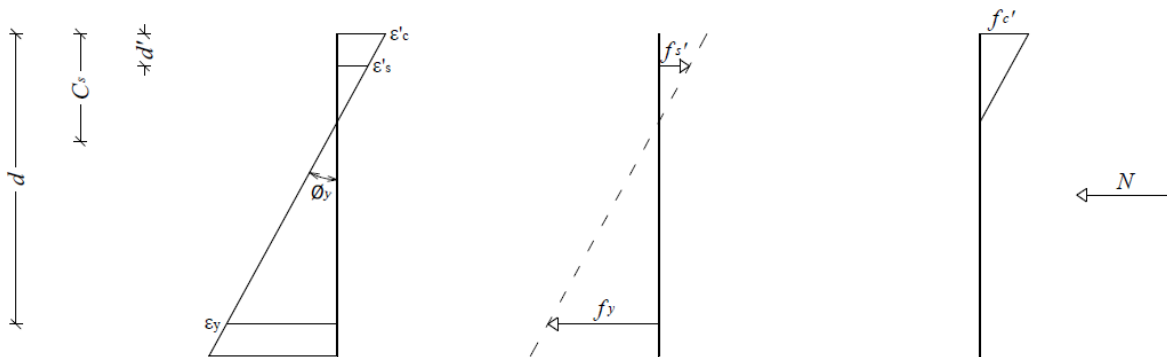
Table 2: Properties of steel in standards

	Standard	Yield Strength MPa	Tensile Strength MPa	Elongation %
GR 40	ASTM A 615	280	420	10 - 12
GR 60	ASTM A 615	420	620	7 - 9
GR 75	ASTM A 615	520	690	6 - 7
GR 100	ASTM A 709	690	760	18

3.4 MOMENT-CURVATURE CURVE

Moment-curvature curve of a reinforced concrete section is the relationship between bending moment resistance and its rotation around the neutral axis in terms of one per meter, either subjected to an axial force or not. Plotting the moment-curvature curve could be done by calculating the moment resistance at each curvature value, starting from a very small curvature, and increasing it gradually until failure where the moment resistance is zero. The following section discusses the derivation of curvature ductility equation in details.

- Curvature at yielding point:



$$N + f_y A_s = f'_s A'_s + 0.5 f'_c C_s B$$

$$\phi_y = \frac{\epsilon_y}{d - C_s} \rightarrow C_s = d - \frac{\epsilon_y}{\phi_y}$$

$$\varepsilon'_s = \frac{C_s - d'}{d - C_s} \varepsilon_y = (d - d') \phi_y - \varepsilon_y$$

$$f'_s = E_s \varepsilon'_s = E_s (d - d') \phi_y - E_s \varepsilon_y = E_s (d - d') \phi_y - f_y$$

$$\varepsilon'_c = d \phi_y - \varepsilon_y$$

$$f_c \cong E_c \varepsilon'_c = E_c d \phi_y - E_c \varepsilon_y$$

$$N + f_y A_s = E_s A'_s (d - d') \phi_y - f_y A'_s + 0.5 f_c B d - 0.5 f_c B \frac{\varepsilon_y}{\phi_y}$$

$$N \phi_y + f_y A_s \phi_y + E_s A'_s (d' - d) \phi_y^2 + f_y A'_s \phi_y - 0.5 f_c B d + 0.5 f_c B \varepsilon_y = 0$$

$$N \phi_y + f_y A_s \phi_y + E_s A'_s (d' - d) \phi_y^2 + f_y A'_s \phi_y - 0.5 B E_c d^2 \phi_y^2 + B E_c d \varepsilon_y \phi_y - 0.5 B E_c \varepsilon_y^2 = 0$$

$$[E_s A'_s (d' - d) - 0.5 B E_c d^2] \phi_y^2 + [N + f_y (A_s + A'_s) + B E_c d \varepsilon_y] \phi_y + [-0.5 B E_c \varepsilon_y^2] = 0$$

$$[-0.5 B E_c d^2] \phi_y^2 + [N + f_y A_s + B E_c d \varepsilon_y] \phi_y + [-0.5 B E_c \varepsilon_y^2] = 0$$

$$[-0.5] \phi_y^2 + \left[\frac{N + f_y A_s + B E_c d \varepsilon_y}{B E_c d^2} \right] \phi_y + \left[\frac{-0.5 \varepsilon_y^2}{d^2} \right] = 0$$

$$[-0.5] \phi_y^2 + \left[\frac{N + f_y A_s}{B E_c d^2} + \frac{\varepsilon_y}{d} \right] \phi_y + \left[0.5 \left(\frac{\varepsilon_y}{d} \right)^2 \right] = 0$$

$$[-0.5] \phi_y^2 + \left[\frac{N + f_y A_s}{B E_c d^2} + \frac{f_y}{E_s d} \right] \phi_y + \left[0.5 \left(\frac{f_y}{E_s d} \right)^2 \right] = 0$$

$$a = -0.5$$

$$b = \frac{N + f_y A_s}{B E_c d^2} + \frac{f_y}{E_s d}$$

$$c = 0.5 \left(\frac{f_y}{E_s d} \right)^2$$

$$\phi_y = \frac{-\sqrt{b^2 - 4 a c} - b}{2a} = \sqrt{b^2 + 2 c} + b$$

$$\alpha_1^2 = 2c$$

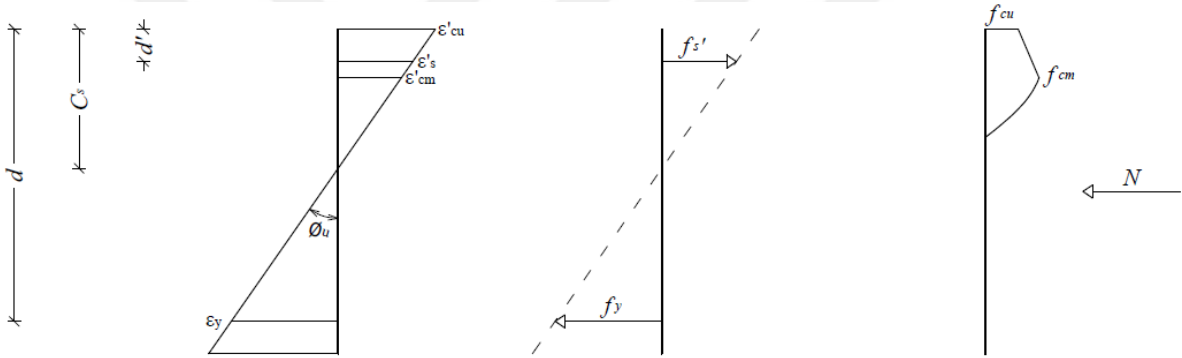
$$\alpha_2 = b$$

$$\alpha_1 = \frac{f_y}{E_s \cdot d}$$

$$\alpha_2 = \frac{N + f_y \cdot A_s}{B \cdot d^2 \cdot E_c} + \alpha_1$$

$$\phi_y = \sqrt{\alpha_2^2 - \alpha_1^2} + \alpha_2$$

- Curvature at ultimate point:



$$N + f_s A_s = f_s' A_s' + \frac{f_{cu} + f_{cm}}{2} y B + \frac{2}{3} f_{cm} (C_s - y) B$$

$$y = C_s \left(1 - \frac{\varepsilon_{cm}}{\varepsilon_{cu}} \right)$$

$$C_s = \frac{\varepsilon_{cu}}{\phi_u}$$

$$y = \frac{\varepsilon_{cu}}{\phi_u} \left(1 - \frac{\varepsilon_{cm}}{\varepsilon_{cu}} \right) = \frac{\varepsilon_{cu}}{\phi_u} - \frac{\varepsilon_{cu} \varepsilon_{cm}}{\varepsilon_{cu} \phi_u} = \frac{\varepsilon_{cu} - \varepsilon_{cm}}{\phi_u}$$

$$\varepsilon_s = \frac{(d - C_s) \varepsilon_{cu}}{C_s} = \frac{d \varepsilon_{cu}}{C_s} - \frac{C_s \varepsilon_{cu}}{C_s} = d \varepsilon_{cu} \left(\frac{\phi_u}{\varepsilon_{cu}} \right) - \varepsilon_{cu} = d \phi_u - \varepsilon_{cu}$$

$$(C_s - y) = \frac{\varepsilon_{cu}}{\phi_u} - \frac{\varepsilon_{cu} - \varepsilon_{cm}}{\phi_u} = \frac{\varepsilon_{cm}}{\phi_u}$$

$$\varepsilon_s' = \frac{(C_s - d') \varepsilon_{cu}}{C_s} = \frac{C_s \varepsilon_{cu}}{C_s} - \frac{d' \varepsilon_{cu}}{C_s} = \varepsilon_{cu} - d' \varepsilon_{cu} \left(\frac{\phi_u}{\varepsilon_{cu}} \right) = \varepsilon_{cu} - d' \phi_u$$

$$f'_s = E_s \varepsilon'_s = E_s(\varepsilon_{cu} - d' \phi_u) = E_s \varepsilon_{cu} - d' E_s \phi_u$$

$$f_s = f_y + \frac{(\varepsilon_s - \varepsilon_y)(f_u - f_y)}{(\varepsilon_u - \varepsilon_y)} \cong f_y$$

$$N + f_y A_s = E_s \varepsilon_{cu} A'_s - d' E_s A'_s + \frac{f_{cu} + f_{cm}}{2} \frac{\varepsilon_{cu} - \varepsilon_{cm}}{\phi_u} B + \frac{2}{3} f_{cm} \frac{\varepsilon_{cm}}{\phi_u} B$$

$$N \phi_u + f_y A_s \phi_u - E_s \varepsilon_{cu} A'_s \phi_u + d' E_s A'_s \phi_u^2 - \frac{(f_{cu} + f_{cm})(\varepsilon_{cu} - \varepsilon_{cm}) B}{2} - \frac{2}{3} f_{cm} \varepsilon_{cm} B = 0$$

$$[d' E_s A'_s] \phi_u^2 + [N + f_y A_s - E_s \varepsilon_{cu} A'_s] \phi_u + \left[-\frac{3(f_{cu} + f_{cm})(\varepsilon_{cu} - \varepsilon_{cm}) B}{6} - \frac{4}{6} f_{cm} \varepsilon_{cm} B \right] = 0$$

$$[d' E_s A'_s] \phi_u^2 + [N + f_y A_s - E_s \varepsilon_{cu} A'_s] \phi_u + \left[\frac{-3(f_{cu} + f_{cm})(\varepsilon_{cu} - \varepsilon_{cm}) B - 4 f_{cm} \varepsilon_{cm} B}{6} \right] = 0$$

$$0.5 \phi_u^2 + \left[\frac{N + f_y A_s - E_s \varepsilon_{cu} A'_s}{2 d' E_s A'_s} \right] \phi_u + \left[\frac{-3(f_{cu} + f_{cm})(\varepsilon_{cu} - \varepsilon_{cm}) B - 4 f_{cm} \varepsilon_{cm} B}{12 d' E_s A'_s} \right] = 0$$

$$\varepsilon_{cm} = 0.5 \varepsilon_{cu} \sim 0.9 \varepsilon_{cu}$$

$$f_{cu} = 0.2 f_{cm} \sim 0.8 f_{cm}$$

$$0.5 \phi_u^2 + \left[\frac{N + f_y A_s - E_s \varepsilon_{cu} A'_s}{2 d' E_s A'_s} \right] \phi_u + \left[\frac{-8.7 f_{cm} \varepsilon_{cu} B}{12 d' E_s A'_s} \right] = 0$$

$$0.5 \phi_u^2 + \left[\frac{N + f_y (A_s + A'_s)}{2 d' E_s A'_s} - \frac{\varepsilon_{cu}}{2 d'} \right] \phi_u + \left[\frac{-f_{cm} \varepsilon_{cu} B}{1.38 d' E_s A'_s} \right] = 0$$

$$d' \cong 40$$

$$0.5 \phi_u^2 + \left[\frac{N + f_y (A_s + A'_s)}{16 A'_s 10^6} - \frac{\varepsilon_{cu}}{80} \right] \phi_u + \left[\frac{-f_{cm} \varepsilon_{cu} B}{22 A'_s \times 10^6} \right] = 0$$

$$a = 0.5$$

$$b = \frac{N + f_y (A_s + A'_s)}{16 A'_s 10^6} - \frac{\varepsilon_{cu}}{80}$$

$$c = \frac{-f_{cm} \varepsilon_{cu} B}{22 A'_s \times 10^6}$$

$$\phi_u = \frac{\sqrt{b^2 - 4 a c} - b}{2a} = \sqrt{b^2 - 2 c} - b$$

$$\alpha_3 = -2 c$$

$$\alpha_4 = b$$

$$\alpha_3 = \frac{\varepsilon_{cu} \cdot f_{cm} \cdot B}{11 \cdot A'_s \cdot 10^6}$$

$$\alpha_4 = \frac{N + f_y \cdot (A_s + A''_s)}{16 \cdot A'_s \cdot 10^6} - \frac{\varepsilon_{cu}}{80}$$

$$\phi_u = \sqrt{\alpha_4^2 + \alpha_3} - \alpha_4$$

For Wall sections:

$$\alpha_3 = \frac{5 \cdot \varepsilon_{cu} \cdot f_{cm} \cdot B}{H_C \cdot A'_s \cdot 10^6}$$

$$\alpha_4 = \frac{N + f_y \cdot (A_s + A''_s)}{2 \cdot H_C \cdot A'_s \cdot 10^6} - \frac{\varepsilon_{cu}}{H_C}$$

Where f_y is steel bars yield strength, f_{cm} is maximum strength of concrete, E_s is modulus of elasticity of steel, E_c is modulus of elasticity of concrete, ε_{cu} is ultimate strain of concrete, A_s is tension bars reinforcement area, A'_s is compression bars reinforcement area, A''_s is middle bars reinforcement area, d is tension bars effective depth, B is section width, N is applied axial force, and H_C is hidden column height of shear wall.

3.5 DEVELOPED SOFTWARE

A new software for estimating and plotting the moment curvature, interaction curve, and curvature ductility of reinforced concrete sections will be developed as a part of the study. Accordingly, the MCI software was created. In general, MCI software is a program that accurately analyzes and

calculates rectangular reinforced concrete components as well as shear walls in order to plot the moment curvature, interaction curve, and curvature ductility of afore-mentioned sections. This is generally done using the principles of finite element method by meshing the analyzed section into several layers. The program has several features and merits that enhances its performance as compared to other available software. These features and merits can be summarized as follows:

- Comparing the behavior of several sections at the same time.
- Evaluating the effect of various axial loads on the performance of the sections.
- Considering the effect of confinement or ignoring it for a certain section with the option of allowing a comparison of the results of both cases.
- Considering the influence of concrete in tension or ignoring it with the possibility of comparing the results together.
- Various material properties were already inserted in the database of the program for simplicity of defining the section properties. In addition, code-based equations were programed to simplify and facilitate the task of defining the material properties.
- Analyzing the section for both positive and negative bending moments with the option of comparing both cases together.
- In the case of rectangular column/beam sections, it allows the user to analyze the section in both perpendicular directions.
- It is possible to automatically identify some of the critical points on the moment curvature curve such as the one when the concrete reaches its maximum resistance and when it reaches the collapse point. In addition to that, in the case of confined concrete, the program determines and specifies the points were the concrete reaches its ultimate capacity and when the concrete crashes. On the other hand, when the tensile strength of concrete is considered, the point at

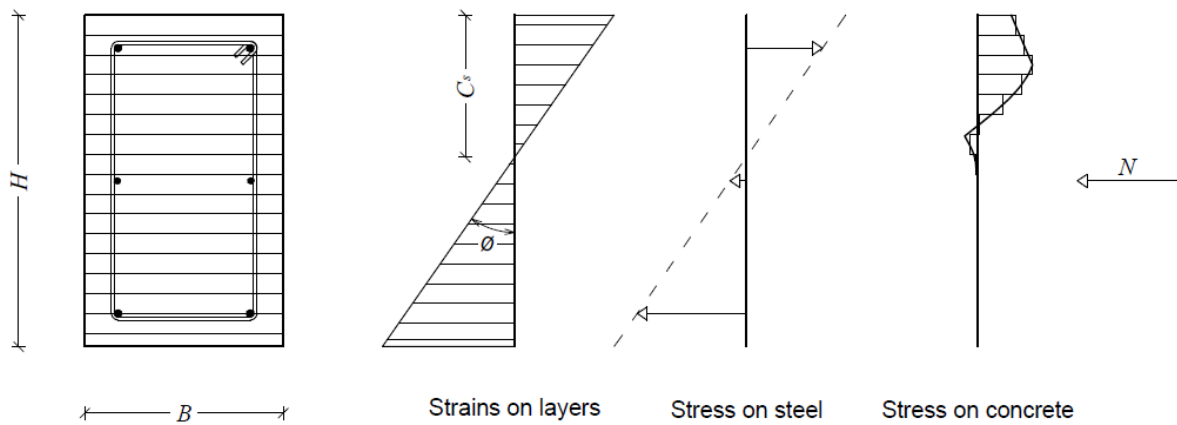
the ultimate tensile capacity and concrete failure in tension are indicated. However, in all cases, the yielding of reinforcements and their failure points are all stored in the program.

- Another important point in the developed software is its capability to present the results of the analysis after the upper layers of the concrete start crushing until total collapse of the section is achieved. This feature is not available in other software since they assume that the section has failed once crushing starts at the upper region, whereas it was found that the section can hold some capacity which can maintain its integrity for a fairly long period of time especially if the confinement is well designed until the complete collapse is reached. This case was not considered in the calculation of curvature ductility since the code presumes a total collapse once the concrete has been crushed.

Moment resistance of a cross section is the sum of the moment resistance of each material's particle around the natural axis. And because of the concrete stress strain relationship nonlinearity, the cross section will be subdivided into thin horizontal layers, assuming the stresses on each layer are uniformly distributed and equal to the stress at the middle of each layer. To find the moment resistance for a curvature value ϕ , the depth of the neutral axis C_s is assumed then strain on each layer is determined as follow:

$$\varepsilon_i = \phi \cdot y_i$$

where y_i is the distance between neutral axis and the center of layer i . After determining strains in all layers then stresses from stress-strain relationships, the sum of the forces for each section should be satisfy the equilibrium condition. When forces throughout the cross-section are in equilibrium, the bending moment can finally be determined using trial and error method.



For this purpose, MCI computer program was developed to make these repeated calculations and allowing the user to increase the accuracy by decreasing the layer's thicknesses as much as possible. The program has many options for section and material properties as shown in Figure 10, and Figure 11. In addition, it was provided with options to involve increment in concrete compressive strength due to lateral confinement and concrete tensile strength and shows their effects on bending resistance. The following figure shows flowchart of the procedure in a loop:

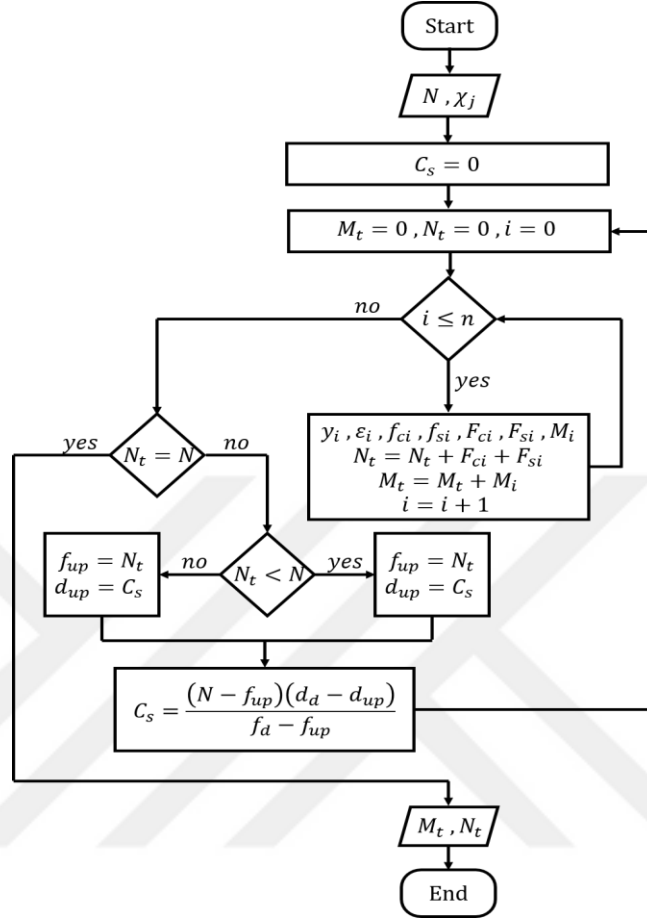


Figure 9: A flowchart of the procedure for calculating moment resistance.

Where N is the applied axial force, ϕ_j is the curvature value, C_s is the depth of neutral axis, n is the number of layers, M_t is the bending resistance of the cross section, N_t is the axial resistance, y_i is the distance between neutral axis and the center of layer i , ε_i is the strain at the center of layer i , f_{ci} is the stresses on concrete in layer i , f_{si} is the stresses on steel in layer i , F_{ci} is the concrete resistance of layer i , F_{si} is the steel resistance of layer i , and M_i is bending resistance of layer i .

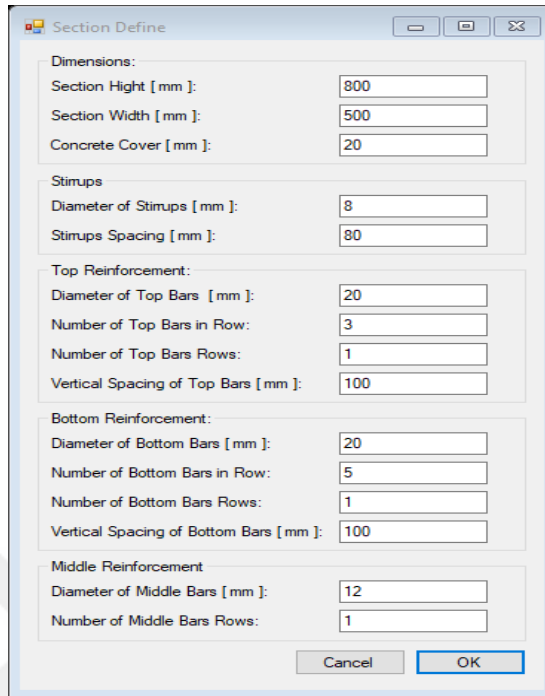


Figure 10: A screenshot of the section define window.

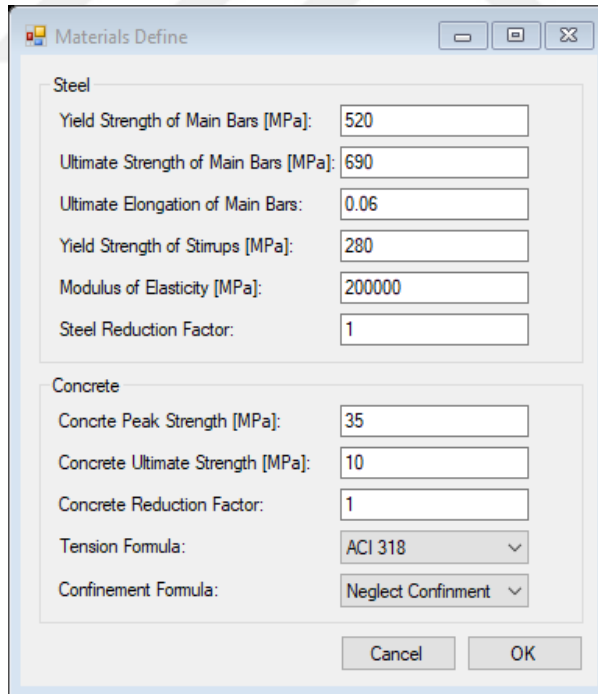


Figure 11: A screenshot of the material define window.

After calculations are done, the previous steps will be repeated for another curvature value until the cross section is unable to carry any bending moment, the following flowchart explain the whole procedure:

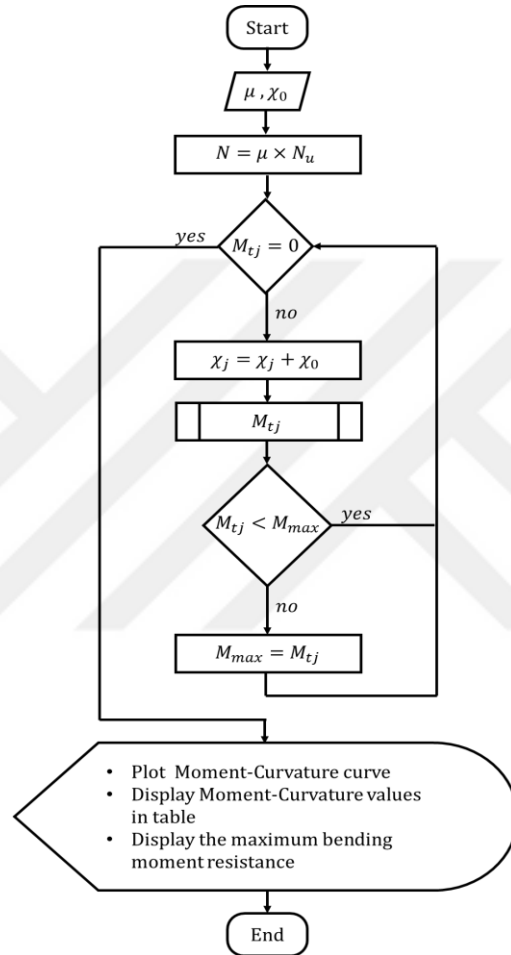


Figure 12: A flowchart of the procedure for plotting the moment curvature curve.

Where ϕ_0 is curvature step, μ is the ratio between the applied axial force and the axial compressive resistance of the cross section, N_u is the axial compressive resistance of the cross section, M_{tj} is the bending resistance of the cross section under a specific axial force and curvature value, and M_{max} is the maximum bending resistance of the cross section under a specific axial force.

The outputs of the program are displayed into two forms, a table and a graph show the relationship between bending moment and curvature as shown in figure 14, and the maximum point of the

moment-curvature curve represents the bending capacity of the cross section under the current applied axial force. The maximum bending capacity values for unlimited number of axial forces ranging between zero for pure bending moment to the ultimate compressive strength of the cross section represent the interaction curve as shown in figure 15. For plotting the interaction curve, the maximum bending resistances for many axial forces as proportions of the ultimate compressive strength of the cross section are determined, as shown in the following flowchart:

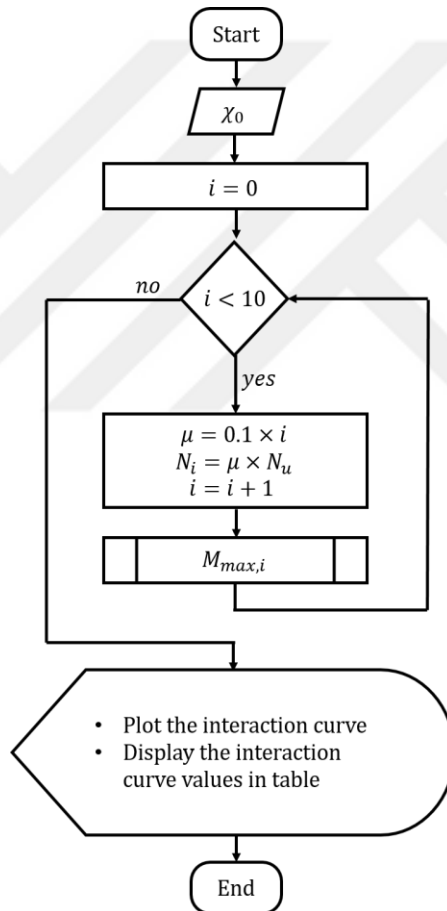


Figure 13: A flowchart of the procedure for plotting the interaction curve.

Where N_i is the applied axial force, i is the iteration number, and $M_{max,i}$ is the maximum bending resistance of the cross section under a specific axial force.

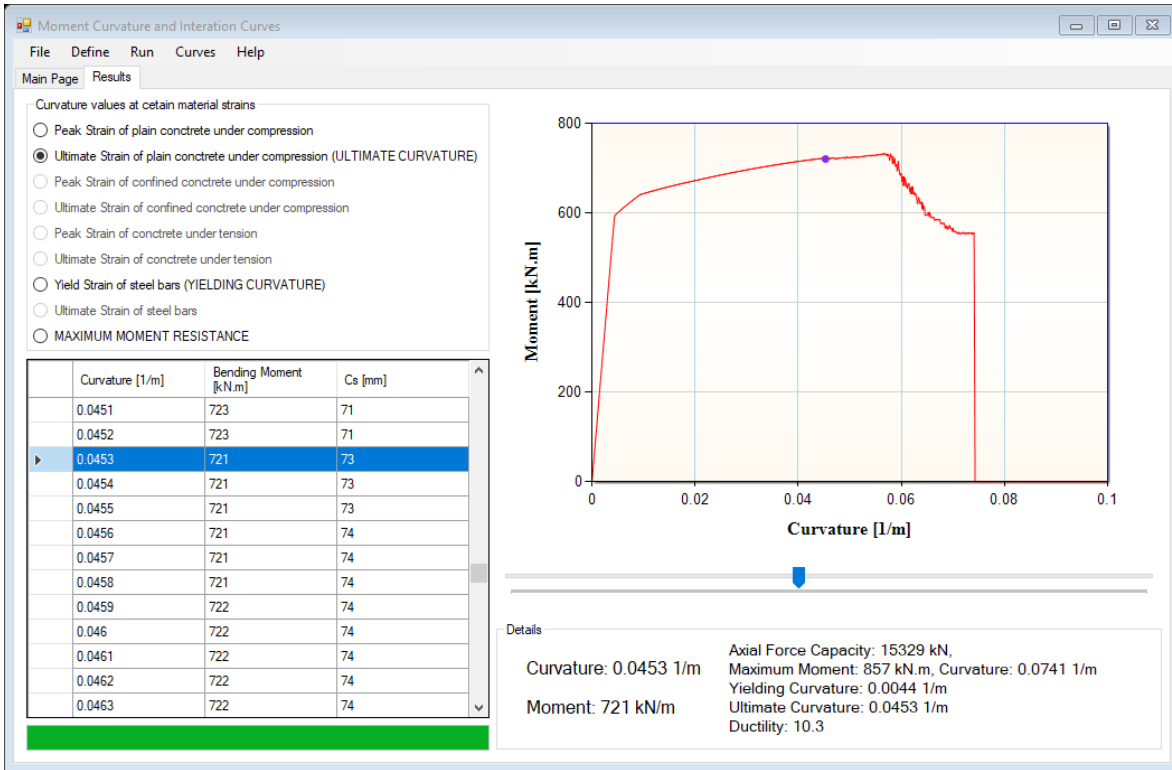


Figure 14: A screenshot of the moment curvature curve.

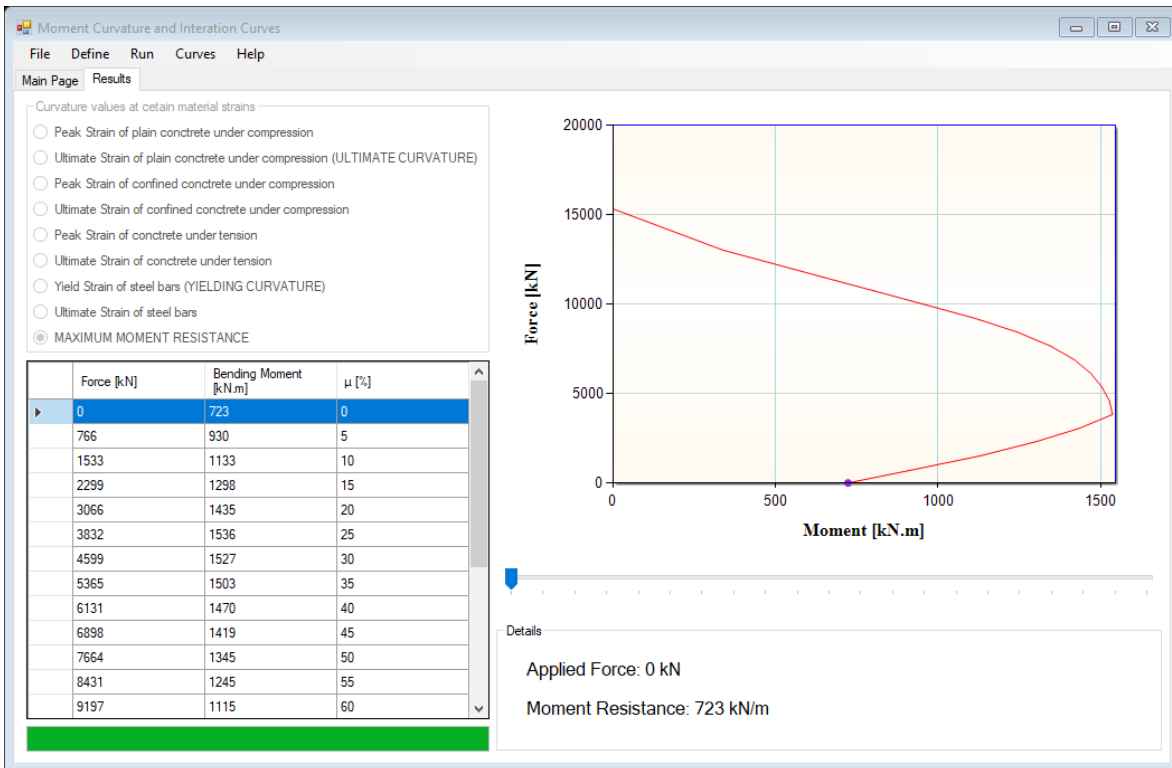


Figure 15: A screenshot of the interaction curve.

This program was designed for educational purpose to study the effects of several factors on moment curvature, interaction curve and curvature ductility. Several sections with various dimensions and material properties will be compared in this thesis. The used cross sections are listed in table 3, reinforcement distribution in table 4, and material properties in table5.

Table 3: Sections Dimensions.

	Height	Width	Concrete Cover	Height / Width
Section 1	500	300	20	1.67
Section 2	800	500	20	1.60
Section 3	1200	600	20	2.00
Wall Section	3000	300	20	10

Table 4: Sections Reinforcement.

	Stirrups		Top reinforcement		Bottom reinforcement		Middle reinforcement	
	Diameter	Spacing	Diameter	Number	Diameter	Number	Diameter	Number
Section 1	8	100	16	3	16	3	16	2
Section 2	8	80	20	3	20	5	12	2
Section 3	10	80	25	4	25	2×4	12	2×2
Wall	8	100	20	4×2	20	4×2	12	10×2

Table 5: Material Properties.

	Concrete				Steel			
	f_{cm}	ϵ_{cm}	ϵ_{cu}	E_c	f_y	f_u	E_s	f_{yt}
Low Strength	15	0.002	0.004	18319	280	420	200000	280
Normal Strength	35	0.002	0.0032	27983	520	690	200000	280
High Strength	80	0.0024	0.0026	42306	690	760	200000	420

The Moment Curvature curves of MCI software were compared with Xtract software and showed a good agreement as in Figure 16, Figure 18, Figure 20, Figure 22, Figure 24, Figure 26, Figure 28, Figure 30, Figure 32, Figure 34, Figure 36, and Figure 38. A slight shift was noticed in some sections after yielding point, and the reason of this shift is because of each software uses different formulae for concrete stress strain relationship and a different shape of mesh. Interaction curves of section 1 with low, normal, and high strength materials were compared with both Xtract and ETABS software as shown in Figure 17, Figure 19, and Figure 21 and they showed a good agreement, where Eurocode 2-2004 [14] was the used code in ETABS for column design. On the other hand, since ETABS software provides interaction curve for column sections with uniformly distributed reinforcement, thus section 2, section 3, and wall section were only compared with Xtract and showed a good agreement as in Figure 23, Figure 25, Figure 27, Figure 29, Figure 31, Figure 33, Figure 35, Figure 37, and Figure 39.

CHAPTER 4

RESULTS AND DISCUSSIONS

5.1 MOMENT CURVATURE

As previously mentioned, MCI software was developed for estimating the curvature ductility through parametric study where different RC sections at different strength characteristics of concrete with and without the consideration of confinement, axial load, and tension in concrete was performed. Furthermore, the written code for MCI software is shown in Appendix II. The software plots the interaction curve and calculates the yielding curvature, ultimate curvature, and curvature ductility accurately. Accordingly, three various strength characteristics of concrete which are low, normal, and high strength concrete were used for conducting the parametric study as well as four different percentages of axial load of 0%, 20%, 40%, and 60% were selected. Thereafter, the results of section 1, 2,3, and wall section of MCI software were compared with Xtract and ETABS for validating the outcomes. However, only results of section 1 were compared with both ETABS and Xtract while results of the other sections were compared only with Xtract since ETABS software provides interaction curve for column sections with uniformly distributed reinforcement. As can be noticed from the results, the accuracy of MCI software is somewhat similar to Xtract and ETABS. In fact, the interaction curve increases with the increase in the strength of the material for all sections. However, the results of section 2 reflected the best accuracy of MCI in comparison to Xtract while the results of wall section relatively exhibited the lowest accuracy as illustrated in Figure 17, Figure 19, Figure 21, Figure 23, Figure 25, Figure 27, Figure 29, Figure 31, Figure 33, Figure 35, Figure 37, and Figure 39.

5.2 EFFECT OF AXIAL LOAD

In this section, the influence of the axial load is discussed in detail. Generally, the results of this study have shown that applying an axial load on a certain reinforced concrete section reduces its ductility as shown in Figure 16, Figure 18, and Figure 20, in which the ductility of section 1 has reduced by almost 80% for 20% axial load regardless of the considerable increase in the moment as compressive axial load reduces the tensile stresses on steel and delay yielding in main bars. Regarding low strength case, the increase in moment is associated with the increase in axial load from 0% to 40% where any increase in axial load results in increase in moment. Normal strength concrete case exhibited similar results where the axial load of 40% showed the highest values in terms of the moment except the case of 20% for section 2 which showed highest values. High strength case showed consistent results for all sections where the highest moment values were at 40%. On the contrary, the decrease in curvature is associated with the increase in axial load from 0% to 60% where any increase in axial load results in decrease in the curvature for all sections at all strength characteristic cases as illustrated in Figure 16, Figure 18, Figure 20, Figure 22, Figure 24, Figure 26, Figure 28, Figure 30, Figure 32, Figure 34, Figure 36, and Figure 38. This observation can mainly be attributed to the increase in compressive stresses on concrete and the decrease in tensile stresses on steel bars. Furthermore, it can be seen in Table 6, Table 7, Table 8, and Table 9 that the ductility of the section reaches its peak in the case of axially unloaded column. Whereas it reduces between 80% to 90% when an axial load of about 20% of the ultimate capacity is applied. On the other hand, when the applied axial load is below 40% of the capacity of the section bending moment increases moderately while higher axial loads results in reducing the bending capacity of the section.

5.3 EFFECT OF STRENGTH OF MATERIALS

In this section, the effect of selecting high strength materials on the load carrying capacity, moment capacity as well as the ductility will be discussed in detail. In general, the curvature ductility of a given reinforced concrete section is influenced by three main factors as discussed by Olivia and Mandal (2015) [2]. These factors are the variation in the loads acting on the section including the rate of axial load applied, the ratio of longitudinal and transverse reinforcements, and the elastic capacity of concrete and steel materials. Similar observation was discussed by Baji and Ronagh (2011) [15] in which they highlighted that the curvature ductility increases with respect to the section size in which larger section provides higher ductility as compared to small sections and increasing the concrete's compressive strength results in enhanced curvature ductility.

The yielding moment can be referred to the peak of moment-curvature curve of an element which is directly dependent on the strength of the materials where any increase in the strength of the concrete or reinforcements results in higher yielding moment. Regarding the load carrying capacity, it is provided by the element to produce the ultimate moment which is referred to the moment acting at the capacity (ultimate). The utilization of high strength materials leads to an increase in the load carrying capacity and hence the ultimate moment capacity. As can be seen from the results, the increase in the strength of the material is accompanied with significant increase in the moment for all sections. For example, the maximum magnitude of moment for wall section at low strength case was approximately $7400 \frac{\text{kN}}{\text{M}}$ while it was $14000 \frac{\text{kN}}{\text{M}}$ for normal strength and $25000 \frac{\text{kN}}{\text{M}}$ for high strength case. On the other hand, ductility can be described as the ability of element to maintain plastic deformation to a high degree under the effect of tensile load before reaching fracture or failure. In addition to that, ductility can be represented as the permanent deformation using stress-strain curve. Therefore, as the strength of the materials increases, the

difference between the moment capacity and ultimate moment increases and hence notably reducing the ductility of the material. With respect to the curvature, the increase in the strength of the material is associated with considerable reduction in the ductility for all sections. For example, the maximum magnitude of curvature for wall section at low strength case was approximately $0.0048 \frac{1}{M}$ while it was $0.003 \frac{1}{M}$ for normal strength and $0.0022 \frac{1}{M}$ for high strength case.

In general, the results of this study have shown that when the tensile strength of concrete was included into analysis, an increment in moment resistance was observed for low curvature values, then a sudden decrease in resistance and returns to the same values in the case of neglecting tension in concrete. Moreover, considering the resistance of the section is the maximum resistance when tensile effect is included may causes a sudden collapse. Therefore, it is preferable to neglect tension in design. Where curvature ductility was not significantly affected, with a slight increase in the yielding curvature value, which led to a slight decrease in the curvature ductility.

The effect of lateral confinement on moment resistance and ductility was neglectable before the point at which concrete begins to collapse on compression. After this point, it was noticed a delay in total collapse and confinement causes an increase in moment resistance in some cases. Therefore, a good confinement helps delay the total section collapse, but should not be included during design.

By adding axial force gradually, we get the interaction curve for the three sections and it was noticed a gradual increase in the moment capacity of the section when applying a small axial force that does not exceed 30 to 40 percent of the total axial resistance, then moment capacity begins decreasing until the section loses its moment resistance when axial force equals to the maximum axial resistance. Where curvature ductility gradually decreases with the addition of axial force until it reaches a value of one, where the collapse under moment after this point becomes brittle.

Table 6: The curvature ductility of section 1 calculated by MCI software.

		Neglecting Confinement and Tension in Concrete			With Tension			With Confinement		
		ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ
LS	0.0	0.0042	0.0780	18.6	0.0046	0.0769	16.7	0.0042	0.0782	18.6
	0.2	0.0059	0.0210	3.6	0.0063	0.0205	3.3	0.0059	0.0245	4.2
	0.4	0.0048	0.0133	2.8	0.0044	0.0128	2.9	0.0050	0.0158	3.2
	0.6	0.0031	0.0098	3.2	0.0031	0.0095	3.1	0.0033	0.0115	3.5
NS	0.0	0.0074	0.0556	7.5	0.0077	0.0542	7.0	0.0074	0.0555	7.5
	0.2	0.0101	0.0177	1.8	0.0103	0.0171	1.7	0.0101	0.0182	1.8
	0.4	0.0096	0.0104	1.1	0.0092	0.0101	1.1	0.0100	0.0110	1.1
	0.6	0.0064	0.0072	1.1	0.0063	0.0072	1.1	0.0067	0.0079	1.2
HS	0.0	0.0093	0.0564	6.1	0.0096	0.0548	5.7	0.0093	0.0563	6.1
	0.2	0.0146	0.0130	0.9	0.0142	0.0126	0.9	0.0145	0.0128	0.9
	0.4	0.0078	0.0074	0.9	0.0078	0.0072	0.9	0.0118	0.0072	0.6
	0.6	0.0047	0.0047	1.0	0.0047	0.0047	1.0	0.0080	0.0048	0.6

Table 7: The curvature ductility of section 2 calculated by MCI software.

		Neglecting Confinement and Tension in Concrete			With Tension			With Confinement		
		ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ
LS	0.0	0.0025	0.0648	25.9	0.0029	0.0618	21.3	0.0025	0.0647	25.9
	0.2	0.0036	0.0141	3.9	0.0039	0.0132	3.4	0.0036	0.0171	4.8
	0.4	0.0027	0.0080	3.0	0.0026	0.0075	2.9	0.0028	0.0100	3.6
	0.6	0.0019	0.0059	3.1	0.0019	0.0058	3.1	0.0019	0.0071	3.7
NS	0.0	0.0044	0.0479	10.9	0.0047	0.0462	9.8	0.0044	0.0477	10.8
	0.2	0.0061	0.0111	1.8	0.0063	0.0105	1.7	0.0061	0.0119	2.0

	0.4	0.0056	0.0063	1.1	0.0054	0.0061	1.1	0.0059	0.0069	1.2
	0.6	0.0038	0.0044	1.2	0.0038	0.0044	1.2	0.0039	0.0048	1.2
HS	0.0	0.0056	0.0512	9.1	0.0058	0.0491	8.5	0.0056	0.0512	9.1
	0.2	0.0079	0.0082	1.0	0.0083	0.0078	0.9	0.0085	0.0080	0.9
	0.4	0.0047	0.0046	1.0	0.0047	0.0045	1.0	0.0072	0.0045	0.6
	0.6	0.0029	0.0029	1.0	0.0029	0.0029	1.0	0.0050	0.0030	0.6

Table 8: The curvature ductility of section 3 calculated by MCI software.

		Neglecting Confinement and Tension in Concrete			With Tension			With Confinement		
		ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ
LS	0.0	0.0018	0.0661	36.7	0.0020	0.0651	32.6	0.0018	0.0661	36.7
	0.2	0.0026	0.0105	4.0	0.0028	0.0100	3.6	0.0026	0.0131	5.0
	0.4	0.0018	0.0055	3.1	0.0017	0.0052	3.1	0.0019	0.0072	3.8
	0.6	0.0012	0.0040	3.3	0.0012	0.0039	3.3	0.0013	0.0050	3.8
NS	0.0	0.0031	0.0462	14.9	0.0033	0.0451	13.7	0.0031	0.0461	14.9
	0.2	0.0044	0.0080	1.8	0.0045	0.0077	1.7	0.0044	0.0088	2.0
	0.4	0.0038	0.0043	1.1	0.0036	0.0042	1.2	0.0040	0.0048	1.2
	0.6	0.0025	0.0029	1.2	0.0025	0.0029	1.2	0.0026	0.0034	1.3
HS	0.0	0.0039	0.0473	12.1	0.0041	0.0458	11.2	0.0039	0.0472	12.1
	0.2	0.0061	0.0057	0.9	0.0059	0.0055	0.9	0.0061	0.0056	0.9
	0.4	0.0031	0.0031	1.0	0.0031	0.0030	1.0	0.0049	0.0030	0.6
	0.6	0.0017	0.0017	1.0	0.0018	0.0018	1.0	0.0033	0.0020	0.6

Table 9: The curvature ductility of wall section calculated by MCI software.

		Neglecting Confinement and Tension in Concrete			With Tension			With Confinement		
		ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ

		ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ
LS	0.0	0.0007	0.0109	15.6	0.0007	0.0106	15.1	0.0007	0.0119	17.0
	0.2	0.0009	0.0040	4.4	0.0010	0.0038	3.8	0.0009	0.0046	5.1
	0.4	0.0007	0.0023	3.3	0.0007	0.0019	2.7	0.0007	0.0022	3.1
	0.6	0.0005	0.0017	3.4	0.0005	0.0016	3.2	0.0005	0.0019	3.8
NS	0.0	0.0011	0.0098	8.9	0.0012	0.0095	7.9	0.0011	0.0101	9.2
	0.2	0.0016	0.0031	1.9	0.0016	0.0029	1.8	0.0016	0.0033	2.1
	0.4	0.0015	0.0018	1.2	0.0014	0.0017	1.2	0.0015	0.0019	1.3
	0.6	0.0010	0.0012	1.2	0.0010	0.0012	1.2	0.0011	0.0014	1.3
HS	0.0	0.0014	0.0105	7.5	0.0015	0.0102	6.8	0.0014	0.0104	7.4
	0.2	0.0020	0.0023	1.2	0.0021	0.0022	1.0	0.0020	0.0023	1.2
	0.4	0.0012	0.0012	1.0	0.0013	0.0012	0.9	0.0019	0.0013	0.7
	0.6	0.0007	0.0007	1.0	0.0007	0.0007	1.0	0.0013	0.0009	0.7

5.4 PROPOSED DUCTILITY EQUATIONS

As mentioned earlier, curvature ductility is important for design. To calculate ductility, ultimate curvature is divided by yielding curvature. After analyzing several sections with various properties using the program that was designed for this purpose the equations shown in the following table were proposed:

Table 10: Curvature ductility equations for rectangular and wall sections.

For Rectangular Sections	
$\alpha_1 = \frac{f_y}{E_s \cdot d}$ $\alpha_2 = \frac{N + f_y \cdot A_s}{B \cdot d^2 \cdot E_c} + \alpha_1$	$\alpha_3 = \frac{\varepsilon_{cu} \cdot f_{cm} \cdot B}{16 \cdot A'_s \cdot 10^6}$ $\alpha_4 = \frac{N + f_y \cdot (A_s + A_s'')}{16 \cdot A'_s \cdot 10^6} - \frac{\varepsilon_{cu}}{80}$
$\phi_y = \sqrt{\alpha_2^2 - \alpha_1^2 + \alpha_2}$	$\phi_u = \sqrt{\alpha_4^2 + \alpha_3 - \alpha_4}$
$\eta_\phi = \frac{\phi_u}{\phi_y} \geq 1$	

For Wall Sections	
$\alpha_1 = \frac{f_y}{E_s \cdot d}$ $\alpha_2 = \frac{N + f_y \cdot A_s}{B \cdot d^2 \cdot E_c} + \alpha_1$	$\alpha_3 = \frac{5 \cdot \varepsilon_{cu} \cdot f_{cm} \cdot B}{H_C \cdot A'_s \cdot 10^6}$ $\alpha_4 = \frac{N + f_y \cdot (A_s + A_s'')}{2 \cdot H_C \cdot A'_s \cdot 10^6} - \frac{\varepsilon_{cu}}{H_C}$
$\phi_y = \sqrt{\alpha_2^2 - \alpha_1^2 + \alpha_2}$	$\phi_u = \sqrt{\alpha_4^2 + \alpha_3 - \alpha_4}$
$\eta_\phi = \frac{\phi_u}{\phi_y} \geq 1$	

5.5 PROPOSED DUCTILITY EQUATIONS VS SOFTWARE RESULTS

The proposed equation for estimating the ductility yielded similar results to MCI software with a mean error of $\pm 15\%$ in the case of absence of axial force and a mean error of $\pm 22\%$ in the case that axial force is available as shown in Tables 11 & 12 and Figures 48, 49, 50 & 51.

In fact, the yield curvature of reinforced concrete section can be affected by the dimensions of its cross-section, the rate of the applied axial load, the characteristic strength of concrete, and slightly by the thickness of the concrete cover and the amount of longitudinal reinforcement according to Sheikh et al. (2010) [16].

Table 11: Comparison of curvature ductility between MCI software and the proposed equation without axial force.

$\mu = 0$									
	MCI Software			Proposed Equation			Error %		
	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ
#1-LS	0.0042	0.0780	18.6	0.0041	0.0769	18.8	-2 %	-1 %	1 %
#1-NS	0.0074	0.0556	7.5	0.0072	0.0584	8.1	-3 %	5 %	8 %
#1-HS	0.0093	0.0564	6.1	0.0091	0.0653	7.2	-2 %	16 %	18 %
#2-LS	0.0025	0.0648	25.9	0.0025	0.0729	29.4	0 %	13 %	14 %
#2-NS	0.0044	0.0479	10.9	0.0043	0.0547	12.6	-2 %	14 %	16 %

#2-HS	0.0056	0.0512	9.1	0.0055	0.0621	11.3	-2 %	21 %	24 %
#3-LS	0.0018	0.0661	36.7	0.0017	0.0532	31.0	-6 %	-20 %	-16 %
#3-NS	0.0031	0.0462	14.9	0.0030	0.0321	10.8	-3 %	-31 %	-28 %
#3-HS	0.0039	0.0473	12.1	0.0038	0.0355	9.5	-3 %	-25 %	-21 %
W-LS	0.0007	0.0109	15.6	0.0006	0.0112	18.5	-14 %	3 %	19 %
W-NS	0.0011	0.0098	8.9	0.0011	0.0084	7.9	0 %	-14 %	-11 %
W-HS	0.0014	0.0105	7.5	0.0014	0.0096	7.0	0 %	-9 %	-7 %

Table 12: Comparison of curvature ductility between MCI software and the proposed equation with 20% axial force.

$\mu = 0.2$									
	MCI Software			Proposed Equation			Error %		
	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ
#1-LS	0.0059	0.0210	3.6	0.0056	0.0279	5.0	-5 %	33 %	39 %
#1-NS	0.0101	0.0177	1.8	0.0096	0.0171	1.8	-5 %	-3 %	0 %
#1-HS	0.0130	0.0130	1.0	0.0127	0.0149	1.2	-2 %	15 %	20 %
#2-LS	0.0036	0.0141	3.9	0.0033	0.0178	5.3	-8 %	26 %	36 %
#2-NS	0.0061	0.0111	1.8	0.0058	0.0117	2.0	-5 %	5 %	11 %
#2-HS	0.0079	0.0082	1.0	0.0076	0.0100	1.3	-4 %	22 %	30 %
#3-LS	0.0026	0.0105	4.0	0.0023	0.0112	5.0	-12 %	7 %	25 %
#3-NS	0.0044	0.0080	1.8	0.0039	0.0072	1.9	-11 %	-10 %	6 %
#3-HS	0.0057	0.0057	1.0	0.0051	0.0063	1.2	-11 %	11 %	20 %
W-LS	0.0009	0.0040	4.4	0.0009	0.0032	3.4	0 %	-20 %	-23 %
W-NS	0.0016	0.0031	1.9	0.0016	0.0021	1.3	0 %	-32 %	-32 %
W-HS	0.0020	0.0023	1.2	0.0021	0.0018	1.0	5 %	-22 %	-17 %

5.6 OLIVIA`S EQUATION FOR DUCTILITY VS SOFTWARE RESULTS

In fact, a detailed comparison between the developed software herein and the approach suggested by Olivia & Mandal (2015) [2] has been conducted to evaluate the reliability of the proposed mathematical formulae. Generally, the results have shown a variation between both methodologies with an error of 56% and 126% for section 1 and 2 as well as the wall section respectively in the case of close values of tensile and compression reinforcements. These considerable differences can be mainly attributed to the basic assumption of these methods in which Olivia & Mandal assume that the compression reinforcements reach their yielding capacity before the crushing. This assumption cannot be generalized for all cases since it is applicable only when the ratio of compression reinforcements steel is relatively small as compared to the ratio of tensile reinforcements as seen in section 3 where the error was between 7% and 37% as shown in Table 13 and Figures 48, 49, 50 & 51. On the other hand, Olivia & Mandal's model cannot predict the cases of axially loaded sections.

Table 13: Comparison of curvature ductility between MCI software and Olivia & Mandal's equation without axial force.

$\mu = 0$									
	MCI Software			Olivia & Mandal Equation			Error %		
	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ	ϕ_y	ϕ_u	η_ϕ
#1-LS	0.0042	0.0780	18.6	0.0040	0.1155	29.1	-5 %	48 %	56 %
#1-NS	0.0074	0.0556	7.5	0.0070	0.1094	15.5	-5 %	97 %	107 %
#1-HS	0.0093	0.0564	6.1	0.0090	0.1243	13.8	-3 %	120 %	126 %
#2-LS	0.0025	0.0648	25.9	0.0024	0.0906	37.4	-4 %	40 %	44 %
#2-NS	0.0044	0.0479	10.9	0.0043	0.0858	20.0	-2 %	79 %	83 %
#2-HS	0.0056	0.0512	9.1	0.0055	0.0975	17.8	-2 %	90 %	96 %
#3-LS	0.0018	0.0661	36.7	0.0017	0.0385	23.1	-6 %	-42 %	-37 %

#3-NS	0.0031	0.0462	14.9	0.0029	0.0364	12.4	-6 %	-21 %	-17 %
#3-HS	0.0039	0.0473	12.1	0.0037	0.0414	11.2	-5 %	-12 %	-7 %
W-LS	0.0007	0.0109	15.6	0.0006	0.0205	34.5	-14 %	88 %	121 %
W-NS	0.0011	0.0098	8.9	0.0011	0.0194	18.3	0 %	98 %	106 %
W-HS	0.0014	0.0105	7.5	0.0014	0.0221	16.2	0 %	110 %	116 %



CHAPTER 5

CONCLUSIONS

This thesis has focused on estimating the curvature ductility of different RC sections at different strength characteristics of concrete with and without the application of axial load, confinement, and tension in concrete using a developed software and a proposed equation. As a part of the research, a parametric study was conducted to evaluate the influencing parameters on the curvature ductility of different RC sections.

In general, the developed software aimed to determine the moment curvature, interaction curve, and curvature ductility of rectangular RC sections and shear walls. The importance of this software is attributed to its enhanced features and capabilities in terms of the possibility of comparing different sections together, assessing the effect of axial load value on the section properties, considering the effects of confinement, and concrete's tensile strength as well as simply defining the material properties of the section either in a manual way or through a code-based equation. In addition to that, it automatically highlights the crucial points of a given curve in which the material achieved its ultimate capacity or has failed. Moreover, it is based on a sophisticated approach by means of conducting the analysis in the post-crush behavior through analyzing the section beyond the state of collapse of the upper layers of the concrete.

The results of this study have shown a significant improvement in the proposed approach against the currently available ones. Furthermore, the developed program was capable of analyzing and estimating the moment curvature, interaction curve, and curvature ductility of different RC sections with good accuracy in comparison to both ETABS and Xtract. In fact, the results of the

parametric study have presented a considerable independency of the sectional ductility on the level of confinement and the tensile strength of the used concrete. Regarding the developed mathematical formulae, the ductility equation produced a good accuracy and has a good agreement with Olivia & Mandal's equation except in the case of high compression reinforcement ratio where some notable differences were seen since Olivia & Mandal's equation presumes that the compression reinforcement always reaches the yielding point before crushing. This study is expected to help practicing engineers in their daily works through reliably estimating the behavior of reinforced concrete section.

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APPENDIX I: LIST OF FIGURES

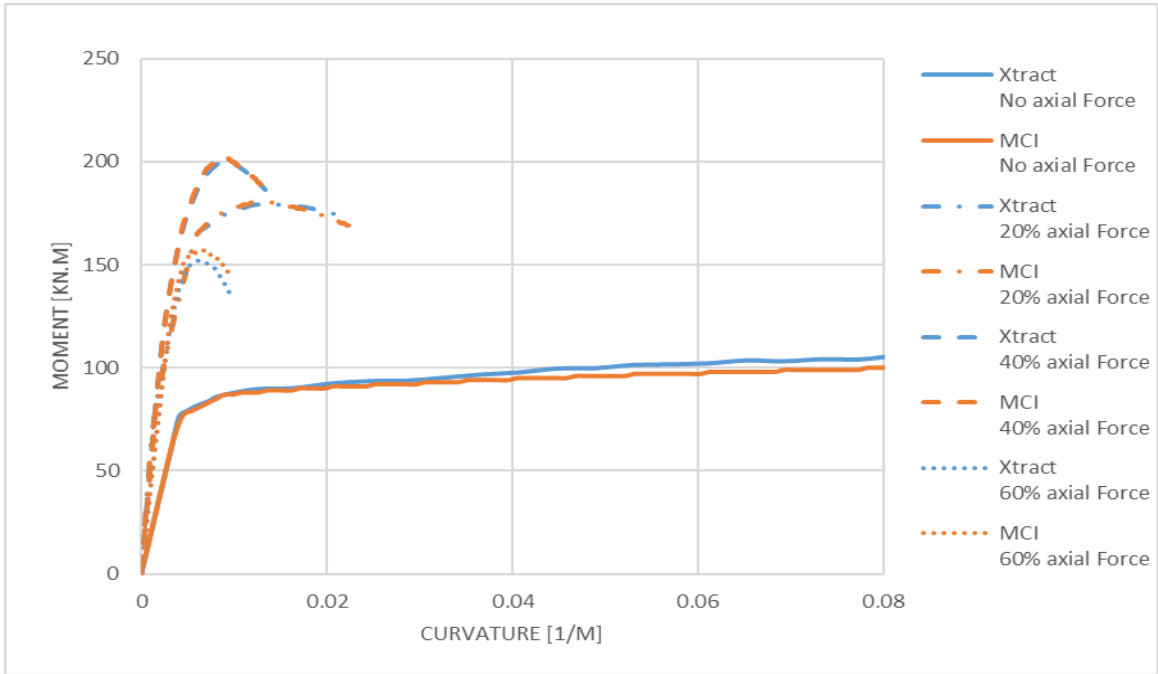


Figure 16: Moment Curvature Curves of Section 1 – Low Strength Materials

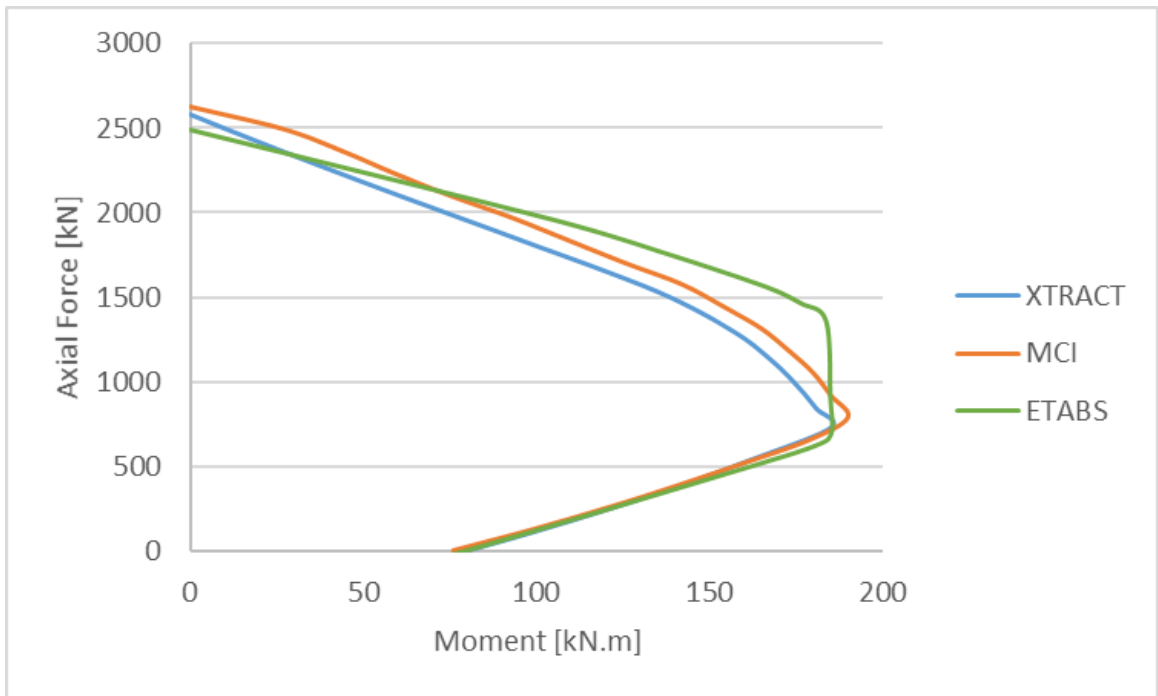


Figure 17: Interaction Curve of Section 1 – Low Strength Materials

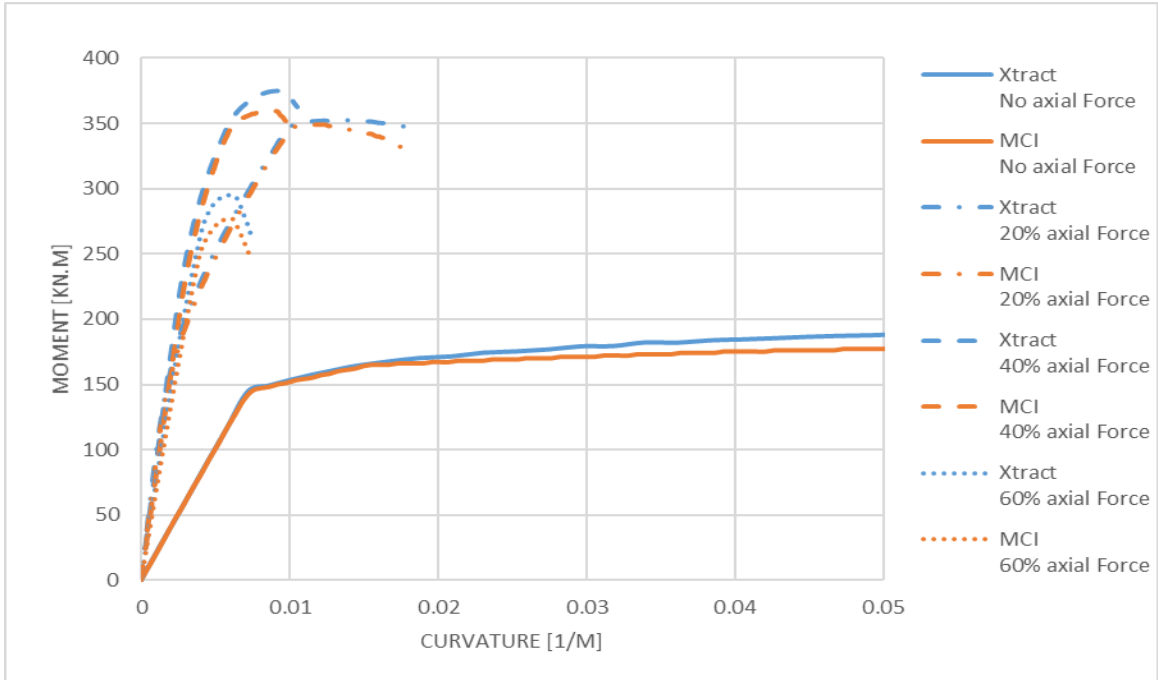


Figure 18: Moment Curvature Curves of Section 1 – Normal Strength Materials

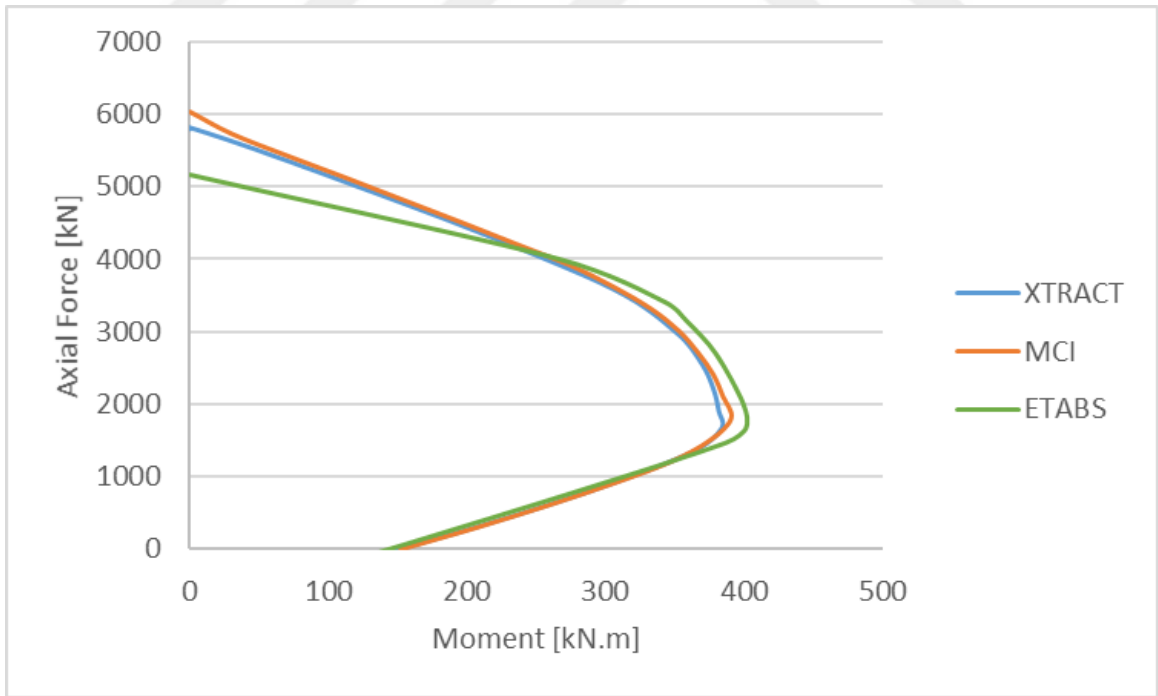


Figure 19: Interaction Curve of Section 1 – Normal Strength Materials

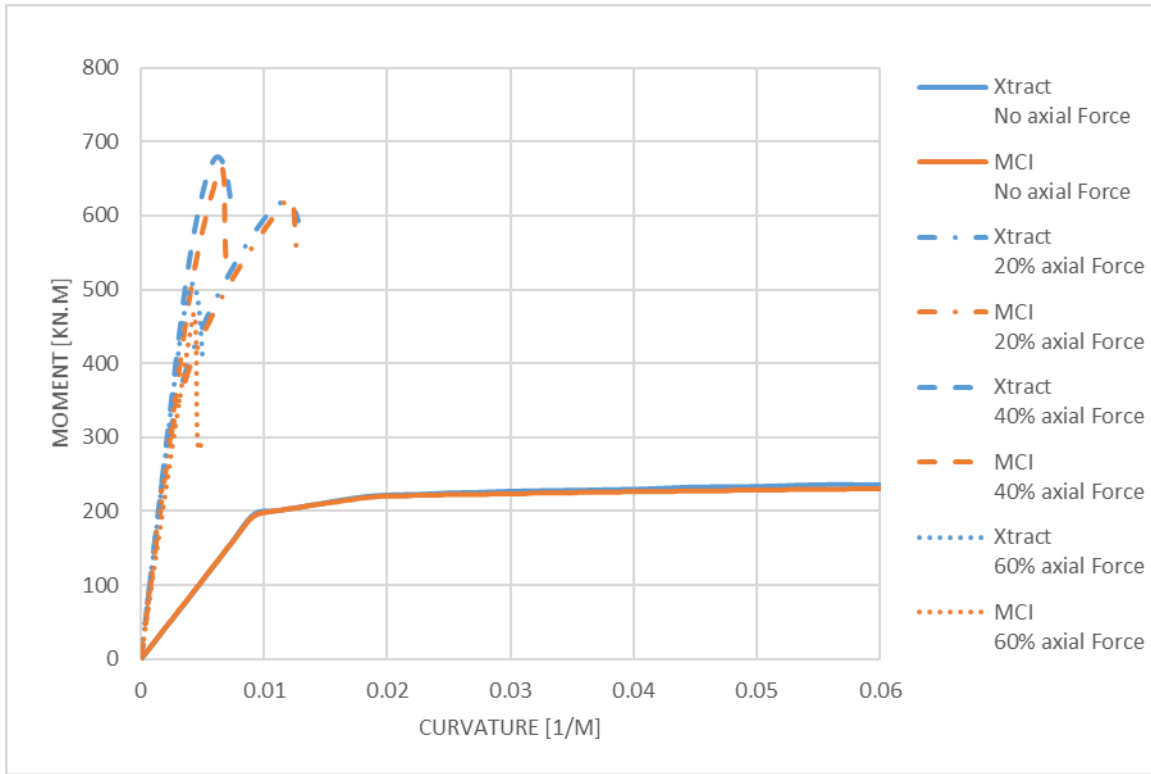


Figure 20: Moment Curvature Curves of Section 1 – High Strength Materials

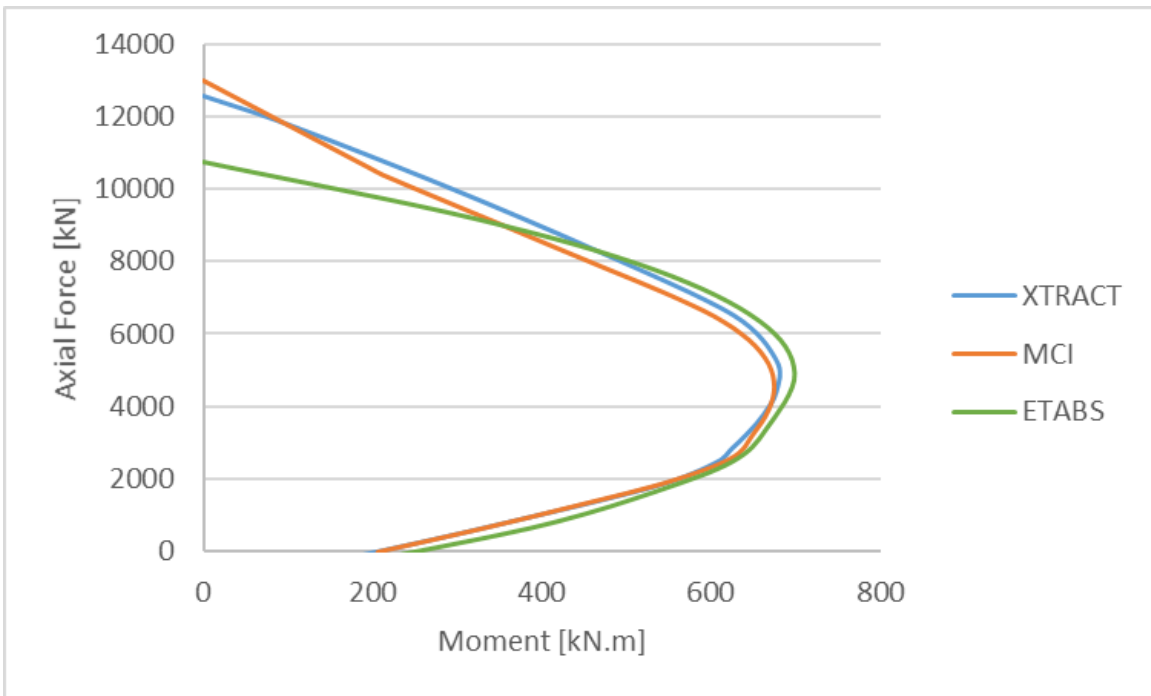


Figure 21: Interaction Curve of Section 1 – High Strength Materials

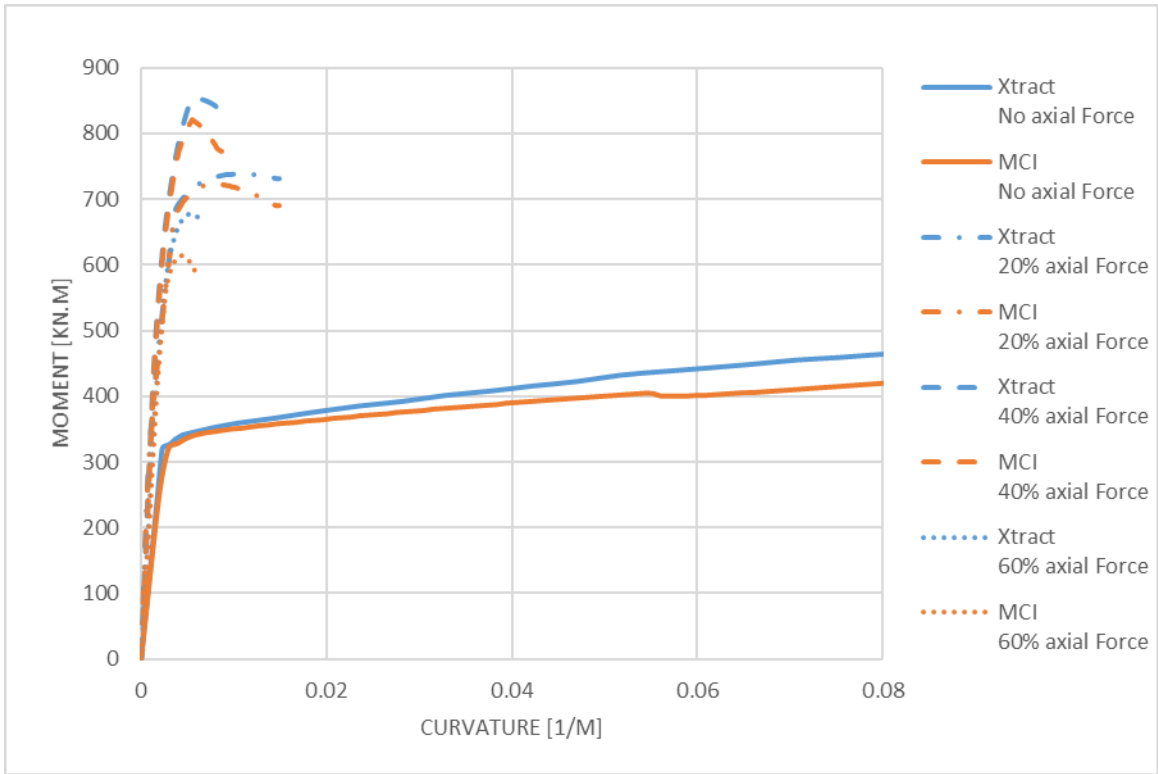


Figure 22: Moment Curvature Curves of Section 2 – Low Strength Materials

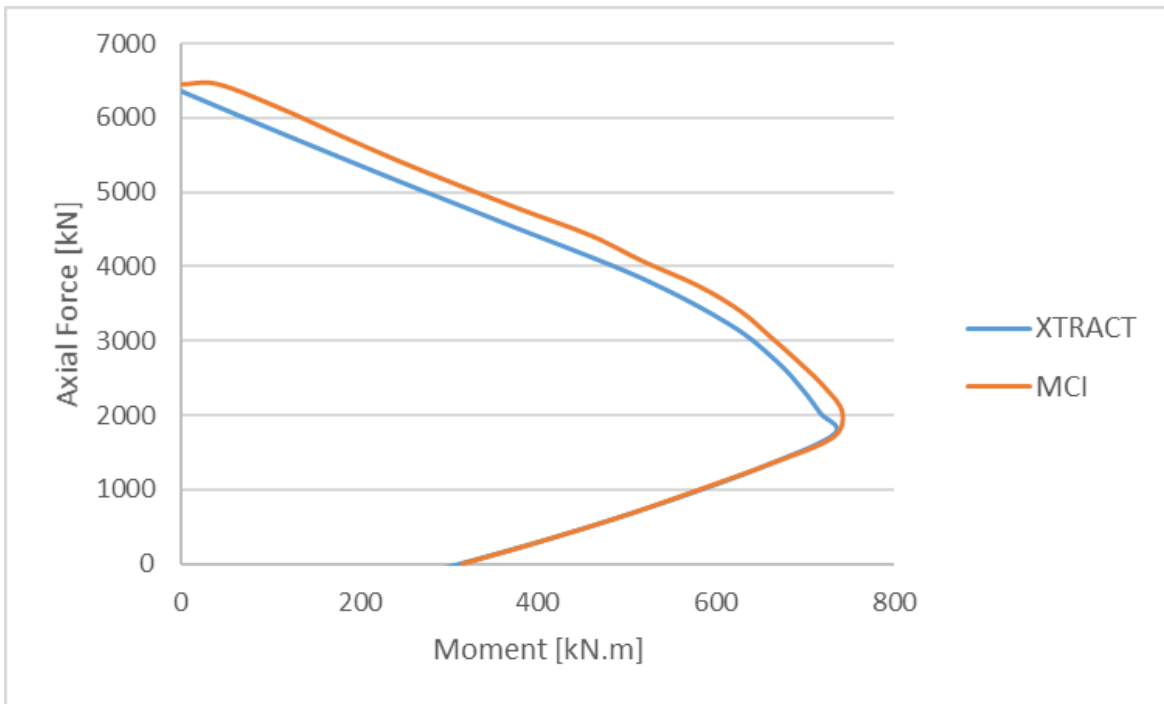


Figure 23: Interaction Curve of Section 2 – Low Strength Materials

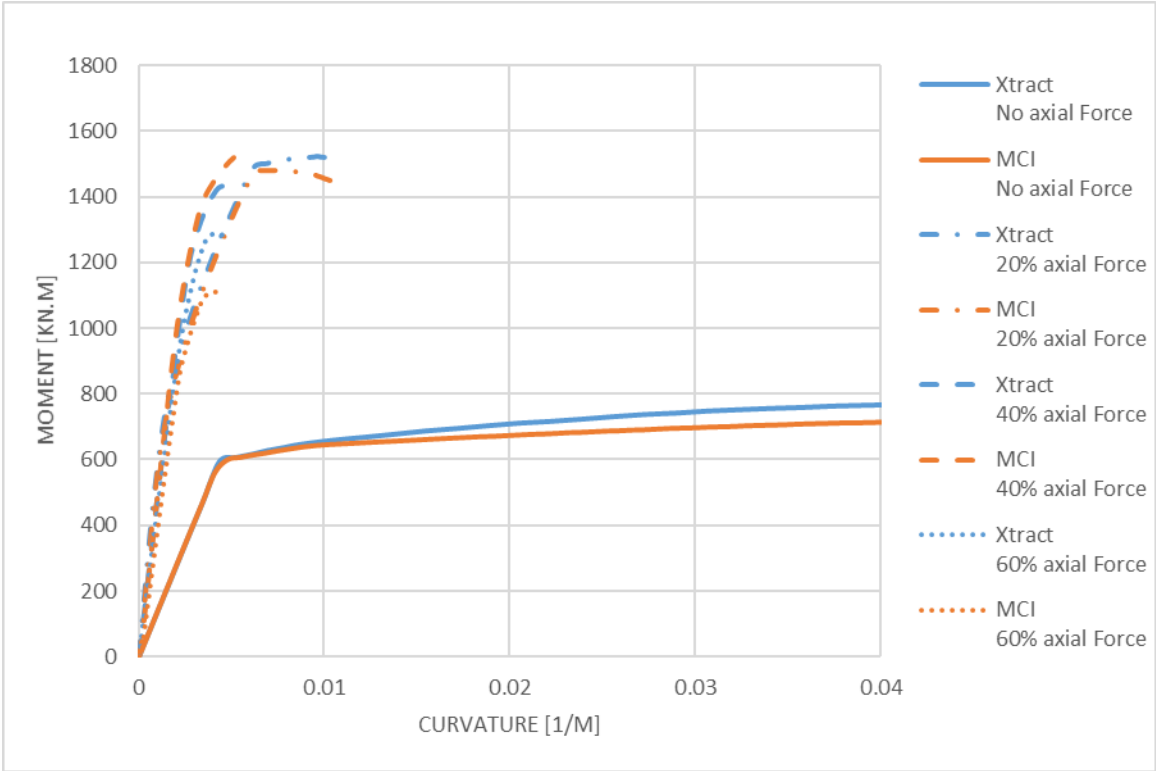


Figure 24: Moment Curvature Curves of Section 2 – Normal Strength Materials

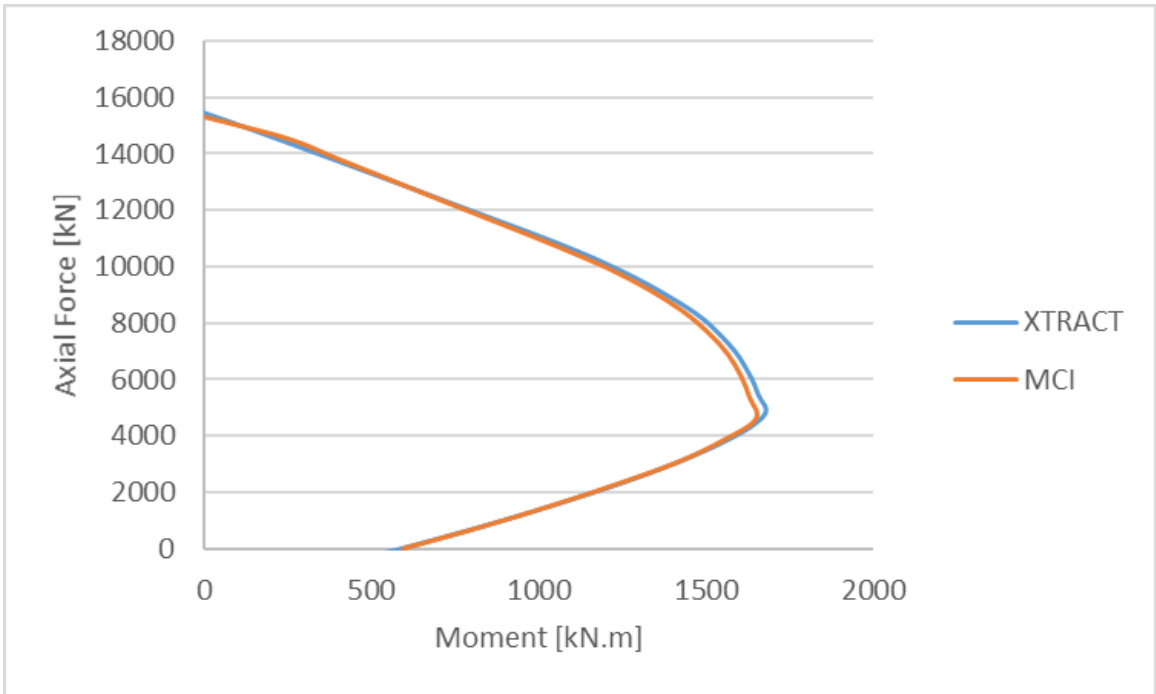


Figure 25: Interaction Curve of Section 2 – Normal Strength Materials

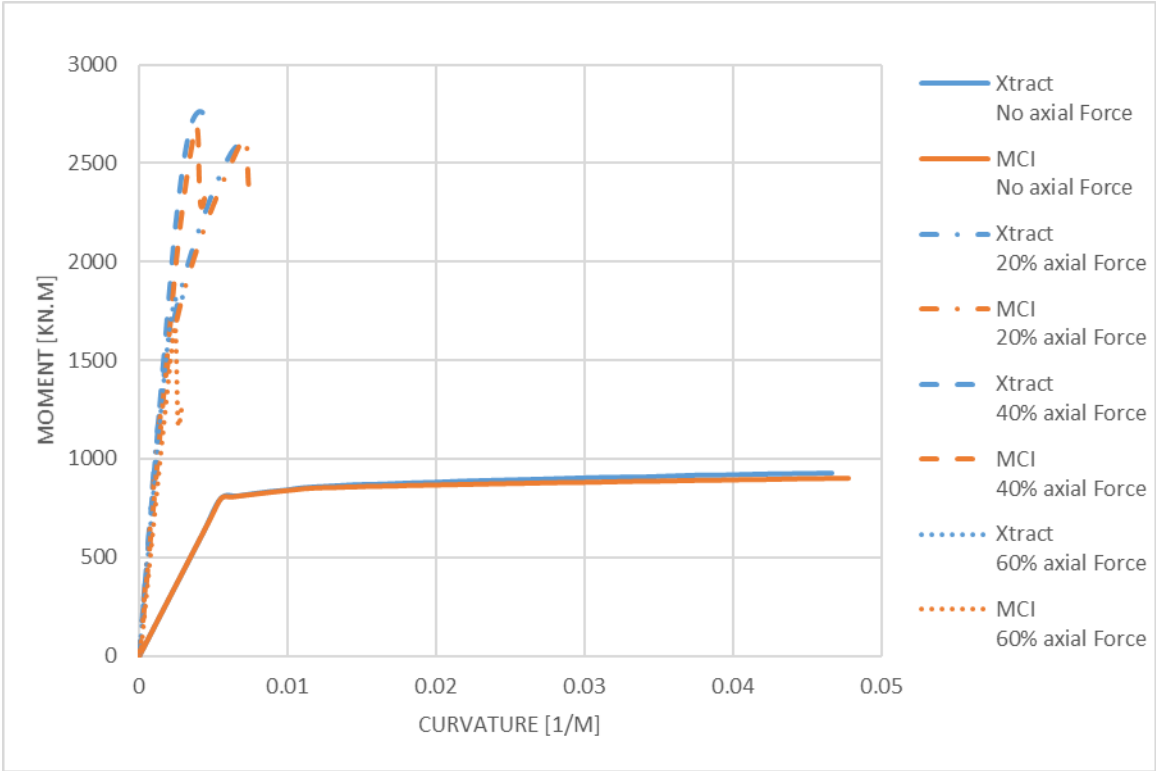


Figure 26: Moment Curvature Curves of Section 2 – High Strength Materials

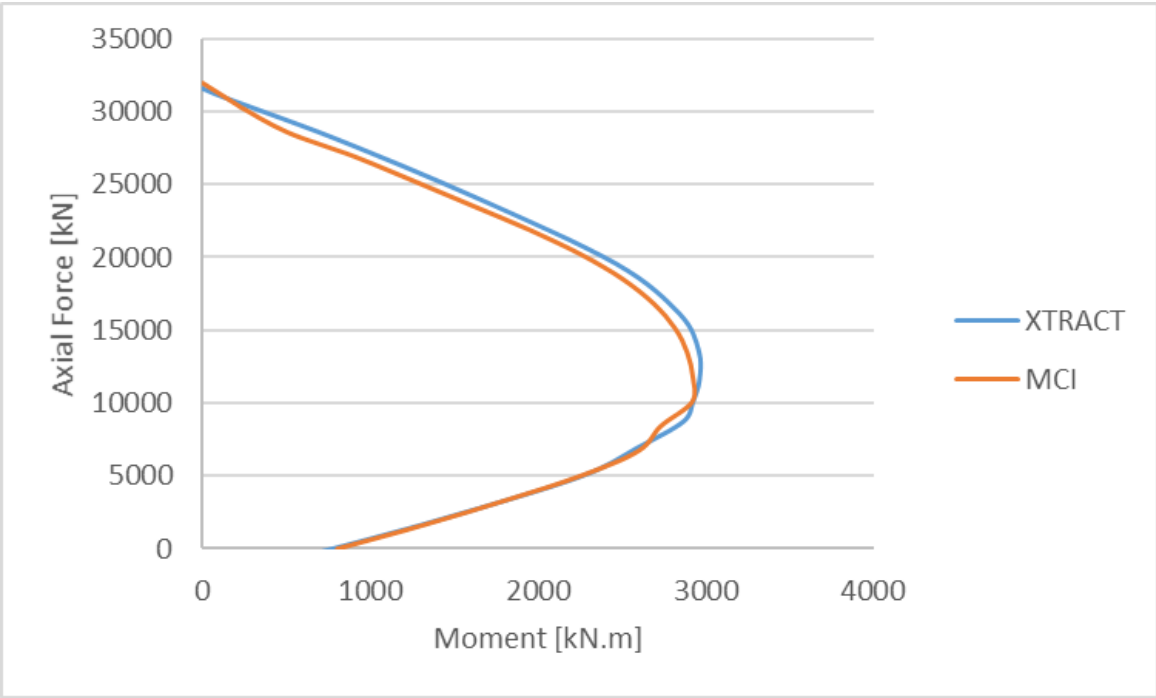


Figure 27: Interaction Curve of Section 2 – High Strength Materials

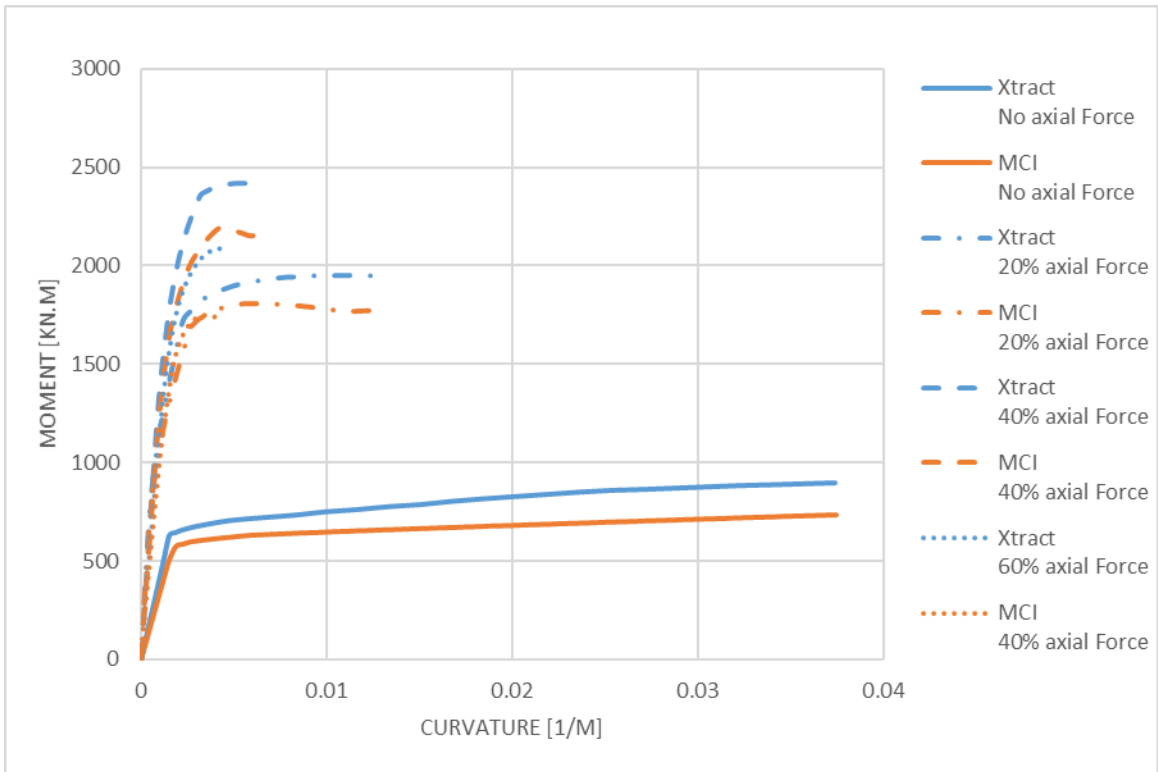


Figure 28: Moment Curvature Curves of Section 3 – Low Strength Materials

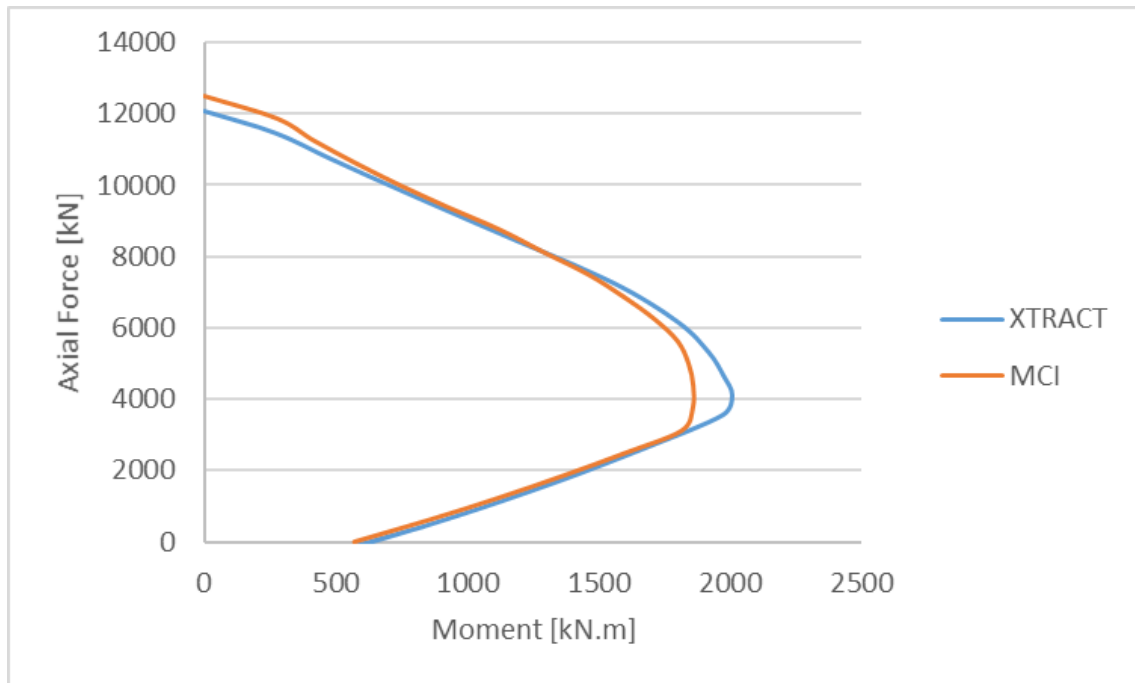


Figure 29: Interaction Curve of Section 3 – Low Strength Materials

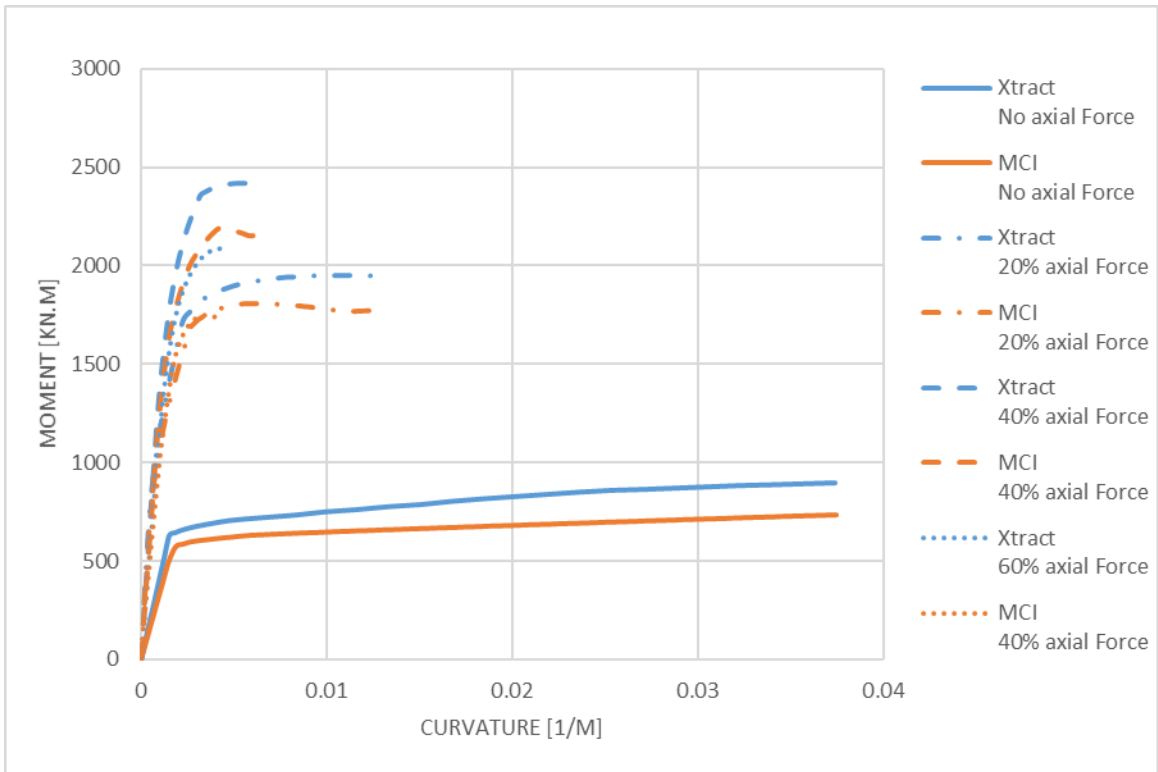


Figure 30: Moment Curvature Curves of Section 3 – Normal Strength Materials

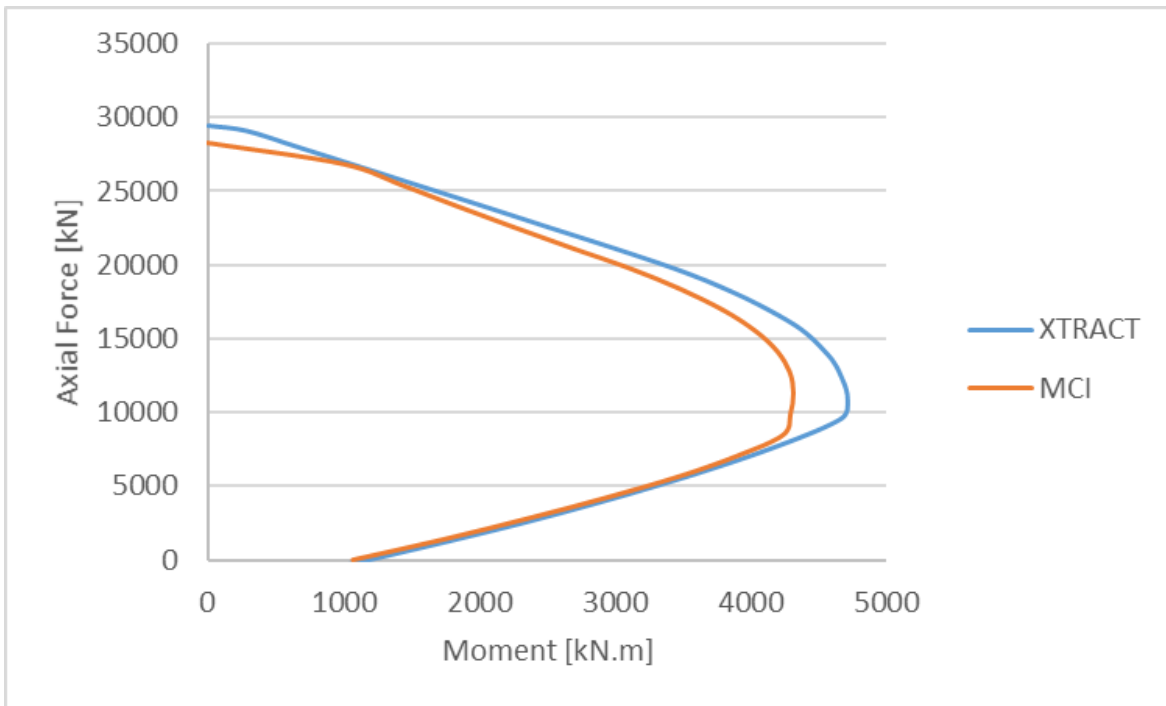


Figure 31: Interaction Curve of Section 3 – Normal Strength Materials

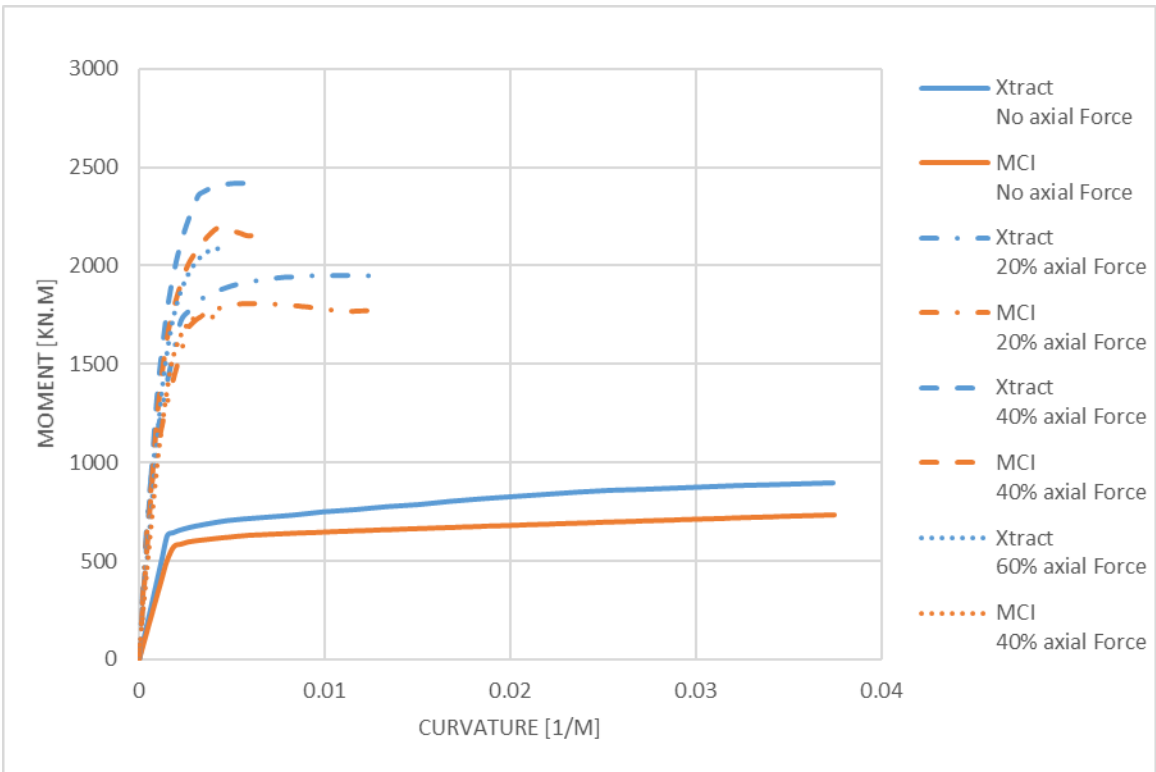


Figure 32: Moment Curvature Curves of Section 3 – High Strength Materials

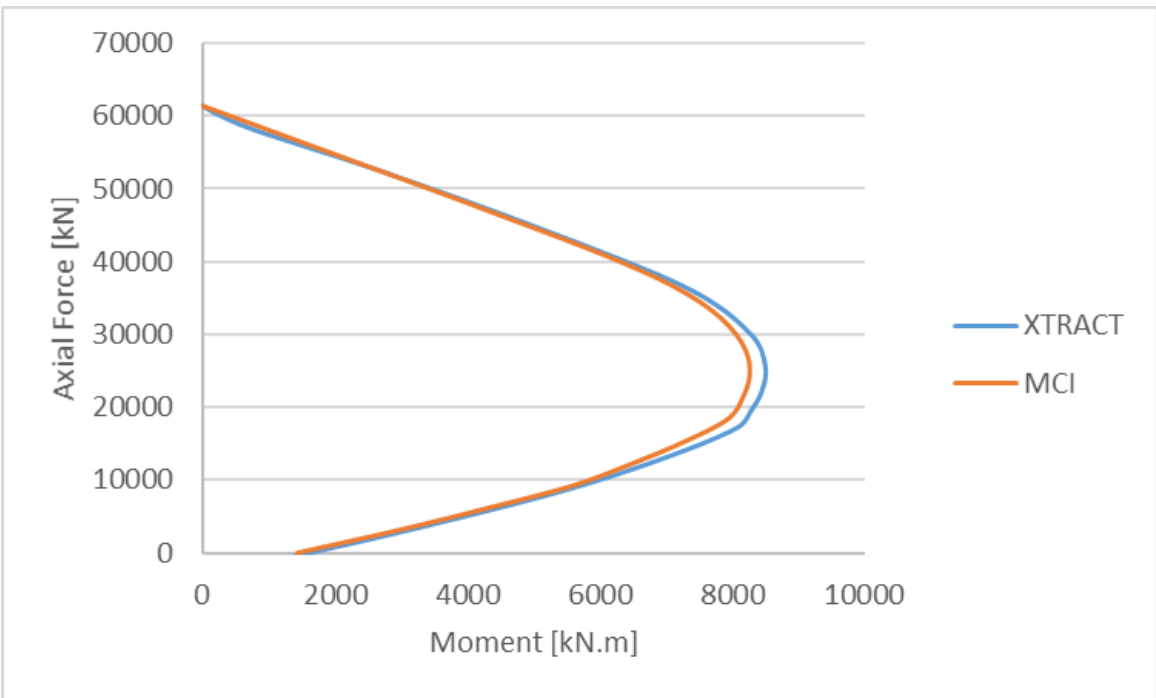


Figure 33: Interaction Curve of Section 3 – High Strength Materials

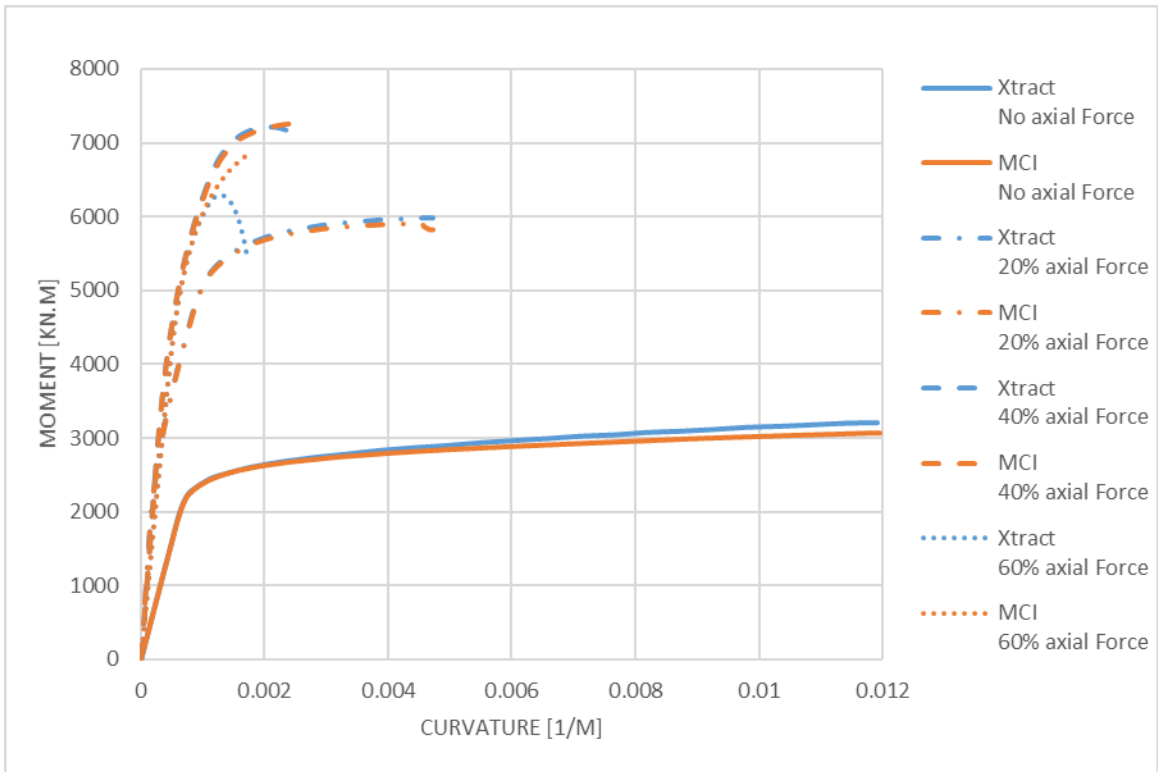


Figure 34: Moment Curvature Curves of Wall Section – Low Strength Materials

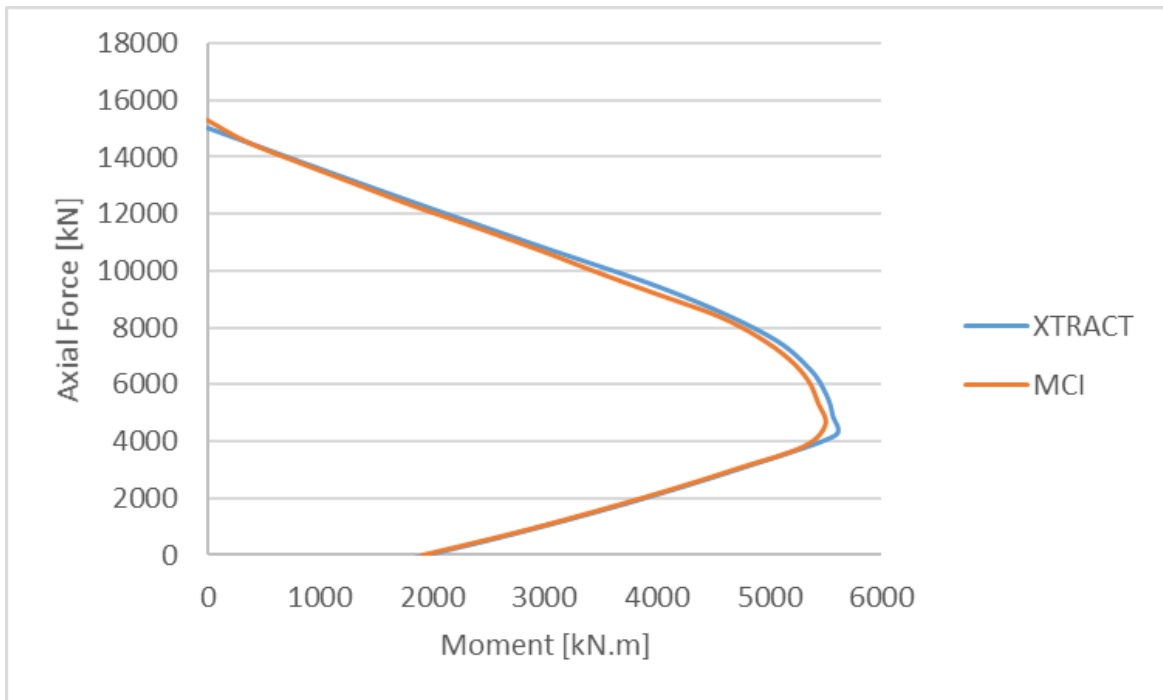


Figure 35: Interaction Curve of Wall Section – Low Strength Materials

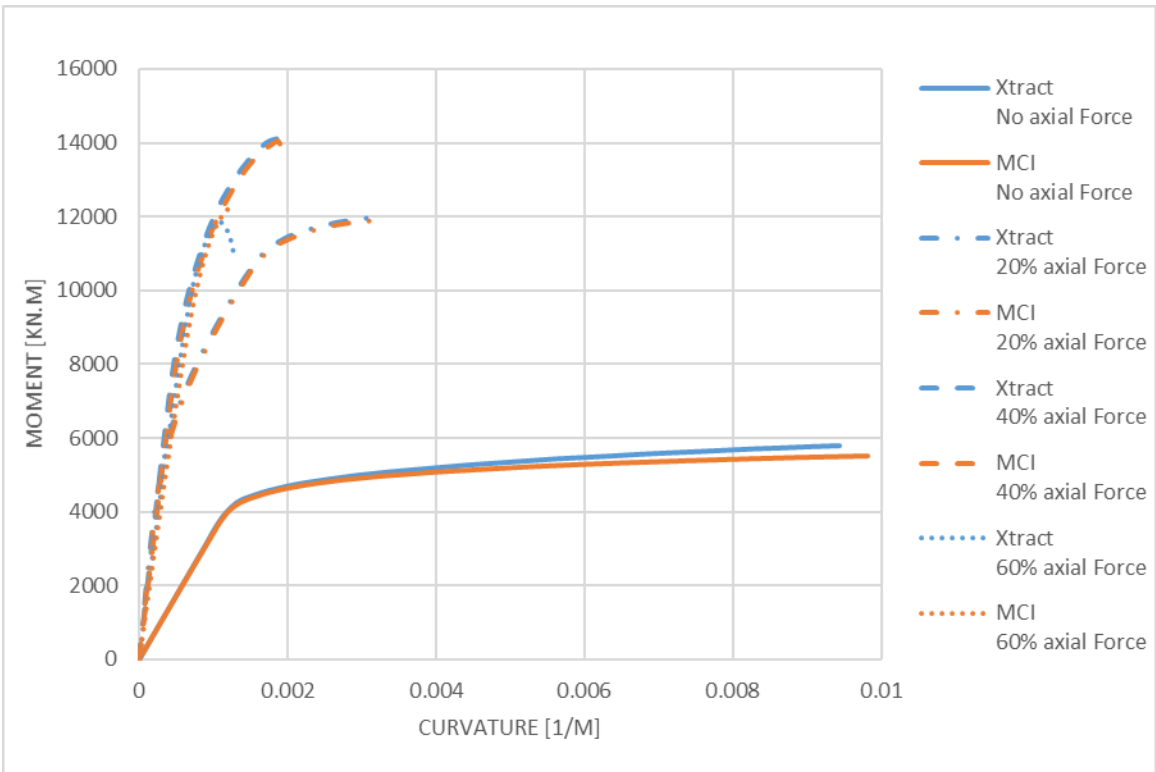


Figure 36: Moment Curvature Curves of Wall Section – Normal Strength Materials

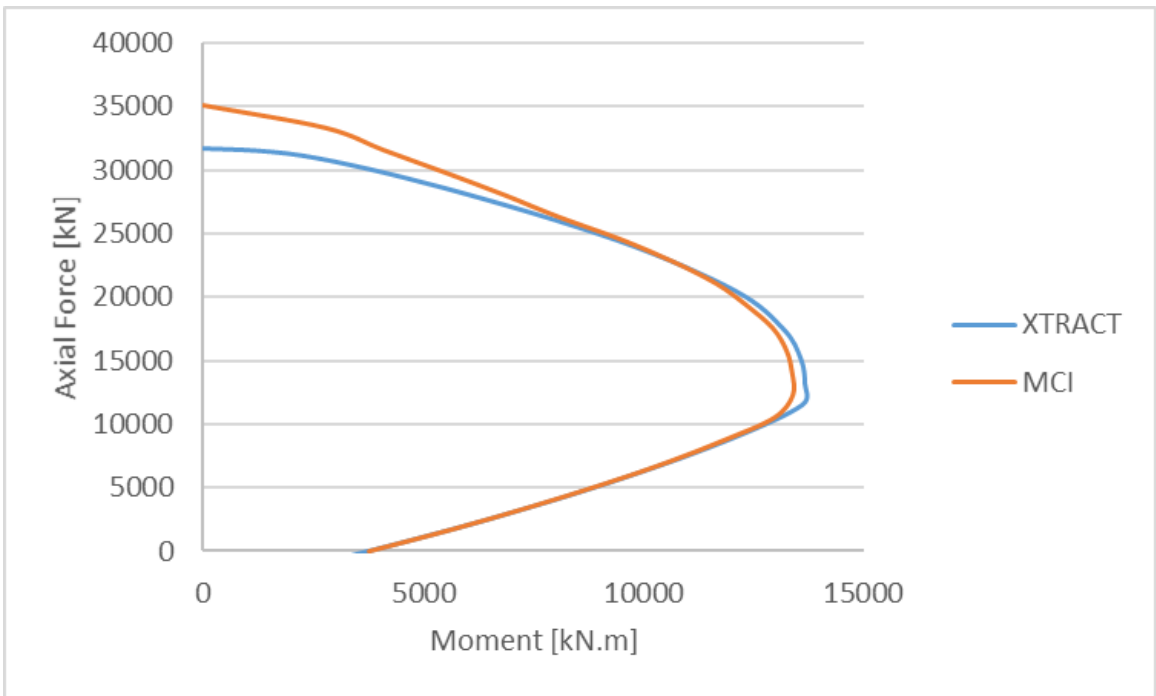


Figure 37: Interaction Curve of Wall Section – Normal Strength Materials

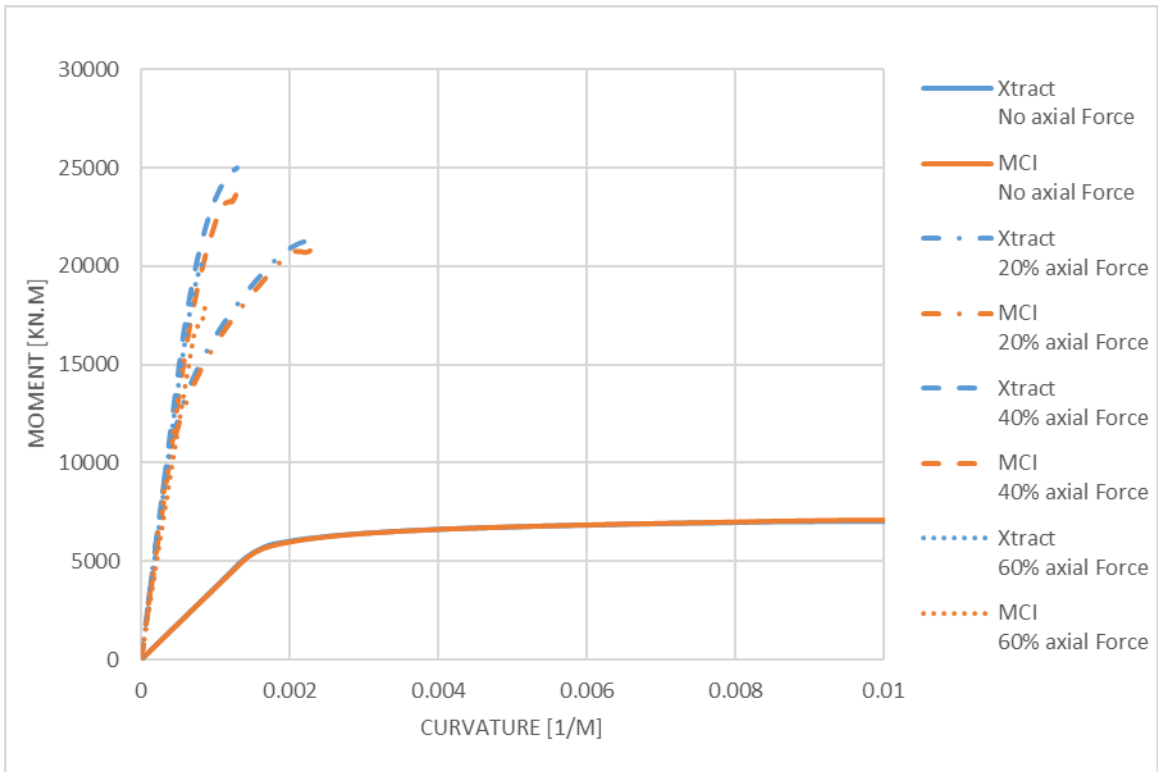


Figure 38: Moment Curvature Curves of Wall Section – High Strength Materials

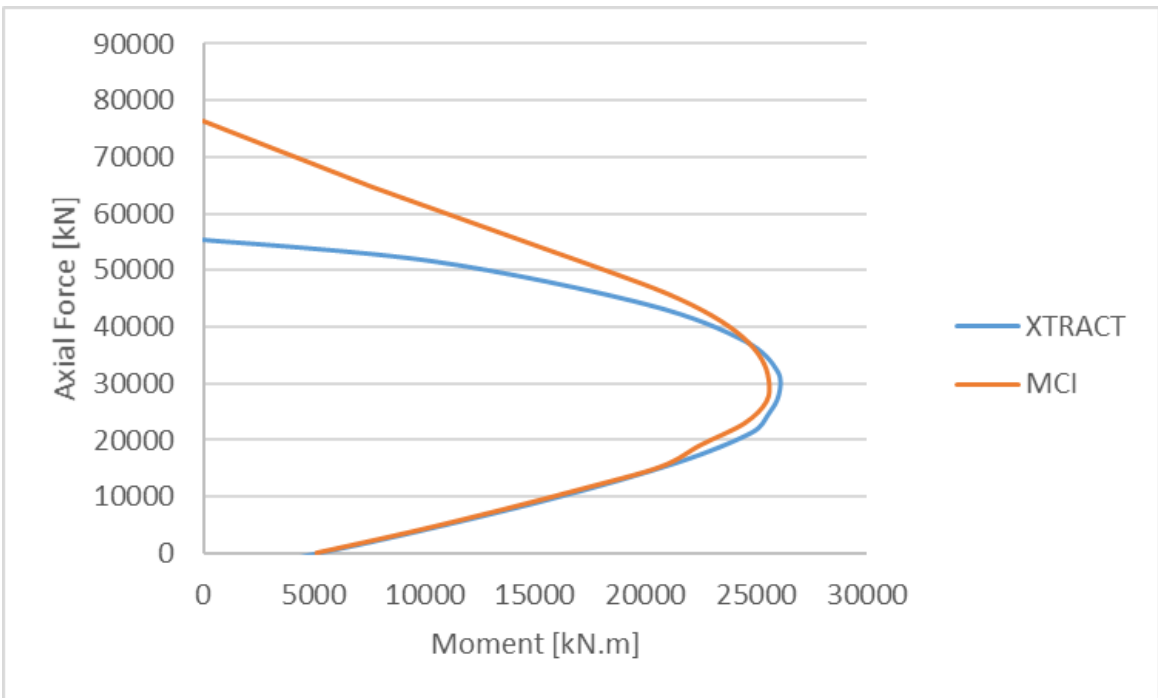
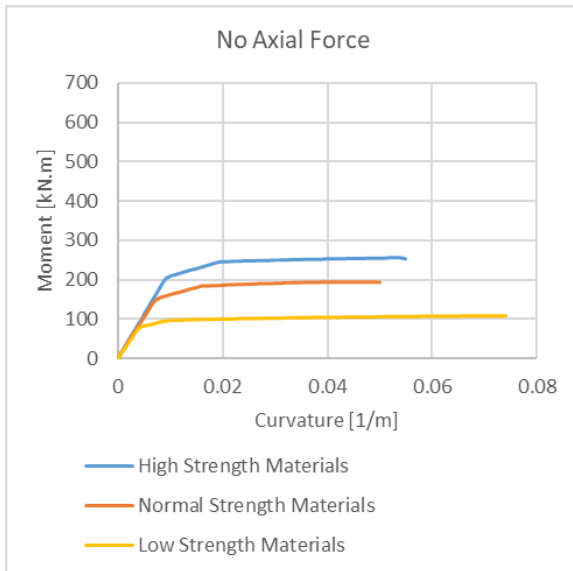
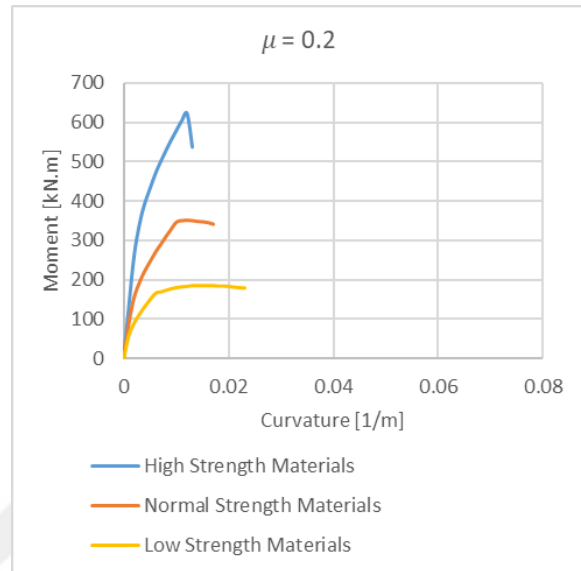


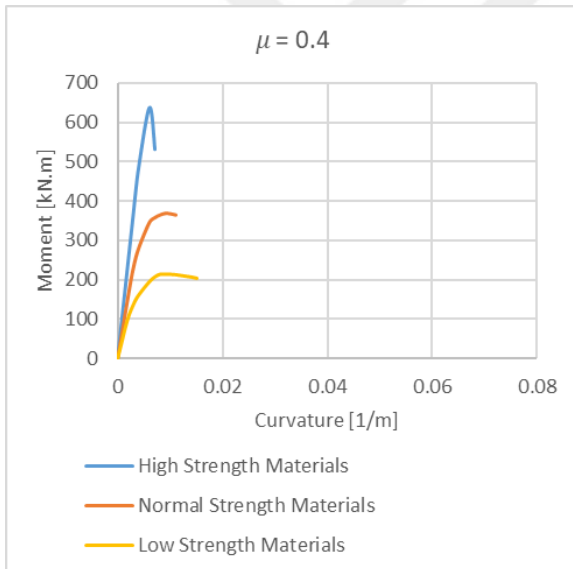
Figure 39: Interaction Curve of Wall Section – High Strength Materials



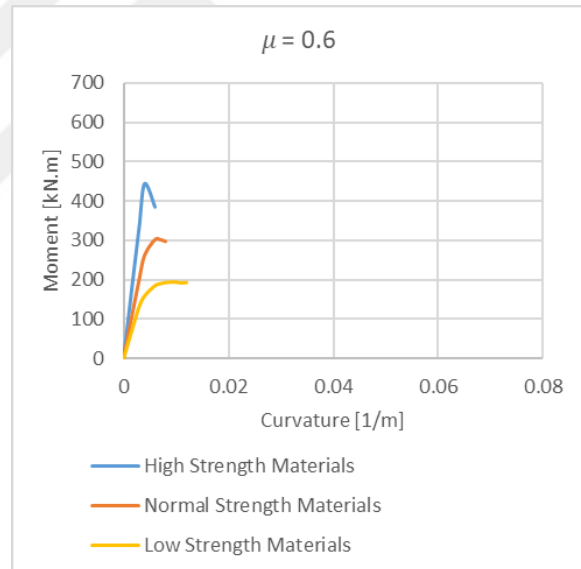
(a)



(b)

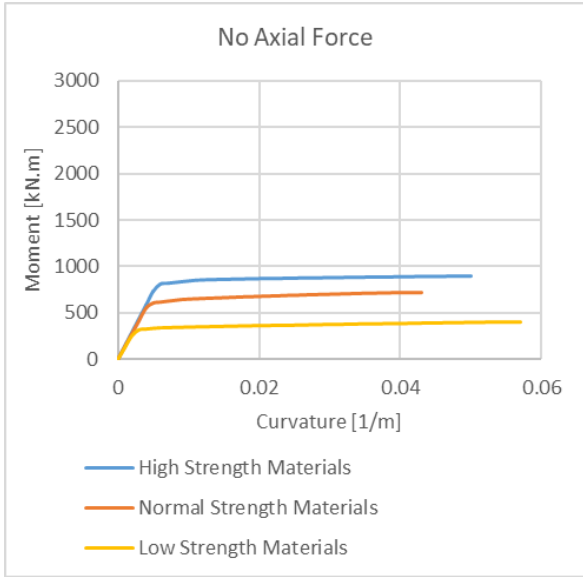


(c)

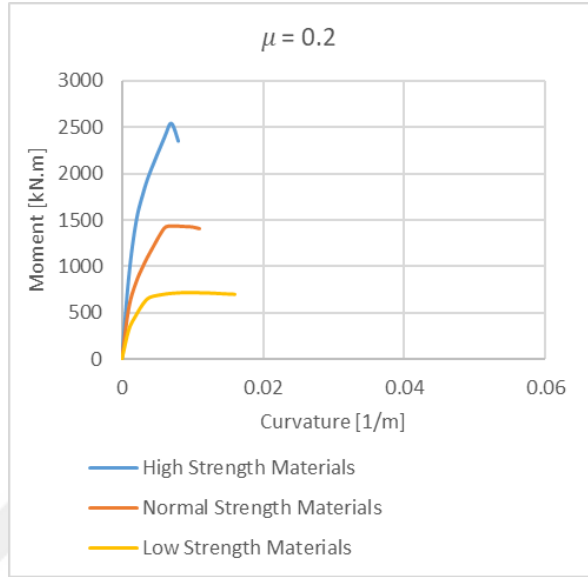


(d)

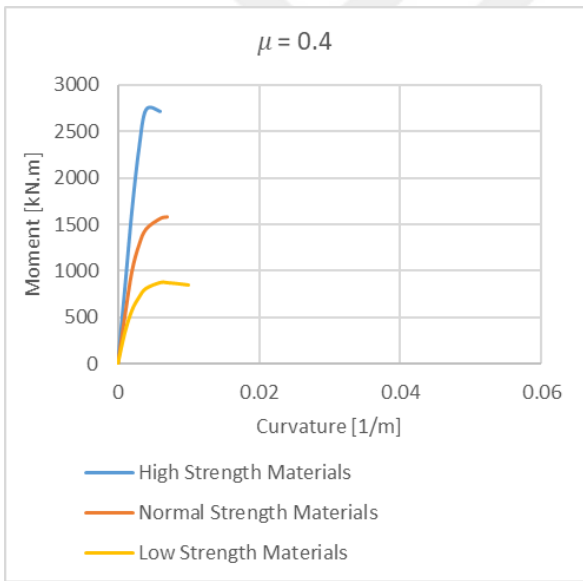
Figure 40: Moment curvature curve of section 1



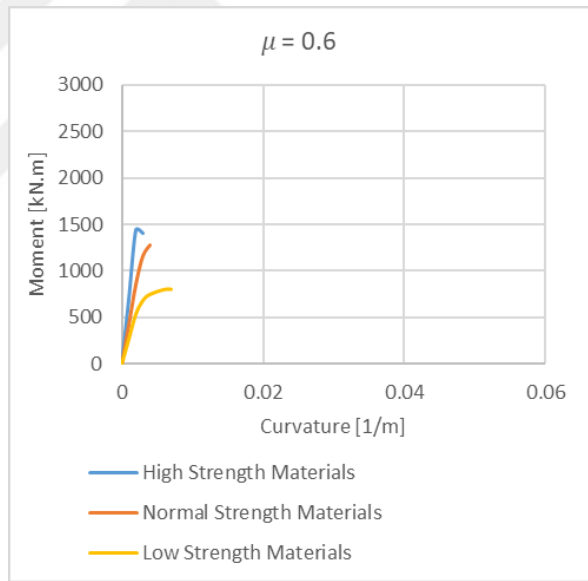
(a)



(b)

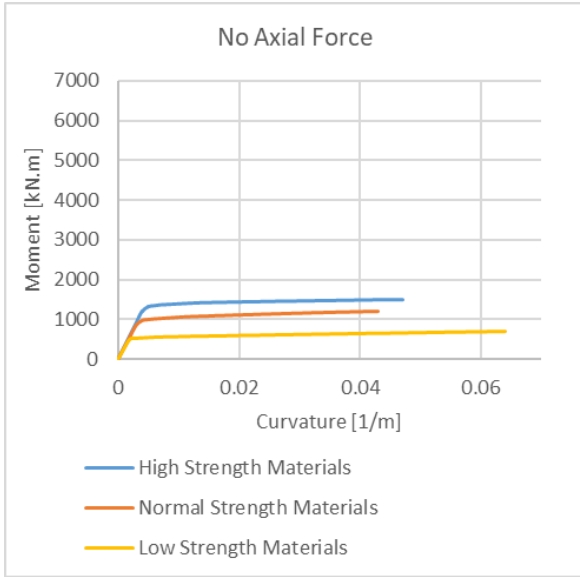


(c)

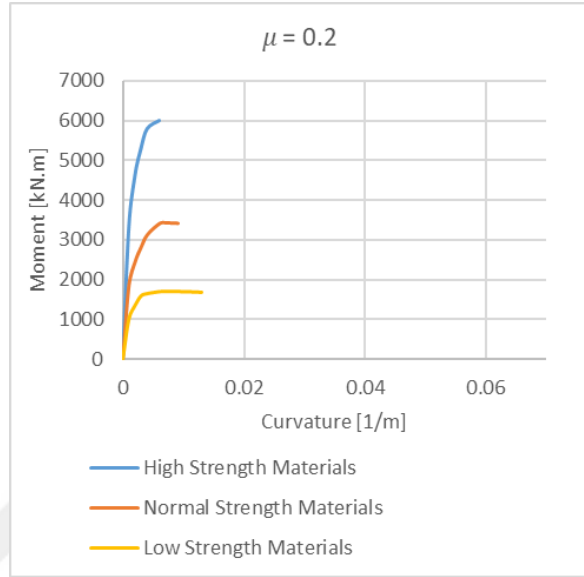


(d)

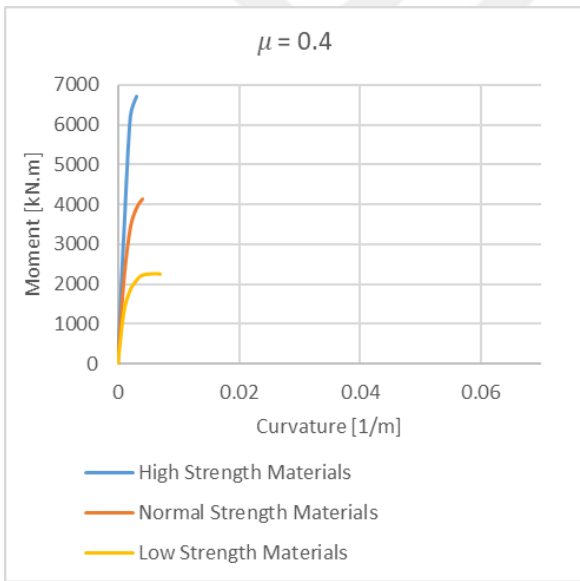
Figure 41: Moment curvature curve of section 2



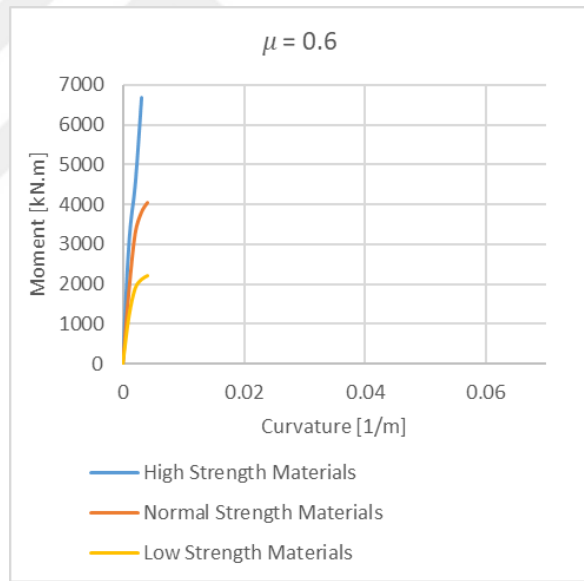
(a)



(b)

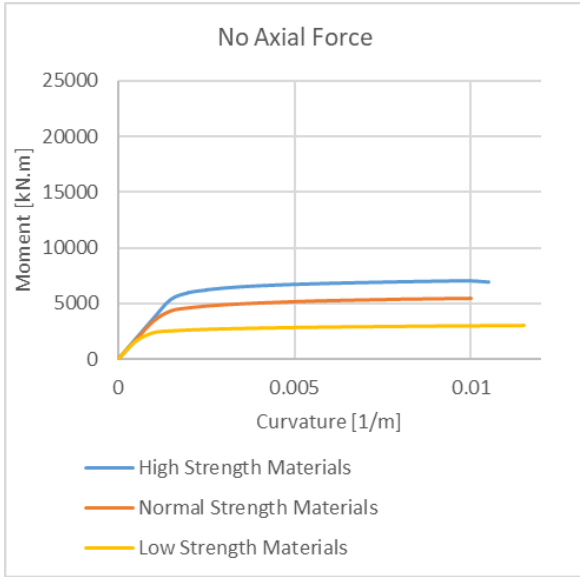


(c)

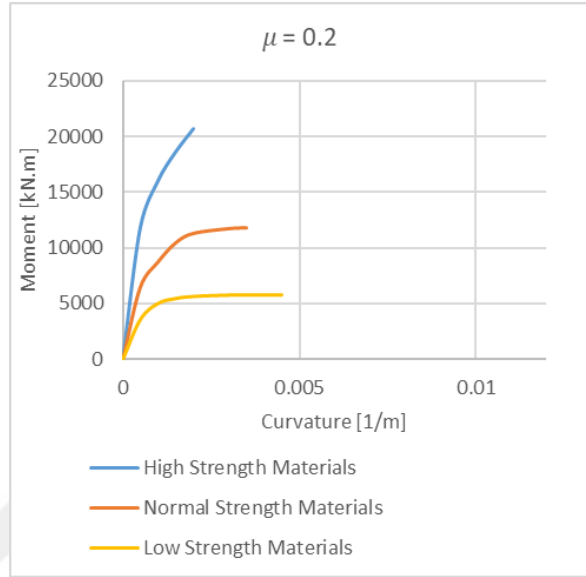


(d)

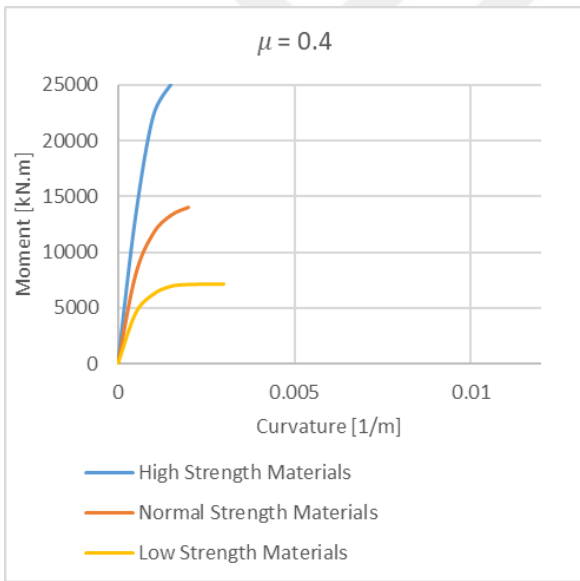
Figure 42: Moment curvature curve of section 3



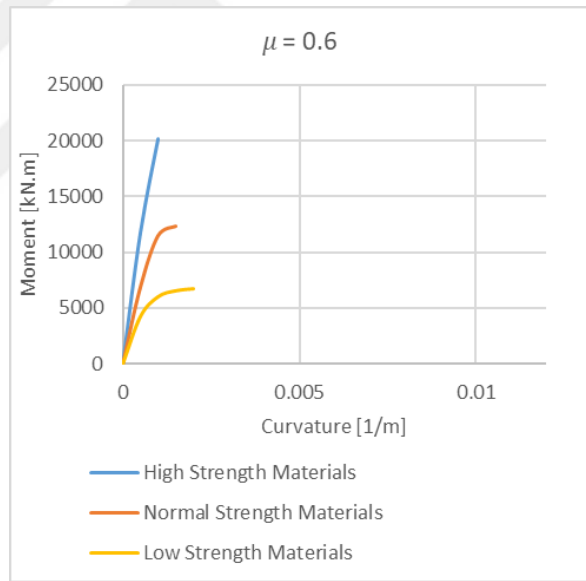
(a)



(b)

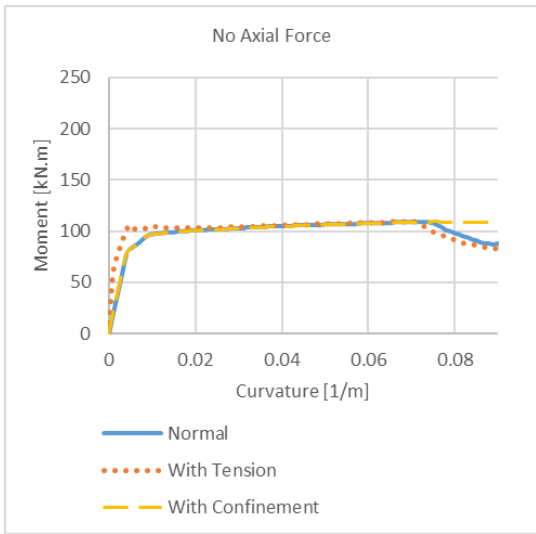


(c)

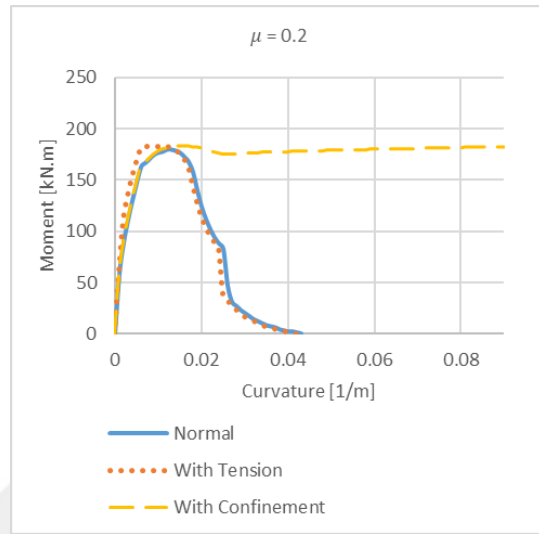


(d)

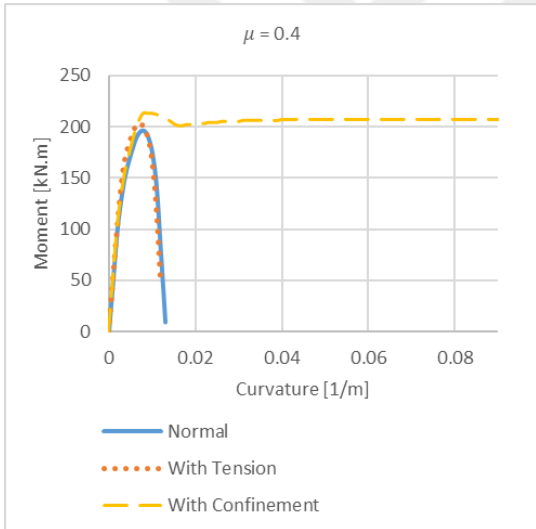
Figure 43: Moment curvature curve of wall section



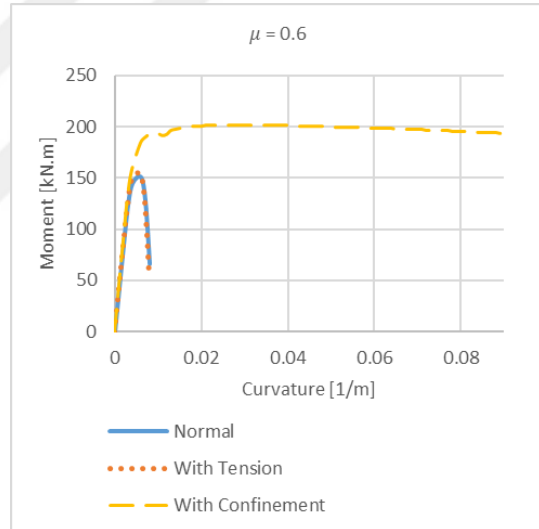
(a)



(b)

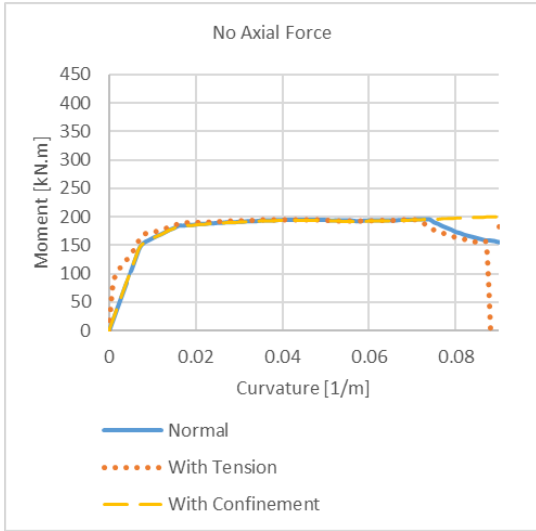


(c)

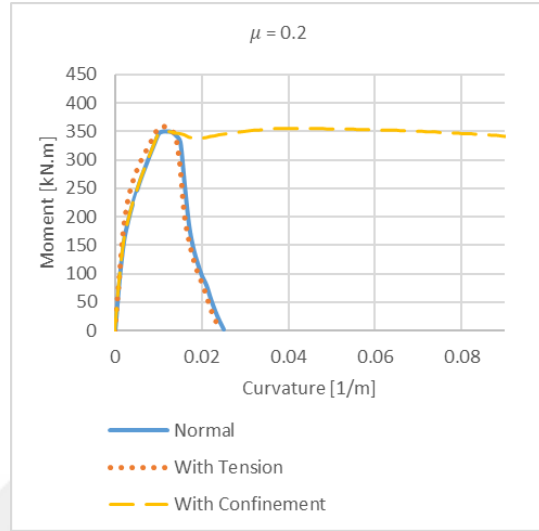


(d)

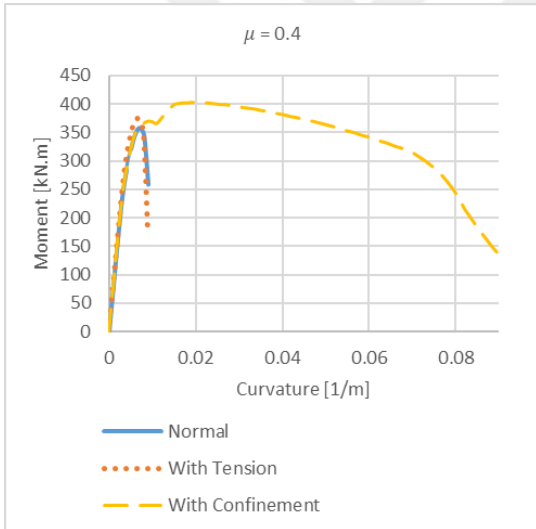
Low Strength Materials



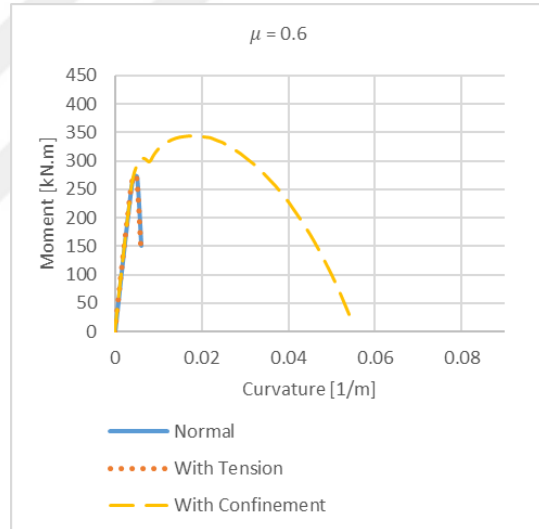
(a)



(b)

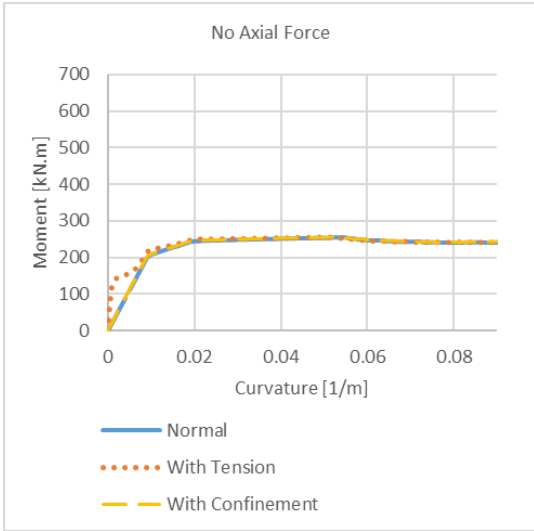


(c)

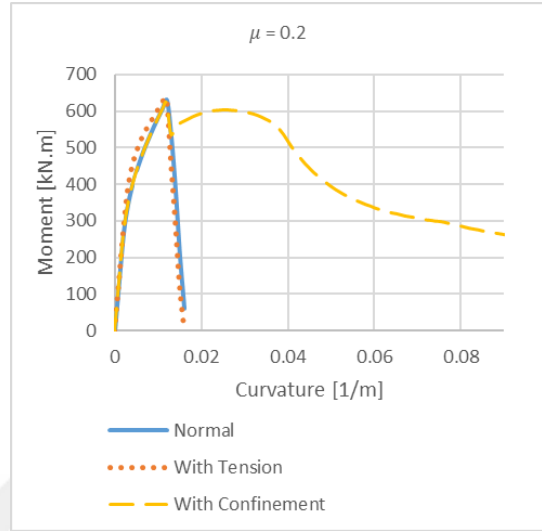


(d)

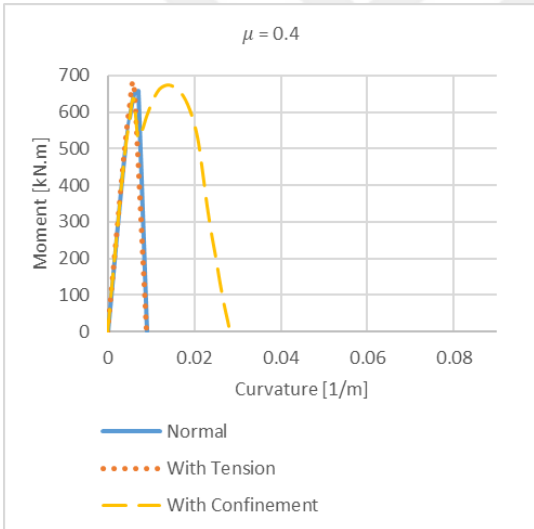
Normal Strength Materials



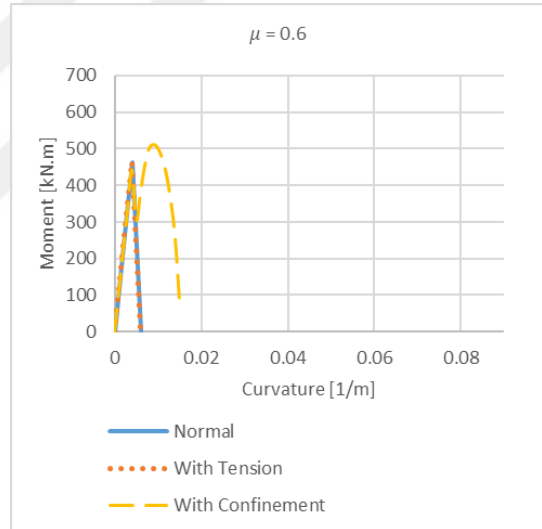
(a)



(b)



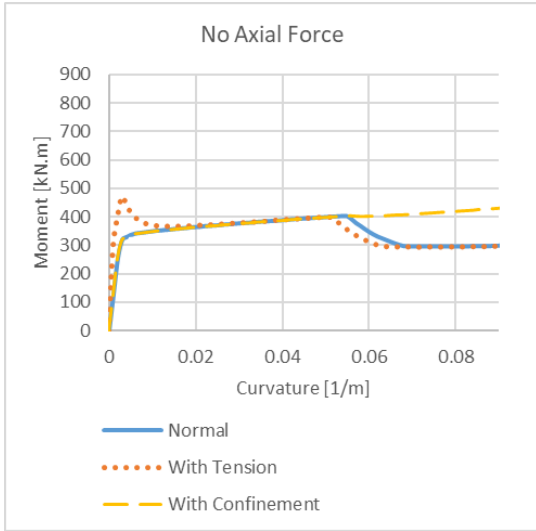
(c)



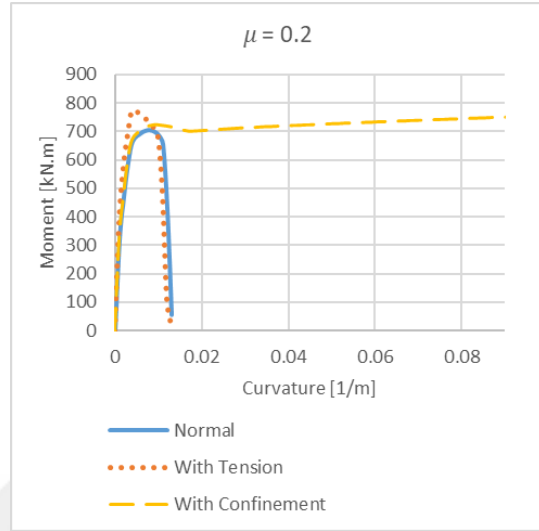
(d)

High Strength Materials

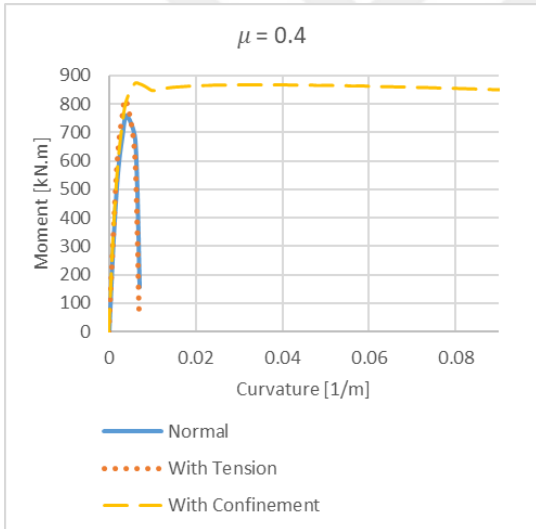
Figure 44: Moment curvature curve of section 1



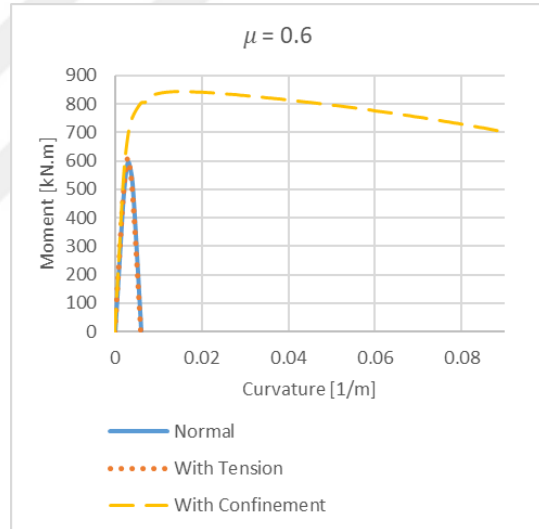
(a)



(b)

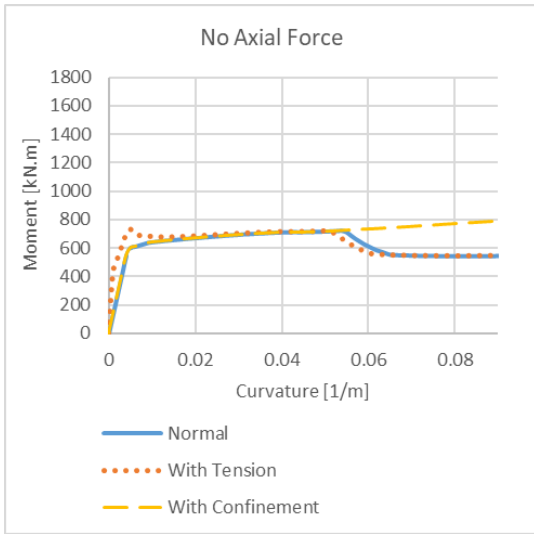


(c)

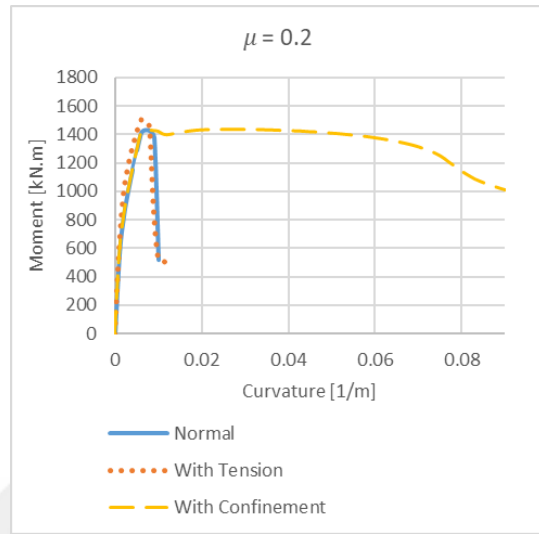


(d)

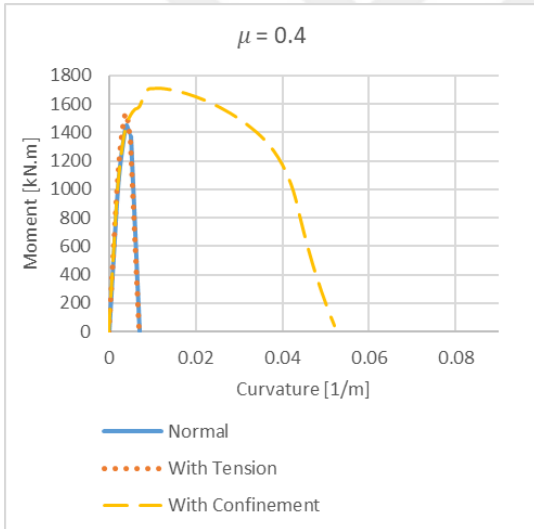
Low Strength Materials



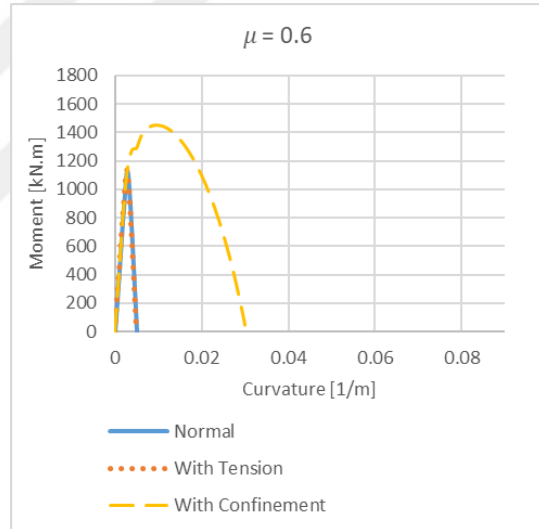
(a)



(b)

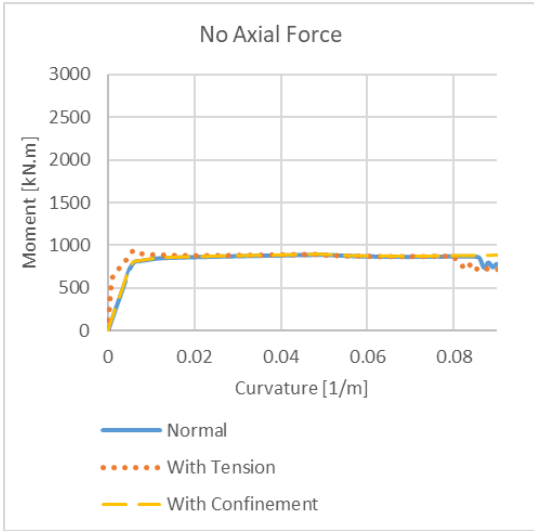


(c)

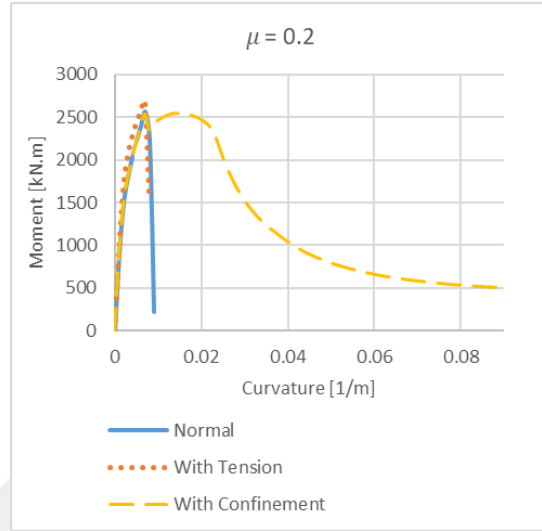


(d)

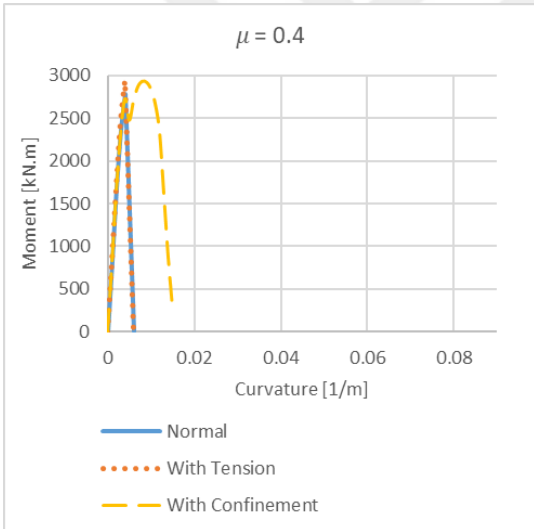
Normal Strength Materials



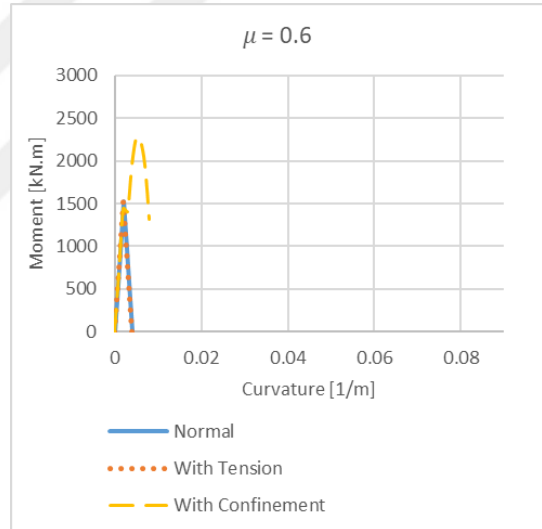
(a)



(b)



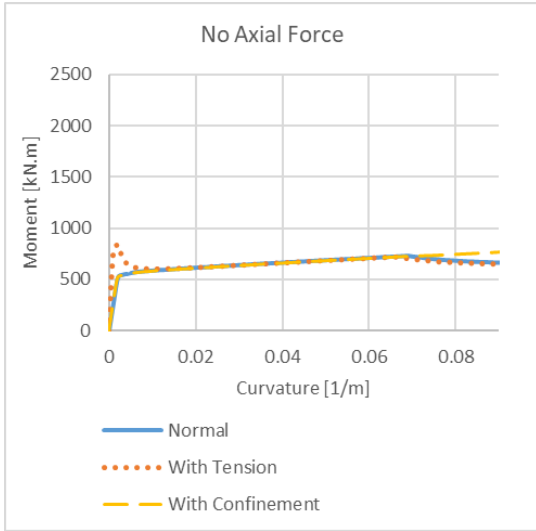
(c)



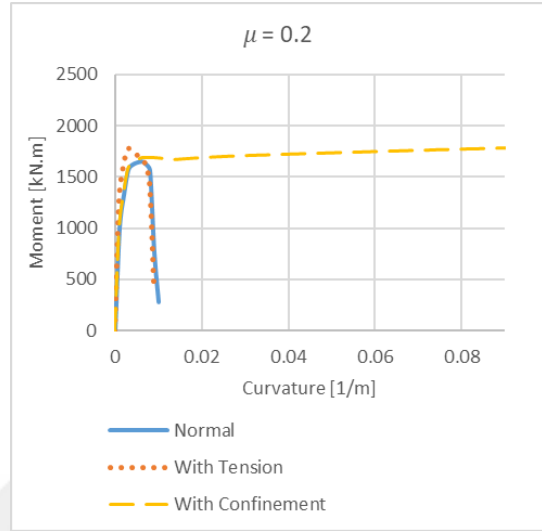
(d)

High Strength Materials

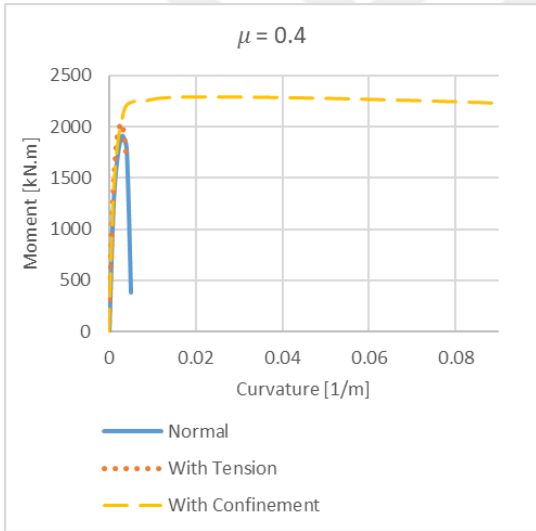
Figure 45: Moment curvature curve of section 2



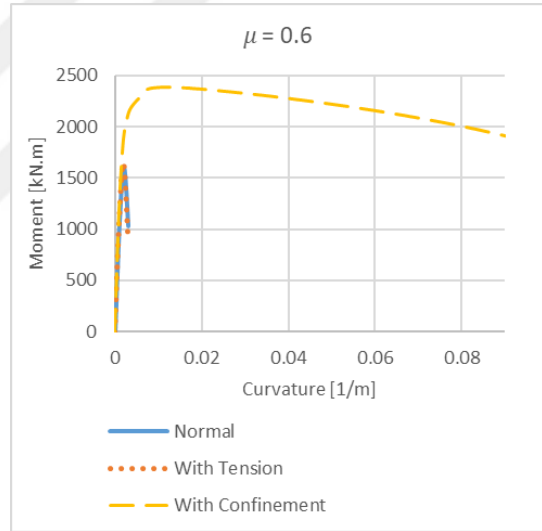
(a)



(b)

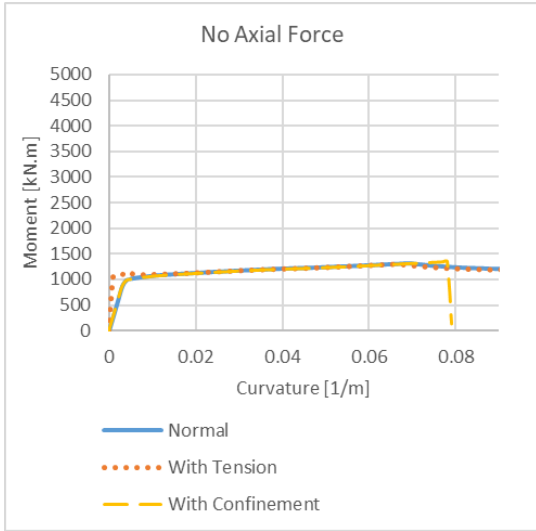


(c)

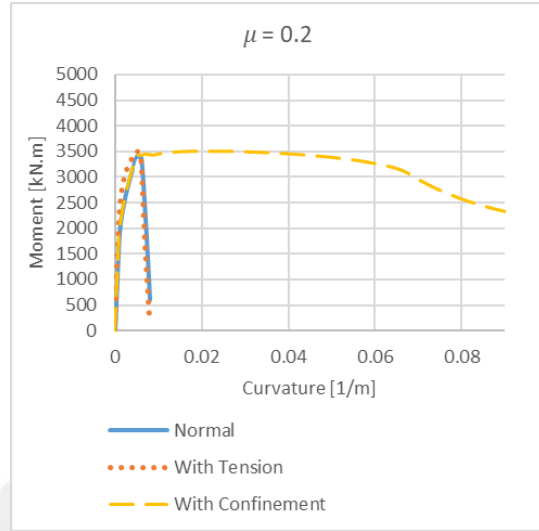


(d)

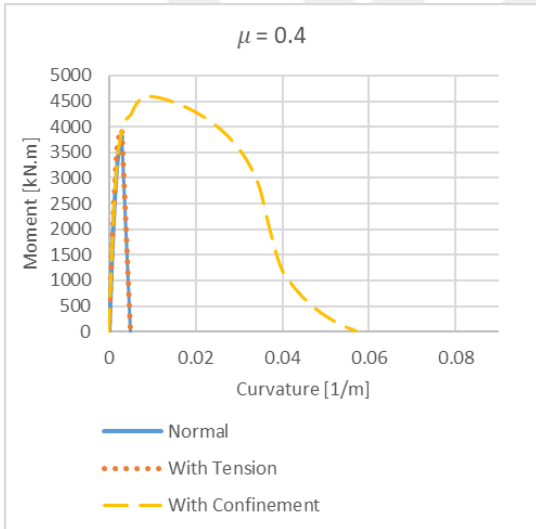
Low Strength Materials



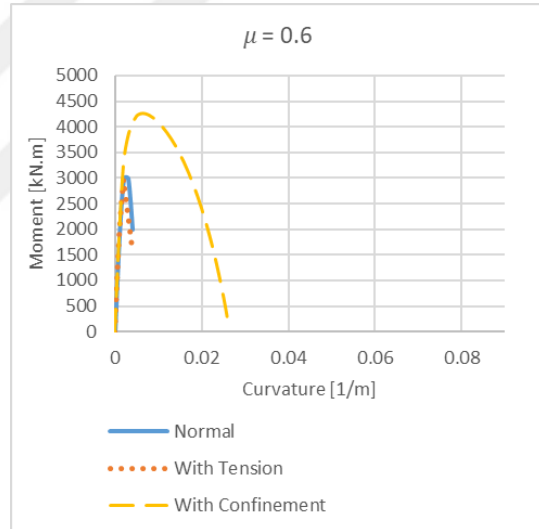
(a)



(b)

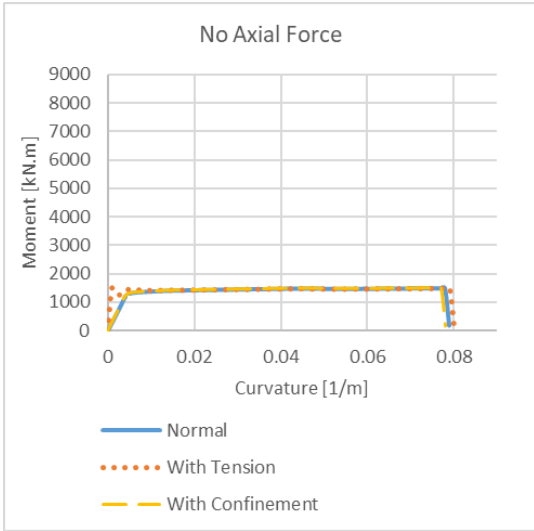


(c)

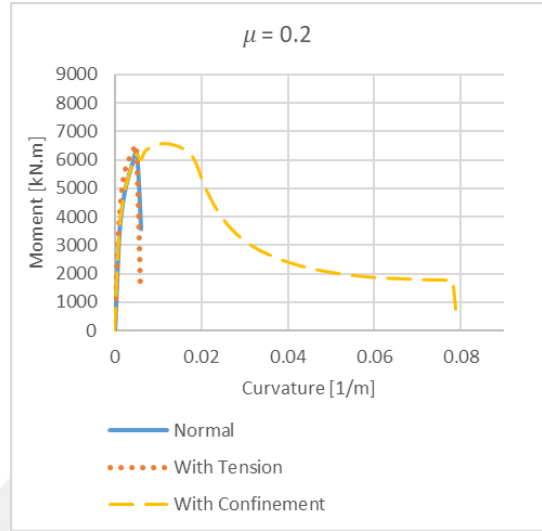


(d)

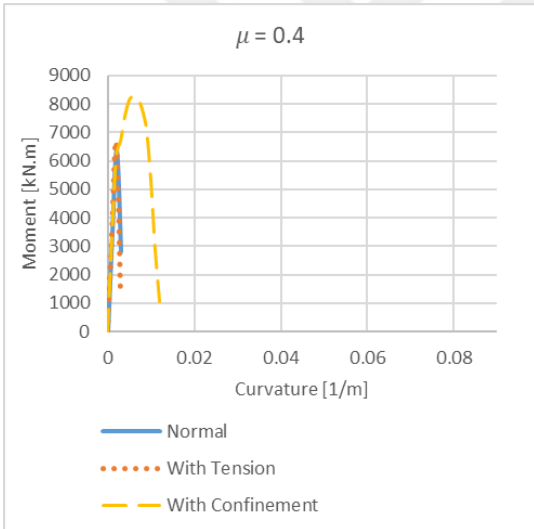
Normal Strength Materials



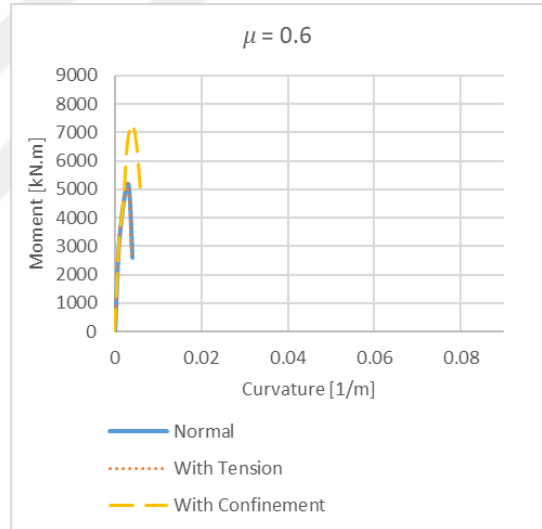
(a)



(b)



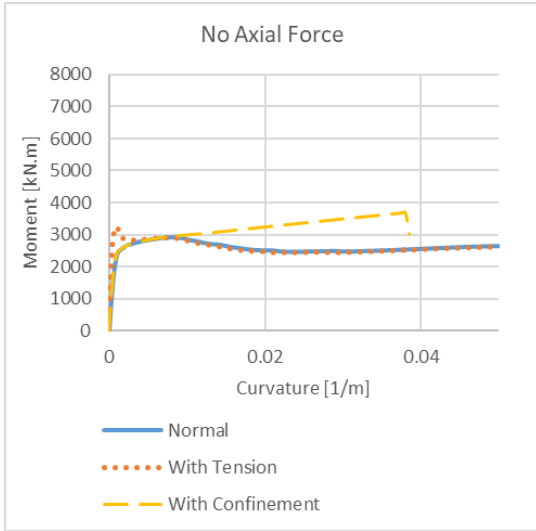
(c)



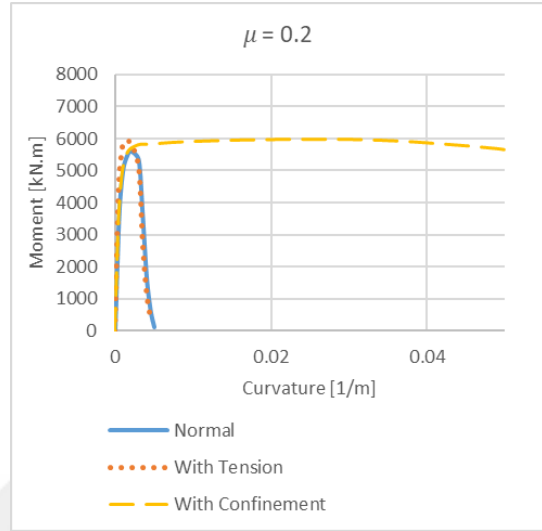
(d)

High Strength Materials

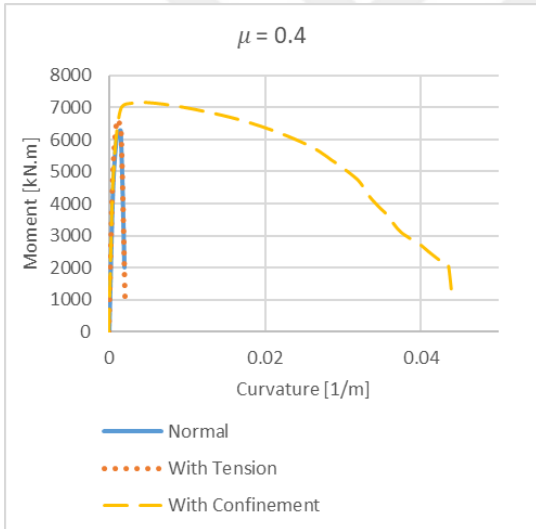
Figure 46: Moment curvature curve of section 3



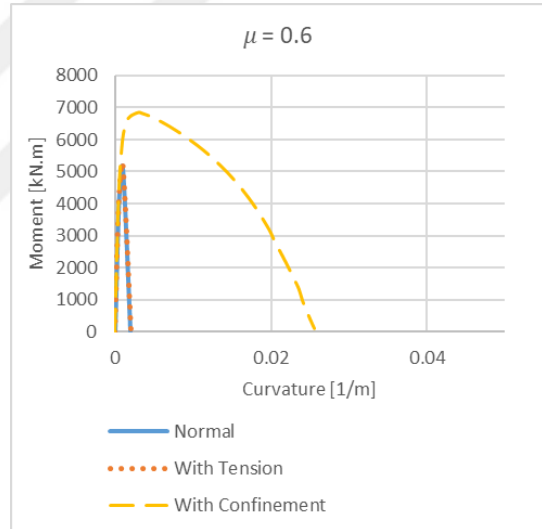
(a)



(b)

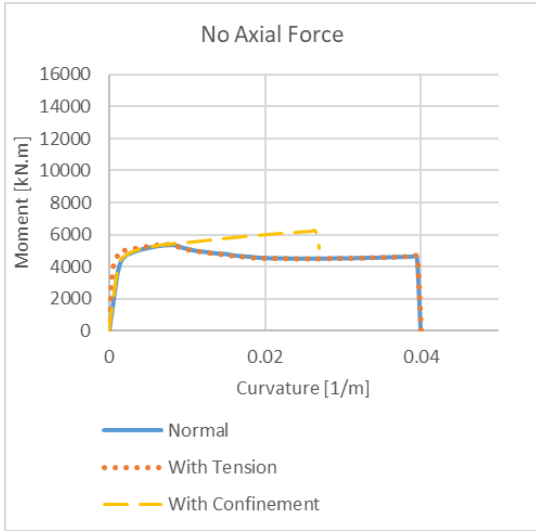


(c)

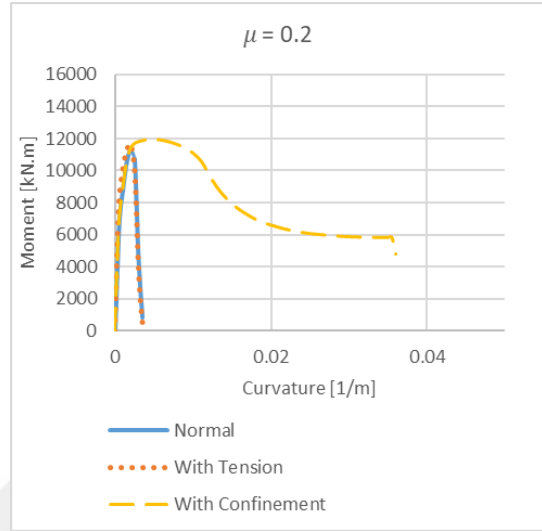


(d)

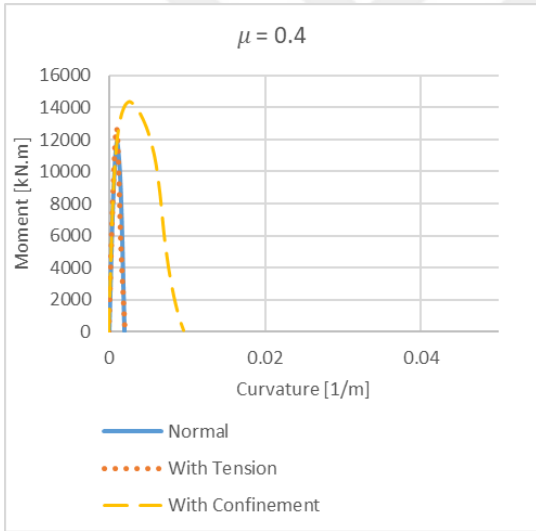
Low Strength Materials



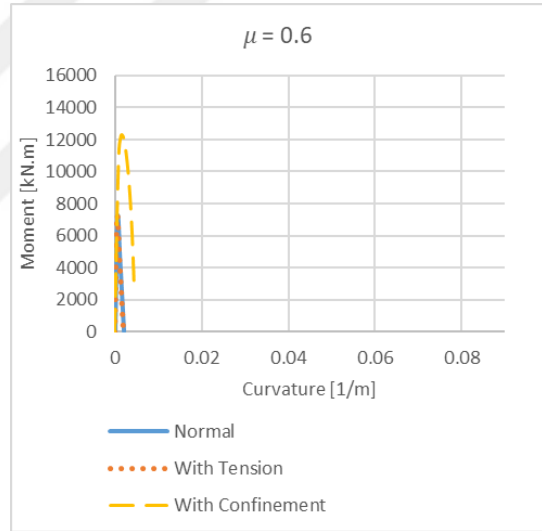
(a)



(b)

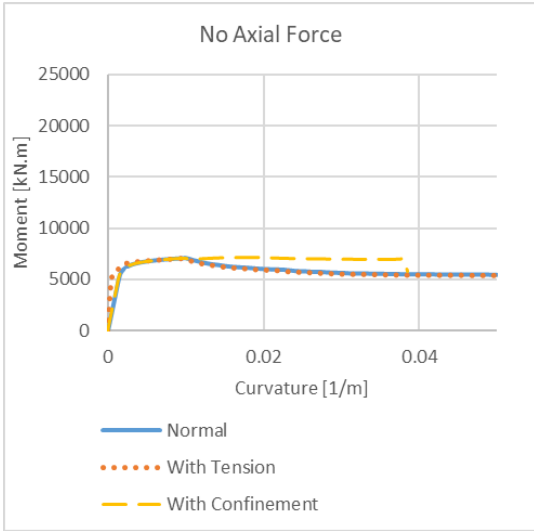


(c)

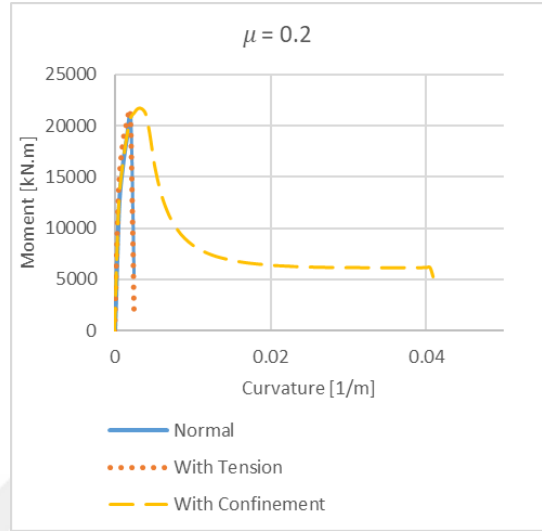


(d)

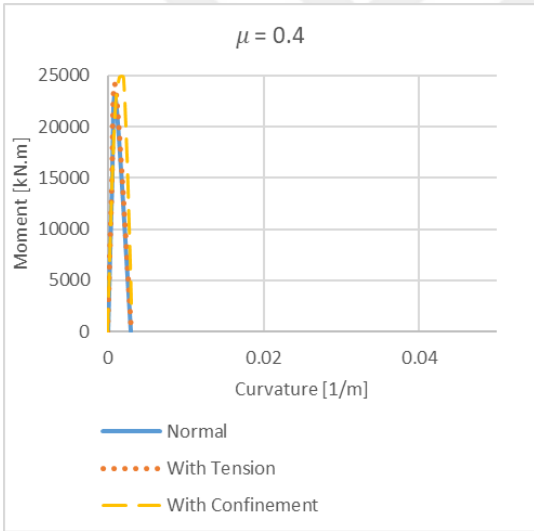
Normal Strength Materials



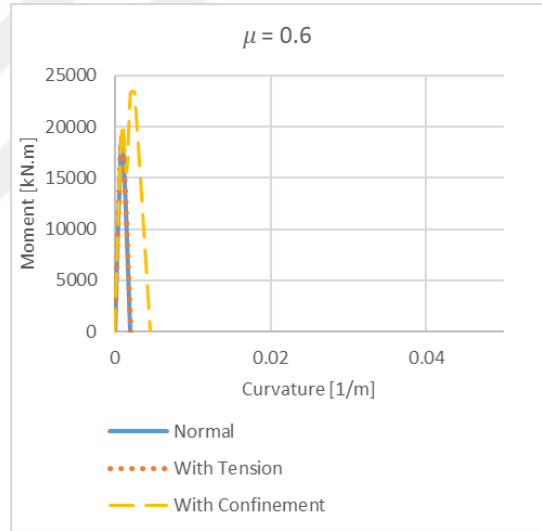
(a)



(b)



(c)



(d)

High Strength Materials

Figure 47: Moment curvature curve of the wall section

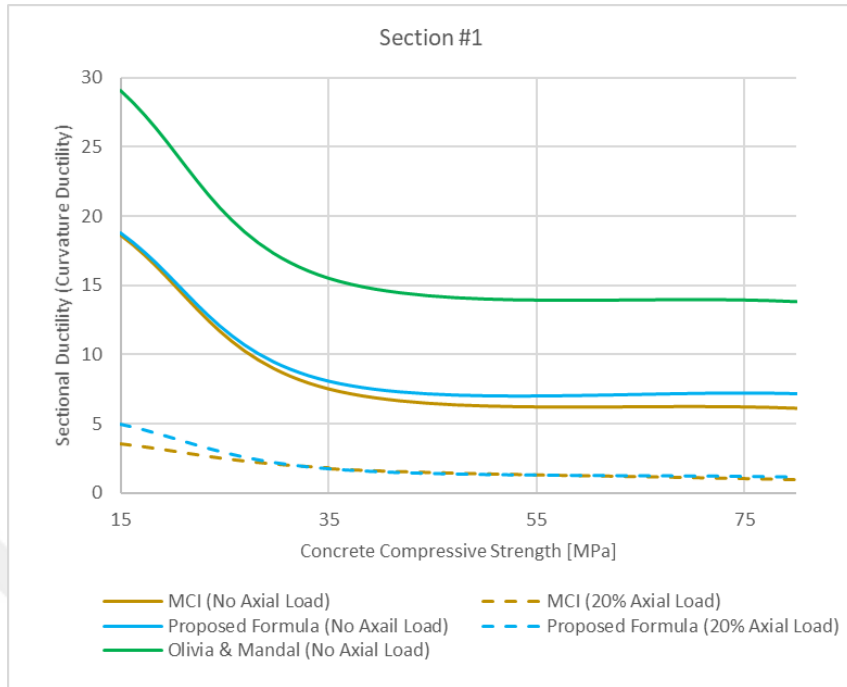


Figure 48: The Influence of Material Properties on Curvature Ductility of Section #1

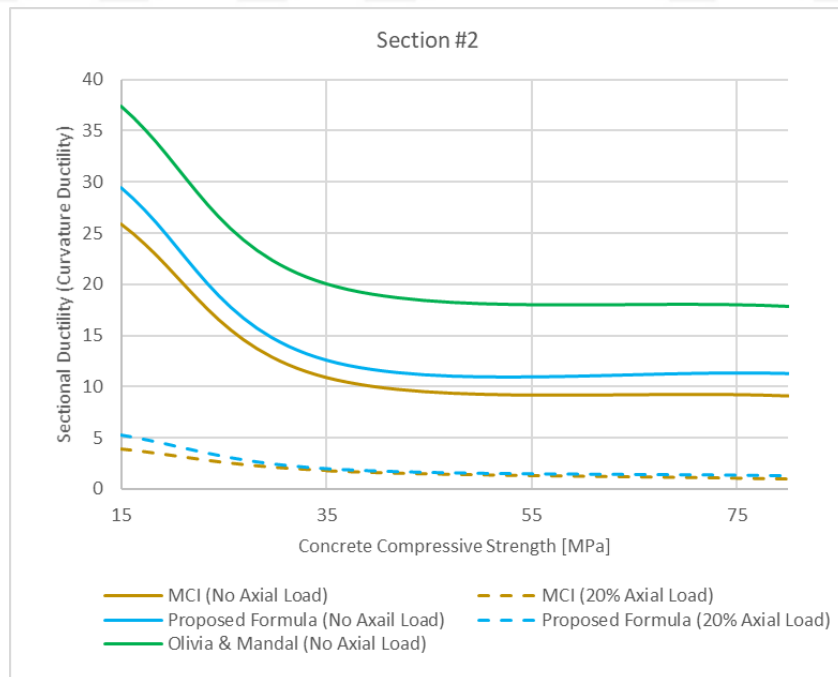


Figure 49: The Influence of Material Properties on Curvature Ductility of Section #2

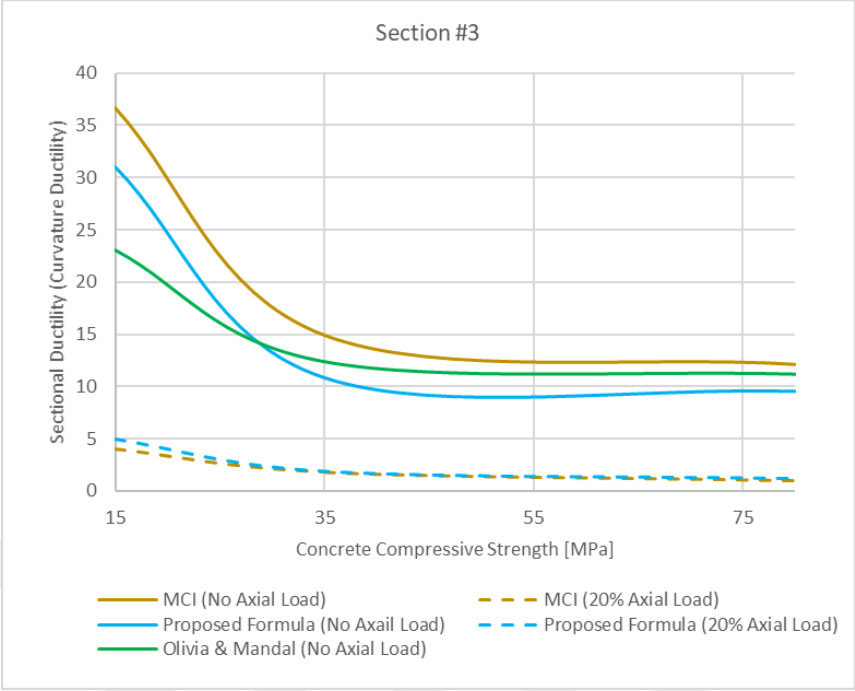


Figure 50: The Influence of Material Properties on Curvature Ductility of Section #3

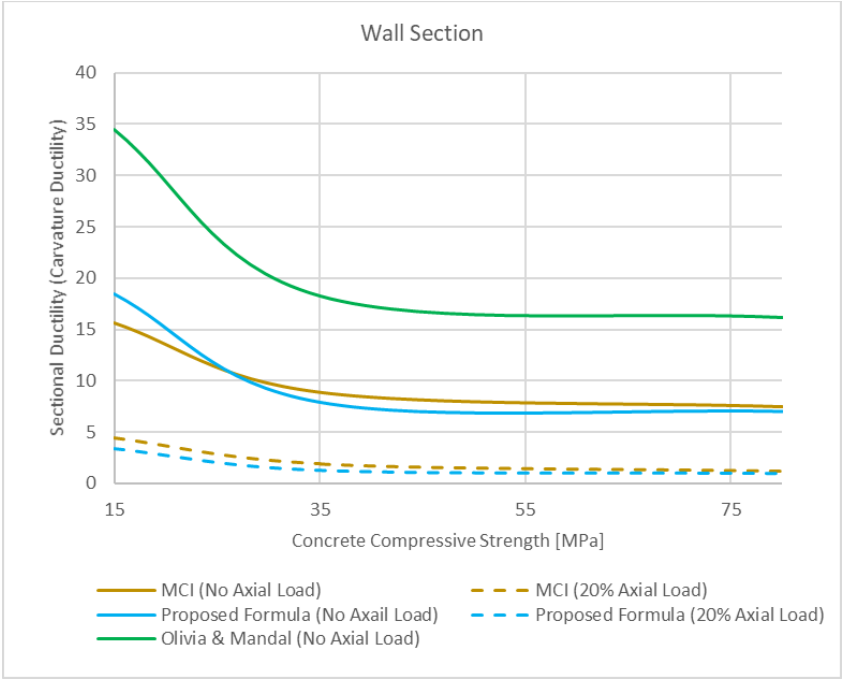


Figure 51: The Influence of Material Properties on Curvature Ductility of Wall Section

APPENDIX II: CODE WRITTEN FOR MCI SOFTWARE

```
1. Imports System.Windows.Forms.DataVisualization.Charting
2. Public Class MainForm
3.     Public section_height, section_width, concrete_cover, unconfined_layer_thickness As Double
4.     Public depth_of_first_row_top_rein, depth_of_top_rein, depth_of_first_row_middle_rein, depth_of_first_row_bottom_rein, depth_of_bottom_rein As Double
5.     Public top_rein_dim, middle_rein_dim, bottom_rein_dim, stirrups_dim As Double
6.     Public top_rein_num_per_row, middle_rein_num_per_row, bottom_rein_num_per_row As Integer
7.     Public top_rein_rows_spacing, middle_rein_rows_spacing, bottom_rein_rows_spacing, stirrups_spacing As Double
8.     Public top_rein_rows_num, middle_rein_rows_num, bottom_rein_rows_num, layers_num As Integer
9.     Public layer_thickness, layer_thickness_new As Double
10.    Public section_area, top_rein_row_area, middle_rein_row_area, bottom_rein_row_area, rein_area As Double
11.    Public E_s, E_c, f_cm, f_ccm, f_cu, f_ccu, f_y, ep_y, ep_u, f_u, f_yt, f_ctm, f_ctu, ep_cm, ep_ccm, E_des, ep_cu, ep_ccu, ep_ccu0, ep_cu0, ep_ctm, ep_ctu, ep_ctu0, C_s, curvature, X_m, X_mm, mio As Double
12.    Public curvatures_iterations As Integer
13.    Public steel_moment, steel_force, conc_moment, conc_force, applied_force, beta As Double
14.    Public max_moment_piont, max_curvature_point, max_moment_force_piont, interaction_points As Integer
15.    Public max_momnet_value, max_curvature_value, max_moment_force_value As Double
16.    Public confined, limit_check(8), failure_at_cu, failure_at_fu, failure_at_fy, interaction As Boolean
17.    Public limit_iteration(8) As Integer
18.    Public concrete_reduction_factor, steel_reduction_factor, force_reduction_factor, moment_reduction_factor, pure_force_reduction_factor As Double
19.    Public limit_value(8), moment_curvature_table(1, 1), moment_force_table(1, 1) As Double
20.    Public ConfinementFormula(2), TensionFormula(10), confinement_formula, tension_formula, sections(12) As String
21.    Dim confinement_formulae_num, tension_formulae_num As Integer
22.
23.    Sub FilFormulaeSB()
24.        confinement_formulae_num = 2
25.        ReDim ConfinementFormula(confinement_formulae_num)
26.        ConfinementFormula(0) = "Suzuki et al. (2004)"
27.        ConfinementFormula(1) = "Legeron and Paultre (2003)"
28.        ConfinementFormula(confinement_formulae_num) = "Neglect Confinment"
29.        tension_formulae_num = 10
30.        ReDim TensionFormula(tension_formulae_num)
31.        TensionFormula(0) = "ACI 318"
32.        TensionFormula(1) = "ACI 363R"
33.        TensionFormula(2) = "Gardner"
34.        TensionFormula(3) = "Nihal"
35.        TensionFormula(4) = "JCI"
36.        TensionFormula(5) = "JSCE"
37.        TensionFormula(6) = "CEB-FIB"
38.        TensionFormula(7) = "Raphael"
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39.     TensionFormula(8) = "Ahmad and Shah"
40.     TensionFormula(9) = "Oloukun et al."
41.     TensionFormula(tension_formulae_num) = "Neglect Tension"
42. End Sub
43. Function RoundUP(ByVal num As Double, ByVal digit As Integer) As Double
44.     Dim new_num As Double
45.     new_num = Math.Round(num, digit)
46.     If new_num < num Then
47.         new_num = new_num + 1 / (10 ^ digit)
48.     End If
49.     Return new_num
50. End Function
51. Sub InitialValuesSB()
52.     FilFormulaeSB()
53.     section_height = 600 '[mm]
54.     section_width = 400 '[mm]
55.     concrete_cover = 20 '[mm]
56.     E_s = 200000 '[MPa]
57.     f_cm = 25 '[MPa]
58.     f_ccm = 50 '[MPa]
59.     f_cu = 10 '[MPa]
60.     f_ccu = 20 '[MPa]
61.     ep_cm = 0.002 '[-]
62.     ep_ccm = 0.01 '[-]
63.     ep_cu = 0.0038 '[-]
64.     ep_cu0 = 1.2 * ep_cu
65.     ep_ccu = 0.02 '[-]
66.     f_y = 240 '[MPa]
67.     f_u = 300 '[MPa]
68.     f_yt = 240 '[MPa]
69.     ep_u = 0.2 '[-]
70.     top_rein_rows_spacing = 100 '[mm]
71.     bottom_rein_rows_spacing = 100 '[mm]
72.     layer_thickness = 5 '[mm]
73.     X_m = 0.1 '[rad/m]
74.     mio = 0.9 '[-]
75.     curvatures_iterations = 1000 '[-]
76.     confined = True
77.     top_rein_dim = 16 '[mm]
78.     middle_rein_dim = 10 '[mm]
79.     bottom_rein_dim = 16 '[mm]
80.     stirrups_dim = 8 '[mm]
81.     top_rein_num_per_row = 3 '[bars]
82.     middle_rein_num_per_row = 2 '[bars] constant
83.     bottom_rein_num_per_row = 4 '[bars]
84.     top_rein_rows_num = 1 '[rows]
85.     middle_rein_rows_num = 2 '[rows]
86.     bottom_rein_rows_num = 1 '[rows]
87.     concrete_reduction_factor = 1
88.     steel_reduction_factor = 1
89.     stirrups_spacing = 200 '[mm]
90.     tension_formula = TensionFormula(10)
91.     confinement_formula = ConfinementFormula(0)
92.     pure_force_reduction_factor = 1
93.     interaction_points = 20
94. End Sub
95. Sub TensileStrengthSB()
96.     Dim f_spt, k, n, ro As Double
97.     ro = rein_area / section_area * 100
98.     If tension_formula = TensionFormula(0) Then
99.         k = 0.56

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100.         n = 0.5
101.         ElseIf tension_formula = TensionFormula(1) Then
102.             k = 0.59
103.             n = 0.5
104.         ElseIf tension_formula = TensionFormula(2) Then
105.             k = 0.47
106.             n = 0.59
107.         ElseIf tension_formula = TensionFormula(3) Then
108.             k = 0.387
109.             n = 0.63
110.         ElseIf tension_formula = TensionFormula(4) Then
111.             k = 0.13
112.             n = 0.85
113.         ElseIf tension_formula = TensionFormula(5) Then
114.             k = 0.23
115.             n = 0.67
116.         ElseIf tension_formula = TensionFormula(6) Then
117.             k = 0.3
118.             n = 0.67
119.         ElseIf tension_formula = TensionFormula(7) Then
120.             k = 0.313
121.             n = 0.667
122.         ElseIf tension_formula = TensionFormula(8) Then
123.             k = 0.462
124.             n = 0.55
125.         ElseIf tension_formula = TensionFormula(9) Then
126.             k = 0.294
127.             n = 0.69
128.         ElseIf tension_formula = TensionFormula(10) Then
129.             k = 0
130.             n = 1
131.         End If
132.         f_spt = k * f_cm ^ n
133.         f_ctm = f_spt * 4 / 3
134.         f_ctu = 0
135.         ep_ctm = f_ctm / E_c
136.         If ro < 2 Then
137.             beta = 32.8 - 27.6 * ro + 7.12 * ro ^ 2
138.         Else
139.             beta = 5
140.         End If
141.         ep_ctu = beta * ep_ctm
142.     End Sub
143.     Sub ResetMomentCurvatureSB()
144.         max_curvature_point = curvatures_iterations
145.         TrackBar1.Maximum = max_curvature_point
146.     End Sub
147.
148.     Sub ConfiStrenghtSB()
149.         Dim b_c, d_c, k_e, wi_2, ro_cc, ro_wx, ro_wy, f_scx, f_scy, ro_ex, ro_ey
150.         , ro_e, kapa_x, kapa_y As Double
151.         b_c = section_width - concrete_cover * 2 - stirrups_dim
152.         d_c = section_height - concrete_cover * 2 - stirrups_dim
153.         ro_cc = rein_area / b_c / d_c
154.         ro_wx = (Math.PI * stirrups_dim ^ 2 / 4) * 2 / (stirrups_spacing * b_c)
155.         ro_wy = (Math.PI * stirrups_dim ^ 2 / 4) * 2 / (stirrups_spacing * d_c)
156.         wi_2 = (top_rein_num_per_row - 1) * ((b_c - stirrups_dim - top_rein_dim)
157.         / (top_rein_num_per_row - 1)) ^ 2

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156.         wi_2 = wi_2 + (bottom_rein_num_per_row - 1) * ((b_c - stirrups_dim - bot
tom_rein_dim) / (bottom_rein_num_per_row - 1)) ^ 2
157.         wi_2 = wi_2 + 2 * (top_rein_rows_num - 1) * top_rein_rows_spacing ^ 2
158.         wi_2 = wi_2 + 2 * (bottom_rein_rows_num - 1) * bottom_rein_rows_spacing
^ 2
159.         wi_2 = wi_2 + 2 * (middle_rein_rows_num + 1) * middle_rein_rows_spacing
^ 2
160.         k_e = ((1 - wi_2 / (6 * b_c * d_c)) * (1 - stirrups_spacing / 2 / b_c) *
(1 - stirrups_spacing / 2 / d_c)) / (1 - ro_cc)
161.         If confinement_formula = ConfinementFormula(0) Then
162.             f_scx = MinFN(E_s * (0.45 * ep_cm + 0.73 * (k_e * ro_wx / f_cm) ^ 0.
7), f_yt)
163.             f_scy = MinFN(E_s * (0.45 * ep_cm + 0.73 * (k_e * ro_wy / f_cm) ^ 0.
7), f_yt)
164.             ro_ex = k_e * ro_wx * f_scx
165.             ro_ey = k_e * ro_wy * f_scy
166.             ro_e = (ro_ex * b_c + ro_ey * d_c) / (b_c + d_c)
167.             f_ccm = (1 + 4.1 * (ro_e / f_cm) ^ 0.7) * f_cm
168.             ep_ccm = ep_cm + 0.015 * (ro_e / f_cm) ^ 0.56
169.             f_ccu = 0.2 * f_ccm
170.         ElseIf confinement_formula = ConfinementFormula(1) Then
171.             kapa_x = f_cm / ((k_e * ro_wx) * E_s * ep_cm)
172.             If kapa_x > 10 Then
173.                 f_scx = MinFN(MaxFN(0.25 * f_cm / ((k_e * ro_wx) * (kapa_x - 10)
), 0.43 * ep_cm * E_s), f_yt)
174.             Else
175.                 f_scx = f_yt
176.             End If
177.             kapa_y = f_cm / ((k_e * ro_wy) * E_s * ep_cm)
178.             If kapa_y > 10 Then
179.                 f_scy = MinFN(MaxFN(0.25 * f_cm / ((k_e * ro_wy) * (kapa_y - 10)
), 0.43 * ep_cm * E_s), f_yt)
180.             Else
181.                 f_scy = f_yt
182.             End If
183.             ro_ex = k_e * ro_wx * f_scx
184.             ro_ey = k_e * ro_wy * f_scy
185.             ro_e = (ro_ex * b_c + ro_ey * d_c) / (b_c + d_c)
186.             f_ccm = f_cm * (-
1.254 + 2.254 * (1 + 7.94 * ro_e / f_cm) ^ 0.5 - 2 * ro_e / f_cm)
187.             ep_ccm = ep_cm * (1 + 5 * (f_ccm / f_cm - 1))
188.             f_ccu = 0.2 * f_ccm
189.         ElseIf confinement_formula = ConfinementFormula(2) Then
190.             f_ccm = f_cm
191.             ep_ccm = ep_cm
192.             f_ccu = 0.2 * f_ccm
193.         End If
194.         E_des = 0.026 * f_cm ^ 3 / ro_e ^ 0.4
195.         ep_ccu = ep_ccm + 0.8 * f_ccm / E_des
196.         ep_ccu0 = 1.2 * ep_ccu
197.         limit_value(1) = ep_cm
198.         limit_value(2) = ep_cu
199.         limit_value(3) = ep_ccm
200.         limit_value(4) = ep_ccu
201.         limit_value(5) = ep_ctm
202.         limit_value(6) = ep_ctu
203.         limit_value(7) = ep_y
204.         limit_value(8) = ep_u
205.     End Sub
206.     Sub ParametersCalcSB()
207.         Dim k_3 As Double

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208.         ep_y = f_y / E_s
209.         E_c = 4730 * (f_cm) ^ 0.5
210.         k_3 = MinFN(40 / f_cm, 1)
211.         ep_cm = 0.0028 - 0.0008 * k_3
212.         ep_cu = MaxFN(0.0078 / f_cm ^ 0.25, ep_cm)
213.         X_mm = X_m / 1000 '[rad/mm]
214.         depth_of_first_row_top_rein = concrete_cover + stirrups_dim + top_rein_d
           im / 2
215.         depth_of_first_row_bottom_rein = section_height - concrete_cover - stirr
           ups_dim - bottom_rein_dim / 2 - bottom_rein_rows_spacing * (bottom_rein_rows_num - 1)
216.         middle_rein_rows_spacing = (depth_of_first_row_bottom_rein - depth_of_fi
           rst_row_top_rein - top_rein_rows_spacing * (top_rein_rows_num - 1)) / (middle_rein_rows
           _num + 1)
217.         depth_of_first_row_middle_rein = depth_of_first_row_top_rein + top_rein_
           rows_spacing * (top_rein_rows_num - 1) + middle_rein_rows_spacing
218.         depth_of_top_rein = depth_of_first_row_top_rein + top_rein_rows_spacing
           * (top_rein_rows_num - 1) / 2
219.         depth_of_bottom_rein = depth_of_first_row_bottom_rein + bottom_rein_rows
           _spacing * (bottom_rein_rows_num - 1) / 2
220.         unconfined_layer_thickness = depth_of_first_row_top_rein
221.         layers_num = Math.Round(section_height / layer_thickness, 0)
222.         layer_thickness_new = section_height / layers_num
223.         top_rein_row_area = Math.PI * top_rein_dim ^ 2 / 4 * top_rein_num_per_ro
           w
224.         middle_rein_row_area = Math.PI * middle_rein_dim ^ 2 / 4 * middle_rein_n
           um_per_row
225.         bottom_rein_row_area = Math.PI * bottom_rein_dim ^ 2 / 4 * bottom_rein_n
           um_per_row
226.         rein_area = top_rein_row_area * top_rein_rows_num + middle_rein_row_area
           * middle_rein_rows_num + bottom_rein_row_area * bottom_rein_rows_num
227.         section_area = section_height * section_width
228.         applied_force = SectionAxialRsistanceFN(False) * mio
229.         ConfiStrenghtSB()
230.         TensileStrengthSB()
231.         End Sub
232.
233.         Function ConStressFN(ByVal ep_layer As Double, ByVal confined As Boolean) As
           Double
234.             Dim stress, abs_ep As Double
235.             abs_ep = Math.Abs(ep_layer)
236.             If ep_layer <= 0 Then
237.                 If confined Then
238.                     If abs_ep <= ep_ccm Then 'if concrete layer is confined
239.                         stress = -
240.                             f_ccm * (1 - (1 - abs_ep / ep_ccm) ^ (E_c * ep_ccm / f_ccm))
241.                     ElseIf abs_ep <= ep_ccu Then
242.                         stress = -f_ccm + E_des * (abs_ep - ep_ccm)
243.                     Else
244.                         stress = -f_ccu
245.                     End If
246.                 Else
247.                     If abs_ep <= ep_cm Then 'if concrete layer is confined
248.                         stress = -
249.                             f_cm * (1 - (1 - abs_ep / ep_cm) ^ (E_c * ep_cm / f_cm))
250.                     ElseIf abs_ep <= ep_cu Then
251.                         stress = -
252.                             (f_cm + (f_cu - f_cm) / (ep_cu - ep_cm)) * (abs_ep - ep_cm)
253.                     Else
254.                         stress = 0
255.                     End If
256.                 End If

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254.         Else
255.             If abs_ep <= ep_ctm Then 'if concrete layer is under tension
256.                 stress = abs_ep * E_c
257.             ElseIf abs_ep <= ep_ctu Then
258.                 stress = 0.625 * f_ctm * (1 - (abs_ep / ep_ctm) / beta + (1 + 0.
6 * beta) / (beta * (abs_ep / ep_ctm)))
259.             Else
260.                 stress = 0
261.             End If
262.         End If
263.         Return stress * concrete_reduction_factor
264.     End Function
265.     Function SteelStressFN(ByVal ep_depth As Double)
266.         Dim stress, abs_ep As Double
267.         abs_ep = Math.Abs(ep_depth)
268.         If abs_ep < ep_y Then
269.             stress = abs_ep * E_s
270.         ElseIf abs_ep <= ep_u Then
271.             stress = (f_u - f_y) / (ep_u - ep_y) * (abs_ep - ep_y) + f_y
272.         Else
273.             stress = 0
274.         End If
275.         stress = stress * Math.Sign(ep_depth)
276.         Return stress * steel_reduction_factor
277.     End Function
278.     Sub SteelMomentForceSB(ByVal C_s As Double, ByVal X_mm As Double, check As B
oolean)
279.         Dim arm, centroid, ep_steel As Double
280.         steel_moment = applied_force * section_height / 2
281.         steel_force = applied_force
282.         For i = 0 To top_rein_rows_num - 1
283.             arm = -
(C_s - depth_of_first_row_top_rein - top_rein_rows_spacing * i)
284.             ep_steel = X_mm * arm
285.             centroid = depth_of_first_row_top_rein + top_rein_rows_spacing * i
286.             steel_moment = steel_moment + SteelStressFN(ep_steel) * top_rein_row
_area * centroid
287.             steel_force = steel_force + SteelStressFN(ep_steel) * top_rein_row_a
rea
288.             If check Then
289.                 For j = 7 To 8
290.                     If Math.Abs(ep_steel) > limit_value(j) And limit_check(j) =
False Then
291.                         limit_check(j) = True
292.                     End If
293.                 Next
294.             End If
295.         Next
296.         For i = 0 To middle_rein_rows_num - 1
297.             arm = -
(C_s - depth_of_first_row_middle_rein - middle_rein_rows_spacing * i)
298.             centroid = depth_of_first_row_middle_rein + middle_rein_rows_spacing
* i
299.             ep_steel = X_mm * arm
300.             steel_moment = steel_moment + SteelStressFN(ep_steel) * middle_rein_
row_area * centroid
301.             steel_force = steel_force + SteelStressFN(ep_steel) * middle_rein_ro
w_area
302.         Next
303.         For i = 0 To top_rein_rows_num - 1

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```

304.         arm = -
(C_s - depth_of_first_row_bottom_rein - bottom_rein_rows_spacing * i)
305.         centroid = depth_of_first_row_bottom_rein + bottom_rein_rows_spacing
* i
306.         ep_steel = X_mm * arm
307.         steel_moment = steel_moment + SteelStressFN(ep_steel) * bottom_rein_
row_area * centroid
308.         steel_force = steel_force + SteelStressFN(ep_steel) * bottom_rein_ro
w_area
309.         If check Then
310.             For j = 7 To 8
311.                 If Math.Abs(ep_steel) > limit_value(j) And limit_check(j) =
False Then
312.                     limit_check(j) = True
313.                 End If
314.             Next
315.         End If
316.     Next
317. End Sub
318. Sub ConcMomentForceSB(ByVal C_s As Double, ByVal X_mm As Double, check As Bo
olean)
319.     Dim arm, centroid, ep_conc As Double
320.     conc_moment = 0
321.     conc_force = 0
322.     For i = 0 To layers_num - 1
323.         arm = -(C_s - layer_thickness_new / 2 - layer_thickness_new * i)
324.         centroid = layer_thickness_new / 2 + layer_thickness_new * i
325.         ep_conc = X_mm * arm
326.         If layer_thickness_new / 2 + layer_thickness_new * i < unconfined_la
yer_thickness Or layer_thickness_new / 2 + layer_thickness_new * i > section_height - u
nconfined_layer_thickness Then
327.             conc_moment = conc_moment + ConStressFN(ep_conc, False) * sectio
n_width * layer_thickness_new * centroid
328.             conc_force = conc_force + ConStressFN(ep_conc, False) * section_
width * layer_thickness_new
329.         Else
330.             conc_moment = conc_moment + ConStressFN(ep_conc, confined) * secti
on_width * layer_thickness_new * centroid
331.             conc_force = conc_force + ConStressFN(ep_conc, confined) * secti
on_width * layer_thickness_new
332.         End If
333.         If check Then
334.             If ep_conc < 0 Then
335.                 For j = 1 To 4
336.                     If Math.Abs(ep_conc) > limit_value(j) And limit_check(j)
= False Then
337.                         limit_check(j) = True
338.                     End If
339.                 Next
340.             Else
341.                 For j = 5 To 6
342.                     If Math.Abs(ep_conc) > limit_value(j) And limit_check(j)
= False Then
343.                         limit_check(j) = True
344.                     End If
345.                 Next
346.             End If
347.         End If
348.     Next
349. End Sub
350. Function FindMomentFN(ByVal X_mm As Double) As Double

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```

351.         TabControl1.SelectedTab = tabPage2
352.         Dim momnet, force, force_up, force_down, depth_up, depth_down As Double

353.         depth_up = section_height * 0.4
354.         depth_down = section_height * 0.6
355.         C_s = depth_up
356.         SteelMomentForceSB(C_s, X_mm, False)
357.         ConcMomentForceSB(C_s, X_mm, False)
358.         force_up = -steel_force - conc_force
359.         C_s = depth_down
360.         SteelMomentForceSB(C_s, X_mm, False)
361.         ConcMomentForceSB(C_s, X_mm, False)
362.         force_down = -steel_force - conc_force
363.         Dim max_i As Integer = 1000
364.         For i = 1 To max_i
365.             C_s = (-
force_up) * (depth_down - depth_up) / (force_down - force_up) + depth_up
366.             If Math.Abs(C_s) > section_height * 10 ^ 6 Then
367.                 C_s = section_height * 10 ^ 3
368.             ElseIf C_s < 0 Then
369.                 C_s = 0.1
370.             End If
371.             SteelMomentForceSB(C_s, X_mm, False)
372.             ConcMomentForceSB(C_s, X_mm, False)
373.             momnet = steel_moment + conc_moment
374.             force = steel_force + conc_force
375.             If Math.Round(force, 3) = 0 Then
376.                 i = max_i + 1
377.             Else
378.                 If force < 0 Then
379.                     force_up = -force
380.                     depth_up = C_s
381.                 ElseIf force > 0 Then
382.                     force_down = -force
383.                     depth_down = C_s
384.                 End If
385.             End If
386.         Next
387.         SteelMomentForceSB(C_s, X_mm, True)
388.         ConcMomentForceSB(C_s, X_mm, True)
389.         Return momnet
390.     End Function
391.     Function SectionAxialRsistanceFN(ByVal confined As Boolean) As Double
392.         Dim resistance, core_height, core_width, core_area As Double
393.         If confined Then
394.             core_height = section_height - 2 * unconfined_layer_thickness
395.             core_width = section_width - 2 * unconfined_layer_thickness
396.             core_area = core_height * core_width
397.             resistance = rein_area * f_y + (core_area - rein_area) * f_ccm + (se
ction_area - core_area) * f_cm
398.         Else
399.             resistance = rein_area * f_y + (section_area - rein_area) * f_cm
400.         End If
401.
402.         Return resistance
403.     End Function
404.
405.     Sub MomentCurvatureSB()
406.         ReDim moment_curvature_table(3, curvatures_iterations + 10)
407.         Dim X_mm_i As Double
408.         ResetSB()

```

```

409.         X_mm_i = X_mm / curvatures_iterations
410.         max_momnet_value = 0
411.         max_moment_piont = 0
412.         ProgressBar1.Value = 0
413.         For i = 1 To curvatures_iterations
414.             moment_curvature_table(1, i) = X_mm_i * i
415.         Next
416.         Dim close As Boolean = False
417.         For i = 1 To curvatures_iterations
418.             ProgressBar1.Value = ProgressBar1.Value + ProgressBar1.Maximum / cur
vatures_iterations
419.             moment_curvature_table(2, i) = FindMomentFN(X_mm_i * i)
420.             moment_curvature_table(3, i) = C_s
421.
422.             If moment_curvature_table(2, i) > max_momnet_value And (Math.Round(m
oment_curvature_table(2, i)) > Math.Round(moment_curvature_table(2, i - 1)) * 5) = Fals
e Then
423.                 max_momnet_value = moment_curvature_table(2, i)
424.                 max_moment_piont = i
425.             End If
426.             If Math.Round(moment_curvature_table(2, i) / 1000) = 0 And moment_cu
rvature_table(1, i) <> 0 Then
427.                 max_curvature_point = i
428.                 close = True
429.             End If
430.             For j = 1 To 8
431.                 Next
432.             If close Then
433.                 i = curvatures_iterations + 1
434.             End If
435.         Next
436.     End Sub
437.     Function MinFN(a As Double, b As Double)
438.         If a < b Then
439.             Return a
440.         Else
441.             Return b
442.         End If
443.     End Function
444.     Function MaxFN(a As Double, b As Double)
445.         If a > b Then
446.             Return a
447.         Else
448.             Return b
449.         End If
450.     End Function
451.     Sub MomentCuruatureTableSB()
452.         DataGridView1.Rows.Clear()
453.         DataGridView1.ColumnCount = 3
454.         DataGridView1.Columns(0).Name = "Curvature [1/m]"
455.         DataGridView1.Columns(1).Name = "Bending Moment [kN.m]"
456.         DataGridView1.Columns(2).Name = "Cs [mm]"
457.         DataGridView1.AutoSizeColumnsMode() = DataGridViewAutoSizeColumnsMode.Fi
11
458.         Dim row As String()
459.         For i = 1 To max_curvature_point
460.             row = New String() {moment_curvature_table(1, i) * 1000, Math.Round(
moment_curvature_table(2, i) / 10 ^ 6, 0), Math.Round(moment_curvature_table(3, i))}
461.             DataGridView1.Rows.Add(row)
462.         Next
463.     End Sub

```

```

464.         Private Sub DrawChart(theChart As Chart)
465.             Dim theFontsize As Integer = CInt(theChart.ClientSize.Width / 60)
466.             'setup the chart
467.             With theChart.ChartAreas(0)
468.                 .AxisX.Title = "Curvature [1/m]"
469.                 .AxisX.TitleFont = New Font("Times New Roman", CInt(theFontsize * 1
.2), FontStyle.Bold)
470.                 .AxisX.MajorGrid.LineColor = Color.LightBlue
471.                 .AxisX.Minimum = 0
472.                 .AxisX.LabelStyle.Font = New Font("Arial", theFontsize)
473.                 .AxisX.IsLabelAutoFit = False
474.                 .AxisY.Title = "Moment [kN.m]"
475.                 .AxisY.TitleFont = New Font("Times New Roman", CInt(theFontsize * 1
.2), FontStyle.Bold)
476.                 .AxisY.MajorGrid.LineColor = Color.LightGray
477.                 .AxisY.Minimum = 0
478.                 .AxisY.LabelStyle.Font = New Font("Arial", theFontsize)
479.                 .AxisY.IsLabelAutoFit = False
480.                 .BackColor = Color.FloralWhite
481.                 .BackSecondaryColor = Color.White
482.                 .BackGradientStyle = GradientStyle.HorizontalCenter
483.                 .BorderColor = Color.Blue
484.                 .BorderDashStyle = ChartDashStyle.Solid
485.                 .BorderWidth = 1
486.                 .ShadowOffset = 2
487.             End With
488.             DrawCurveSB(max_moment_piont)
489.         End Sub
490.         Sub DrawCurveSB(mark As Integer)
491.             'draw the chart
492.             Chart1.Series.Clear()
493.             Chart1.Series.Add("Y = f(x)")
494.             With Chart1.Series(0)
495.                 .ChartType = DataVisualization.Charting.SeriesChartType.Line
496.                 .BorderWidth = CInt(Chart1.ClientSize.Width / 400)
497.                 .Color = Color.Red
498.                 .IsVisibleInLegend = False
499.
500.                 Dim y As Single
501.                 For i = 0 To curvatures_iterations Step 1
502.                     y = Math.Abs(Math.Round(moment_curvature_table(2, i) / 10 ^ 6, 3
))
503.                     .Points.AddXY(moment_curvature_table(1, i) * 1000, y)
504.                 Next
505.             End With
506.             Chart1.Series.Add("Point")
507.             With Chart1.Series("Point")
508.                 .IsVisibleInLegend = False
509.                 .ChartType = DataVisualization.Charting.SeriesChartType.Point
510.                 .MarkerStyle = MarkerStyle.Circle
511.                 .MarkerSize = 7
512.                 .MarkerColor = Color.BlueViolet
513.                 .Points.AddXY(moment_curvature_table(1, mark) * 1000, moment_curvatu
re_table(2, mark) / 10 ^ 6)
514.             End With
515.         End Sub
516.         Sub MomentCurvatureGraphSB()
517.             DrawChart(Chart1)
518.         End Sub
519.

```

```

520.         Private Sub SectionToolStripMenuItem_Click(sender As Object, e As EventArgs)
           Handles SectionToolStripMenuItem.Click
521.             DefineSection.Show()
522.         End Sub
523.         Private Sub MaterialsToolStripMenuItem_Click(sender As Object, e As EventArgs)
           Handles MaterialsToolStripMenuItem.Click
524.             DefineMaterials.Show()
525.         End Sub
526.         Sub DuctilityTextSB()
527.             LabelForce.Text = "Axial Force Capacity: " & Math.Round(SectionAxialResistanceFN(False) / 1000) & " kN," & vbNewLine & "Maximum Moment: " & Math.Round(max_moment_value / 10 ^ 6) & " kN.m, Curvature: " & moment_curvature_table(1, max_moment_pion
           t) * 1000 & " 1/m"
528.             If limit_check(7) And limit_check(2) Then
529.                 LabelForce.Text = LabelForce.Text & vbNewLine & "Yielding Curvature:
           " & moment_curvature_table(1, limit_iteration(7)) * 1000 & " 1/m" & vbNewLine & "Ultimate Curvature: " & moment_curvature_table(1, limit_iteration(2)) * 1000 & " 1/m" & vbNewLine & "Ductility: " & Math.Round(moment_curvature_table(1, limit_iteration(2)) / moment_curvature_table(1, limit_iteration(7)), 2)
530.             End If
531.         End Sub
532.         Private Sub MomentCurvatureToolStripMenuItem_Click(sender As Object, e As EventArgs)
           Handles MomentCurvatureToolStripMenuItem.Click
533.             GetBoxesSB()
534.             interaction = False
535.             ParametersCalcSB()
536.             MomentCurvatureSB()
537.             MomentCurvatureTableSB()
538.             MomentCurvatureGraphSB()
539.             ResetMomentCurvatureSB()
540.             TrackBar1.Value = max_moment_pion
541.             DuctilityTextSB()
542.             SetVisibilitySB(False)
543.         End Sub
544.         Private Sub MainForm_Load(sender As Object, e As EventArgs)
           Handles MyBase.Load
545.             InitialValuesSB()
546.             ParametersCalcSB()
547.             FillBoxesSB()
548.         End Sub
549.         Private Sub TrackBar1_Scroll(sender As Object, e As EventArgs)
           Handles TrackBar1.Scroll
550.             Dim i As Integer = TrackBar1.Value
551.             If interaction Then
552.                 DrawCurveMomentForceSB(i)
553.             Else
554.                 DrawCurveSB(i)
555.                 RadioButton10.Checked = True
556.             End If
557.             TextSB(i)
558.         End Sub
559.         Sub TextSB(i As Integer)
560.             If interaction Then
561.                 LabelPion1.Text = "Applied Force: " & Math.Round(moment_force_table(1, i) / 1000) & " kN"
562.                 LabelPion2.Text = "Moment Resistance: " & Math.Round(moment_force_table(2, i) / 10 ^ 6) & " kN/m"
563.             Else
564.                 LabelPion1.Text = "Curvature: " & moment_curvature_table(1, i) * 1000 & " 1/m"

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565.         LabelPiont2.Text = "Moment: " & Math.Round(moment_curvature_table(2,
    i) / 10 ^ 6) & " kN/m"
566.         End If
567.     End Sub
568.     Private Sub ConcreteStressStrainToolStripMenuItem_Click(sender As Object, e
    As EventArgs) Handles ConcreteStressStrainToolStripMenuItem.Click
569.         ConfinedConcreteStressStrain.Show()
570.     End Sub
571.     Private Sub UnconfinedConcreteStressStrainToolStripMenuItem_Click(sender As
    Object, e As EventArgs) Handles UnconfinedConcreteStressStrainToolStripMenuItem.Click
572.         UnconfinedConcreteStressStrain.Show()
573.     End Sub
574.     Private Sub SteelSressStrainToolStripMenuItem_Click(sender As Object, e As E
    ventArgs) Handles SteelSressStrainToolStripMenuItem.Click
575.         SteelBarsStressStrain.Show()
576.     End Sub
577.     Sub LimitsTableSB()
578.         DataGridView1.ColumnCount = 3
579.         DataGridView1.Columns(0).Name = "Curvature [1/m]"
580.         DataGridView1.Columns(1).Name = "Bending Moment [kN.m]"
581.         DataGridView1.Columns(2).Name = "Cs [mm]"
582.         DataGridView1.AutoSizeColumnsMode() = DataGridViewAutoSizeColumnsMode.Fi
    ll
583.         Dim row As String()
584.         For i = 1 To max_curvature_point
585.             row = New String() {moment_curvature_table(1, i) * 1000, Math.Round(
    moment_curvature_table(2, i) / 10 ^ 6, 0), Math.Round(moment_curvature_table(3, i))}
586.             DataGridView1.Rows.Add(row)
587.         Next
588.     End Sub
589.     Private Sub RadioButton1_CheckedChanged(sender As Object, e As EventArgs) Ha
    ndles RadioButton1.CheckedChanged
590.         Try
591.             DrawCurveSB(limit_iteration(1))
592.             TrackBar1.Value = limit_iteration(1)
593.             TextSB(limit_iteration(1))
594.         Catch ex As Exception
595.         End Try
596.     End Sub
597.     Private Sub RadioButton2_CheckedChanged(sender As Object, e As EventArgs) Ha
    ndles RadioButton2.CheckedChanged
598.         Try
599.             DrawCurveSB(limit_iteration(2))
600.             TrackBar1.Value = limit_iteration(2)
601.             TextSB(limit_iteration(2))
602.         Catch ex As Exception
603.         End Try
604.     End Sub
605.     Private Sub RadioButton3_CheckedChanged(sender As Object, e As EventArgs) Ha
    ndles RadioButton3.CheckedChanged
606.         Try
607.             DrawCurveSB(limit_iteration(3))
608.             TrackBar1.Value = limit_iteration(3)
609.             TextSB(limit_iteration(3))
610.         Catch ex As Exception
611.
612.         End Try
613.     End Sub
614.     Private Sub RadioButton4_CheckedChanged(sender As Object, e As EventArgs) Ha
    ndles RadioButton4.CheckedChanged
615.         Try

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616.             DrawCurveSB(limit_iteration(4))
617.             TrackBar1.Value = limit_iteration(4)
618.             TextSB(limit_iteration(4))
619.         Catch ex As Exception
620.         End Try
621.     End Sub
622.     Private Sub RadioButton5_CheckedChanged(sender As Object, e As EventArgs) Handles RadioButton5.CheckedChanged
623.         Try
624.             DrawCurveSB(limit_iteration(5))
625.             TrackBar1.Value = limit_iteration(5)
626.             TextSB(limit_iteration(5))
627.         Catch ex As Exception
628.
629.         End Try
630.     End Sub
631.     Private Sub RadioButton6_CheckedChanged(sender As Object, e As EventArgs) Handles RadioButton6.CheckedChanged
632.         Try
633.             DrawCurveSB(limit_iteration(6))
634.             TrackBar1.Value = limit_iteration(6)
635.             TextSB(limit_iteration(6))
636.         Catch ex As Exception
637.         End Try
638.     End Sub
639.     Private Sub RadioButton7_CheckedChanged(sender As Object, e As EventArgs) Handles RadioButton7.CheckedChanged
640.         Try
641.             DrawCurveSB(limit_iteration(7))
642.             TrackBar1.Value = limit_iteration(7)
643.             TextSB(limit_iteration(7))
644.         Catch ex As Exception
645.
646.         End Try
647.     End Sub
648.     Private Sub RadioButton8_CheckedChanged(sender As Object, e As EventArgs) Handles RadioButton8.CheckedChanged
649.         Try
650.             DrawCurveSB(limit_iteration(8))
651.             TrackBar1.Value = limit_iteration(8)
652.             TextSB(limit_iteration(8))
653.         Catch ex As Exception
654.         End Try
655.     End Sub
656.     Private Sub TensileConcreteStressStrainToolStripMenuItem_Click(sender As Object, e As EventArgs) Handles TensileConcreteStressStrainToolStripMenuItem.Click
657.         TensileConcreteStressStrain.Show()
658.     End Sub
659.     Sub MomentForceSB()
660.         Dim mio_i As Double
661.         max_moment_force_value = 0
662.         max_moment_force_piont = 0
663.         ReDim moment_force_table(3, interaction_points)
664.         For i = 0 To interaction_points - 1
665.             If pure_force_reduction_factor < 1 Then
666.                 mio_i = i / (interaction_points - 1) * pure_force_reduction_factor
or
667.             Else
668.                 mio_i = i / interaction_points
669.             End If
670.         applied_force = mio_i * SectionAxialRsistanceFN(False)

```

```

671.         MomentCurvatureSB()
672.         If max_momnet_value = 0 Then
673.             moment_force_table(2, i) = moment_force_table(2, i - 1)
674.             moment_force_table(1, i) = moment_force_table(1, i - 1)
675.             moment_force_table(3, i) = moment_force_table(3, i - 1)
676.         Else
677.             moment_force_table(2, i) = max_momnet_value
678.             moment_force_table(1, i) = applied_force
679.             moment_force_table(3, i) = mio_i * 100
680.         End If
681.         If max_moment_force_value < max_momnet_value Then
682.             max_moment_force_value = max_momnet_value
683.             max_moment_force_piont = i
684.         End If
685.     Next
686.     moment_force_table(2, interaction_points) = 0
687.     moment_force_table(1, interaction_points) = SectionAxialRsistanceFN(Fals
e) * pure_force_reduction_factor
688.     moment_force_table(3, interaction_points) = 100 * pure_force_reduction_f
actor
689. End Sub
690. Sub MomentForceTableSB()
691.     DataGridView1.Rows.Clear()
692.     DataGridView1.ColumnCount = 3
693.     DataGridView1.Columns(0).Name = "Force [kN]"
694.     DataGridView1.Columns(1).Name = "Bending Moment [kN.m]"
695.     DataGridView1.Columns(2).Name = "μ [%]"
696.     DataGridView1.AutoSizeColumnsMode() = DataGridViewAutoSizeColumnsMode.Fi
ll
697.     Dim row As String()
698.     For i = 0 To interaction_points
699.         row = New String() {Math.Round(moment_force_table(1, i) / 1000, 0),
Math.Round(moment_force_table(2, i) / 10 ^ 6, 0), Math.Round(moment_force_table(3, i))}
700.         DataGridView1.Rows.Add(row)
701.     Next
702. End Sub
703. Sub MomentForceGraphSB()
704. End Sub
705. Private Sub InteractionCurveToolStripMenuItem_Click(sender As Object, e As E
ventArgs) Handles InteractionCurveToolStripMenuItem.Click
706.     GetBoxesSB()
707.     interaction = True
708.     ParametersCalcSB()
709.     MomentForceSB()
710.     MomentForceTableSB()
711.     DrawChartMomentForceSB(Chart1)
712.     TrackBar1.Maximum = interaction_points
713.     TrackBar1.Value = max_moment_force_piont
714.     SetVisibilitySB(True)
715. End Sub
716. Private Sub DrawChartMomentForceSB(theChart As Chart)
717.     Dim theFontsize As Integer = CInt(theChart.ClientSize.Width / 60)
718.     'setup the chart
719.     With theChart.ChartAreas(0)
720.         .AxisX.Title = "Moment [kN.m]"
721.         .AxisX.TitleFont = New Font("Times New Roman", CInt(theFontsize * 1
.2), FontStyle.Bold)
722.         .AxisX.MajorGrid.LineColor = Color.LightBlue
723.         .AxisX.Minimum = 0
724.         .AxisX.LabelStyle.Font = New Font("Arial", theFontsize)

```

```

725.         .AxisX.IsLabelAutoFit = False
726.         .AxisY.Title = "Force [kN]"
727.         .AxisY.TitleFont = New Font("Times New Roman", CInt(theFontsize * 1
.2), FontStyle.Bold)
728.         .AxisY.MajorGrid.LineColor = Color.LightGray
729.         .AxisY.Minimum = 0
730.         .AxisY.LabelStyle.Font = New Font("Arial", theFontsize)
731.         .AxisY.IsLabelAutoFit = False
732.         .BackColor = Color.FloralWhite
733.         .BackSecondaryColor = Color.White
734.         .BackGradientStyle = GradientStyle.HorizontalCenter
735.         .BorderColor = Color.Blue
736.         .BorderDashStyle = ChartDashStyle.Solid
737.         .BorderWidth = 1
738.         .ShadowOffset = 2
739.     End With
740.     DrawCurveMomentForceSB(max_moment_force_piont)
741. End Sub
742. Sub DrawCurveMomentForceSB(mark As Integer)
743.     'draw the chart
744.     Chart1.Series.Clear()
745.     Chart1.Series.Add("Y = f(x)")
746.     With Chart1.Series(0)
747.         .ChartType = DataVisualization.Charting.SeriesChartType.Line
748.         .BorderWidth = CInt(Chart1.ClientSize.Width / 400)
749.         .Color = Color.Red
750.         .IsVisibleInLegend = False
751.         Dim y As Single
752.         For i = 0 To interaction_points Step 1
753.             .Points.AddXY(moment_force_table(2, i) / 10 ^ 6, moment_force_ta
ble(1, i) / 1000)
754.         Next
755.     End With
756.     Chart1.Series.Add("Point")
757.     With Chart1.Series("Point")
758.         .IsVisibleInLegend = False
759.         .ChartType = DataVisualization.Charting.SeriesChartType.Point
760.         .MarkerStyle = MarkerStyle.Circle
761.         .MarkerSize = 7
762.         .MarkerColor = Color.BlueViolet
763.         .Points.AddXY(moment_force_table(2, mark) / 10 ^ 6, moment_force_tab
le(1, mark) / 1000)
764.     End With
765. End Sub
766. Private Sub ExitToolStripMenuItem_Click(sender As Object, e As EventArgs) Ha
ndles ExitToolStripMenuItem.Click
767.     Me.Close()
768. End Sub
769.
770. Private Sub TextBox3_TextChanged(sender As Object, e As EventArgs) Handles T
extBox3.TextChanged
771.     Try
772.         TextBox6.Text = Math.Round(TextBox3.Text * SectionAxialRsistanceFN(F
alse) / 1000)
773.     Catch ex As Exception
774.     End Try
775. End Sub
776. Private Sub RadioButton9_CheckedChanged(sender As Object, e As EventArgs) Ha
ndles RadioButton9.CheckedChanged
777.     Try
778.         DrawCurveSB(max_moment_piont)

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```
779.         TrackBar1.Value = max_moment_piont
780.         TextSB(max_moment_piont)
781.         Catch ex As Exception
782.         End Try
783.     End Sub
784. End Class
```

